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SURFACE TEMPERATURE EFFECTS IN THE SLIDER BEARING

by



A THESIS

SUBMITTED TO THE FACULTY OF GRADUATE STUDIES AND RESEARCH
IN PARTIAL FULFILMENT OF THE REQUIREMENTS FOR THE DEGREE
OF MASTER OF SCIENCE

DEPARTMENT OF MECHANICAL ENGINEERING

EDMONTON, ALBERTA FALL, 1972

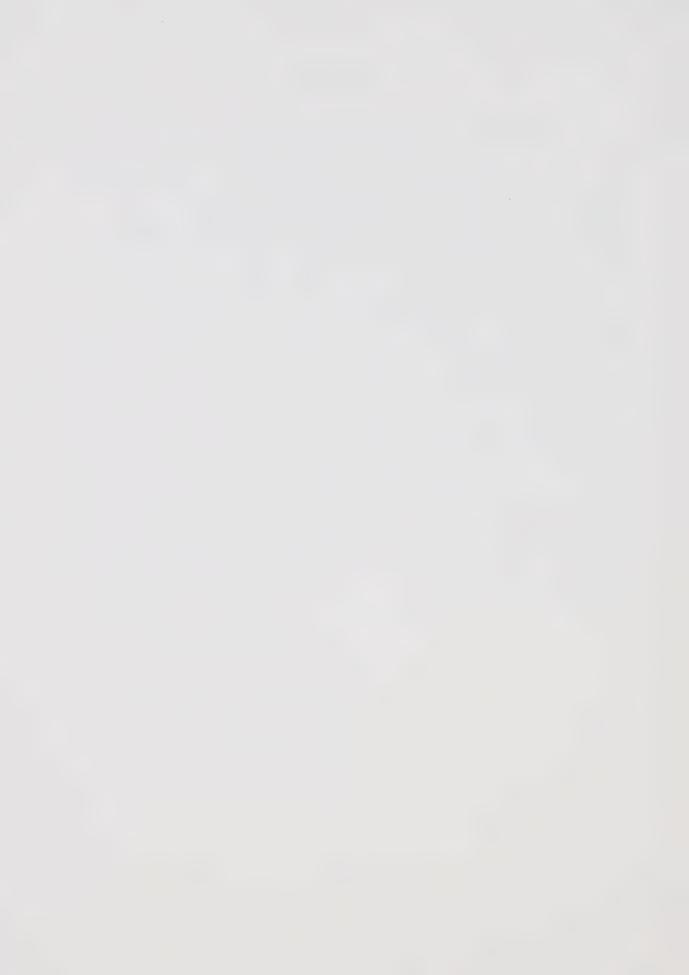
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UNIVERSITY OF ALBERTA FACULTY OF GRADUATE STUDIES AND RESEARCH

The undersigned certify that they have read, and recommend to the Faculty of Graduate Studies and Research for acceptance, a thesis entitled "Surface Temperature Effects in the Slider Bearing," submitted by John Christopher Hinds in partial fulfilment of the requirements for the degree of Master of Science.

ABSTRACT

The effect of various temperature boundary conditions and different inlet to outlet ratios on the load carrying capacity of a plane slider bearing is analysed. The contribution of the inertia terms, and the effects of convection and dissipation are also examined. The lubricant is assumed to be incompressible, and the variation of viscosity with temperature is taken into account. From the governing equations, a set of reduced equations is first obtained by nondimensionalizing and carrying out an order of magnitude analysis. These reduced equations, together with the boundary conditions, are then transformed by use of the stream function, and the resulting equations are solved numerically. Using expressions developed, the load capacity, drag, mass flow, and average flow temperature are evaluated.



ACKNOWLEDGEMENTS

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Thanks are also extended to Mr. T. K. Chattopadhyay for his help in checking the equations, and to Mrs. Marilyn Wahl, whose skill and patience resulted in such a well typed thesis. Mr. A. Karim must also be thanked for his help in preparing the Figures, which allowed an early completion of the work.

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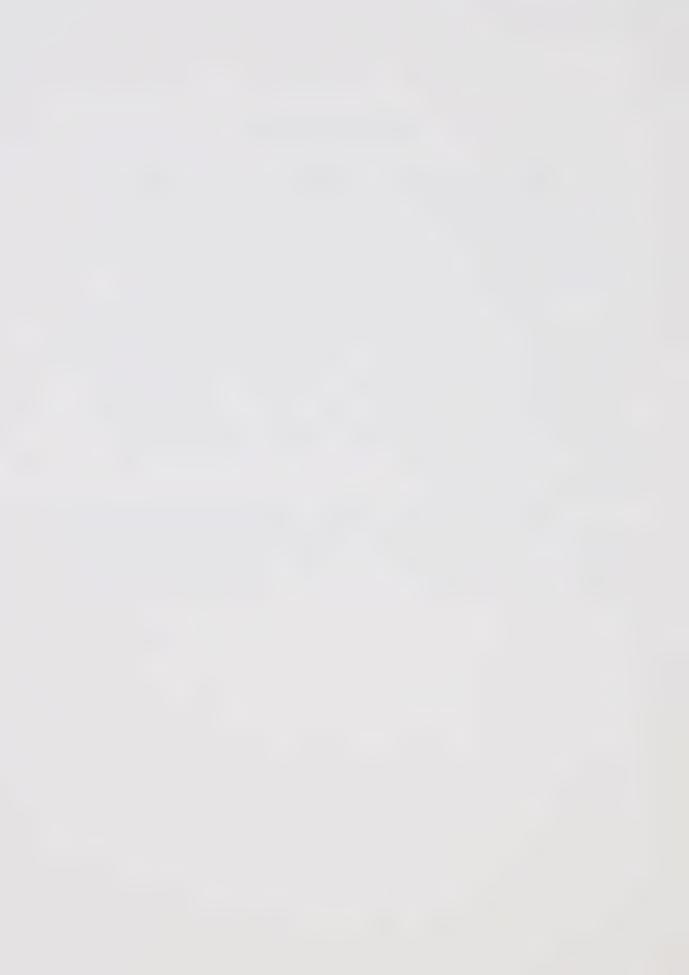
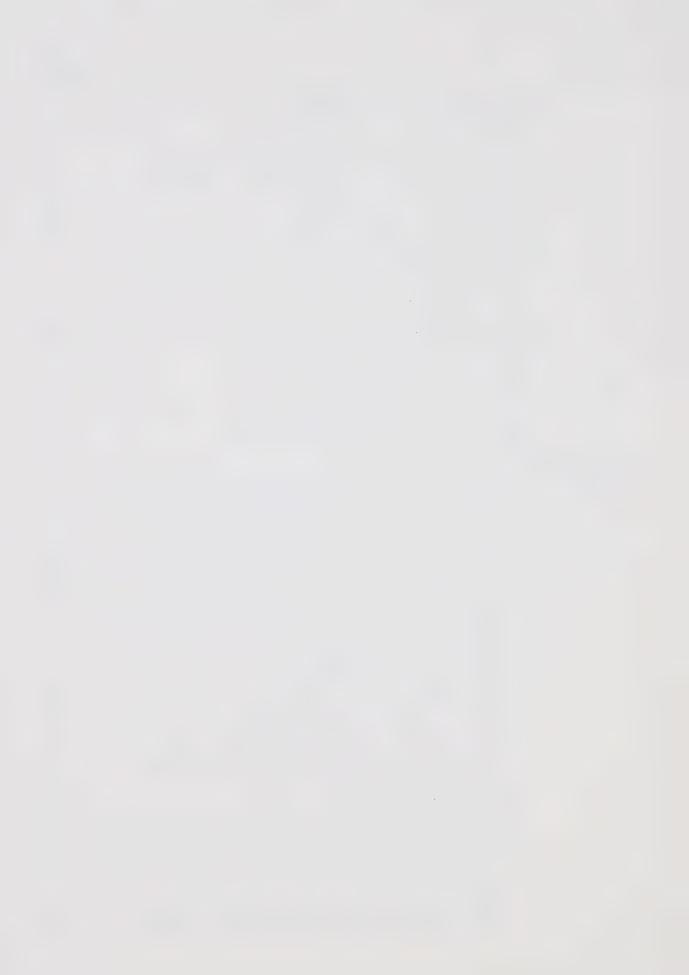


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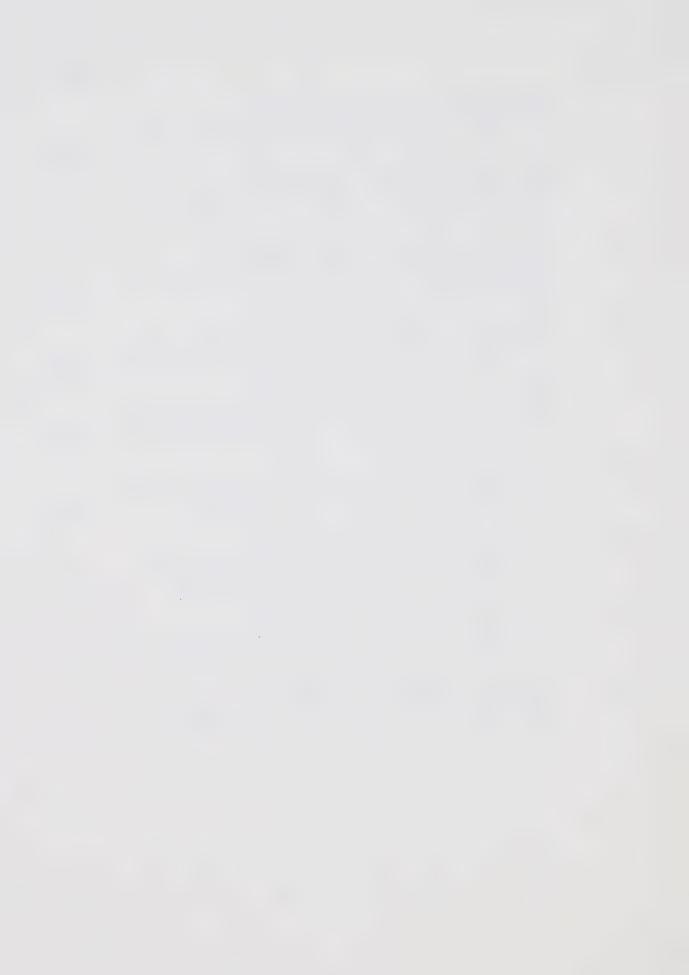


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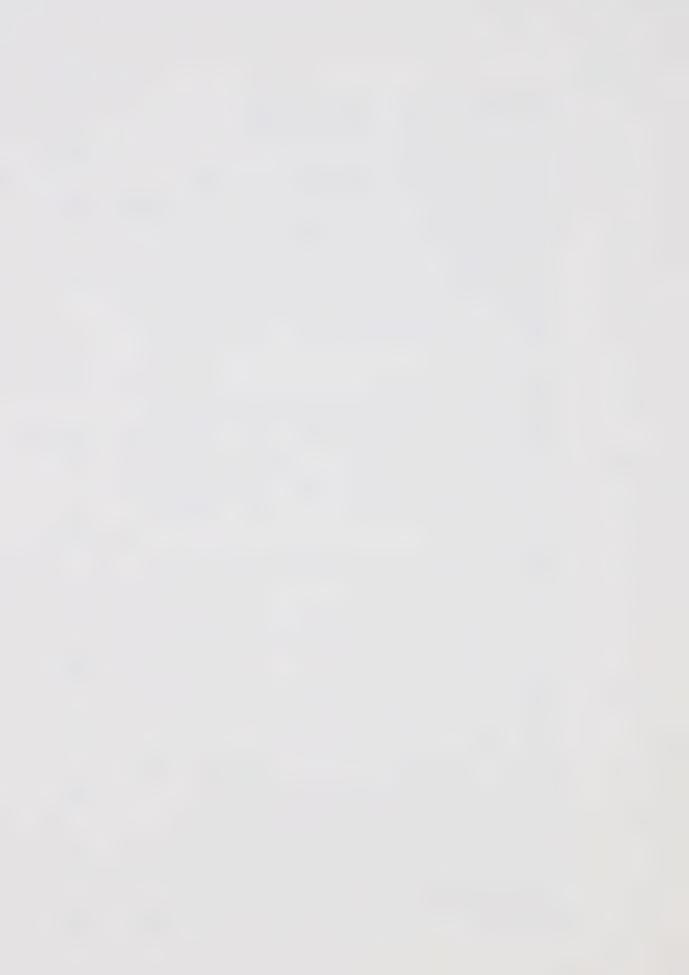


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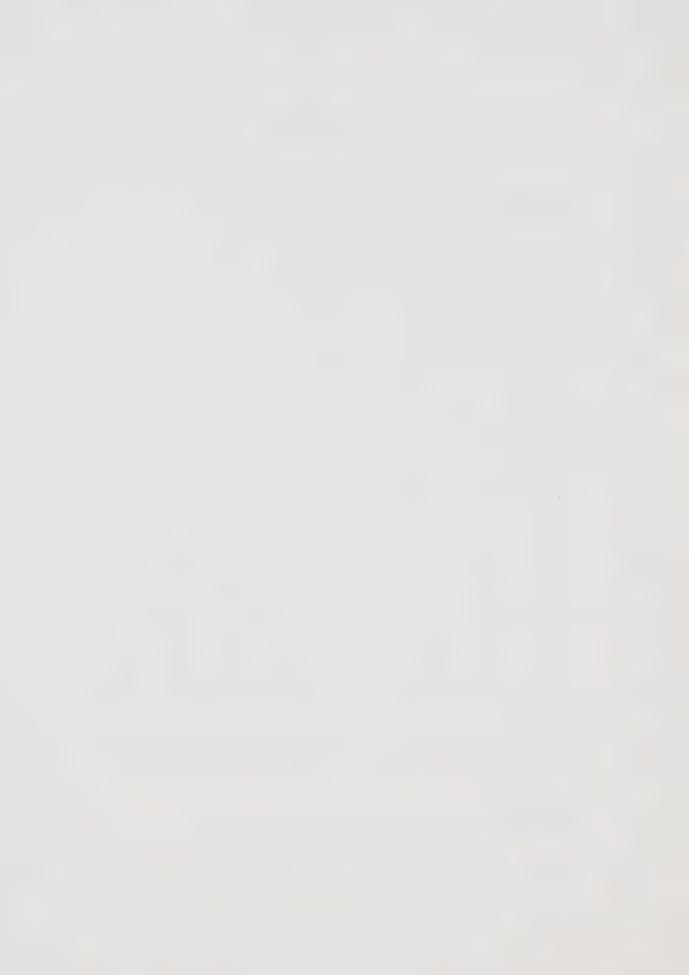


LIST OF SYMBOLS

```
coefficient in difference equations (3.21) and (A.12)
a
A_1 =
      integral expression of equations (3.13)
      integral expression of equations (3.13)
A_2 =
A_3 =
      integral expression of equations (3.13)
A_{\Lambda} =
      integral expression of equations (3.13)
A_5 =
      integral expression of equations (3.20)
A_6 =
      integral expression of equations (3.20)
b
      coefficient in difference equations (3.21) and (A.12)
      expression for constant in equations (3.12) and (3.19)
B_1 =
B_2 =
      expression for constant in equations (3.12) and (3.19)
      coefficient in difference equations (3.21) and (A.12)
C =
     coeff. in equations (3.2), (3.9) and (3.16)
C_3 =
             in equations (3.2), (3.9) and (3.16)
C_2 =
C_3 =
      coeff. in equations (3.2), (3.9) and (3.16)
      specific heat of lubricant at constant pressure
C_{D} =
               in difference equations (3.21) and (A.12)
d =
      expression for constant in equations (3.6), (3.11)
D_1 =
      and (3.18)
      expression for constant in equations (3.6), (3.11)
D_2 =
      and (3.18)
\bar{D}
      dimensionless drag, Dh / µ UL
```

type of Eckert number, U2/CpTr

E



F = correction due to the presence of inertia terms, as
 described by equation (3.15)

h = film thickness determined by equation (2.6)

h; = inlet spacing between bearing members

h = outlet spacing between bearing members

 \bar{h} = dimensionless film thickness

 $\bar{h}_r = ratio of inlet to outlet$

i = parameter indicating sectional location along \bar{x} direction of grid

L = length of bearing

 $m = \bar{h}_r - 1$

M = number of sectional locations along \bar{x} direction of grid

 \bar{N} = number of sectional locations along \bar{y} direction of grid

p = gauge pressure

 \bar{p} = dimensionless pressure, pRe $^*/\rho U^2$

 $P = Prandtl number, \mu_r C_p / K$

 $q_p = heat flux at pad$

 $q_s = \text{heat flux at slider}$

 $\bar{q}_p = \text{dimensionless heat flux at pad, } q_p h_o / KT_r$

 $q_s = dimensionless heat flux at slider, <math>q_s h_o / KT_r$

Q = heat convected out of bearing

 \bar{Q}_{e} = dimensionless heat convected out of bearing, $\frac{Q_{e}}{(\rho C_{p} T_{r} U h_{o})}$



Q_i = heat convected into bearing

 \bar{Q}_{i} = dimensionless heat convected into bearing, $\frac{Q_{i}}{(\rho C_{p}T_{r}Uh_{o})}$

Qp = heat conducted through pad

 \bar{Q}_{p} = dimensionless heat conducted through pad, $Q_{p}h_{o}/\kappa T_{r}L$

Q = heat conducted through slider

 \bar{Q}_{s} = dimensionless heat conducted through slider, $Q_{s}h_{o}/\kappa T_{r}L$

Re* = modified Reynolds number, $\frac{\rho UL}{\mu_r} (\frac{h_o}{L})^2$

T = lubricant temperature

 $T_{b} = average flow temperature$

T_p = temperature at interface between lubricant and pad

 $T_s = temperature$ at interface between lubricant and slider

 $T_r = reference temperature, (T_s + T_p)/2.0$

 \bar{T} = dimensionless temperature, T/T_r

u = velocity in x-direction

u = dimenionsless velocity in x-direction, u/U

U = velocity of slider

v = velocity in y-direction

 \bar{v} = dimensionless velocity in \bar{y} -direction

V = reference velocity in y-direction

W = load capacity of bearing

 \bar{W} = dimensionless load capacity of bearing, $\frac{Wh^2}{\mu_r UL}$

 \bar{W}_{L} = dimensionless load capacity of bearing, $\frac{Wh^{2}}{o}$

x = longitudinal coordinate

 \bar{x} = dimensionless longitudinal coordinate, $x/_L$



 $\Delta \bar{x} = \text{grid spacing in } \bar{x} \text{ direction}$

y = transverse coordinate

 \bar{y} = dimensionless transverse coordinate, y/h(x)

 $\Delta \bar{y} = grid spacing in \bar{y} direction$

GREEK LETTERS

 β = temperature coefficient of viscosity

 κ = thermal conductivity of lubricant

ρ = density of lubricant

Y = stream function

 $\overline{\Psi}$ = dimensionless stream function, Ψ/Ψ_{C}

 Ψ_{c} = rate of mass flow through bearing

 $\overline{\Psi}_{C}$ = dimensionless mass flow, $\frac{\Psi_{C}}{\rho U h_{O}}$

 τ = shear stress at a point in the fluid

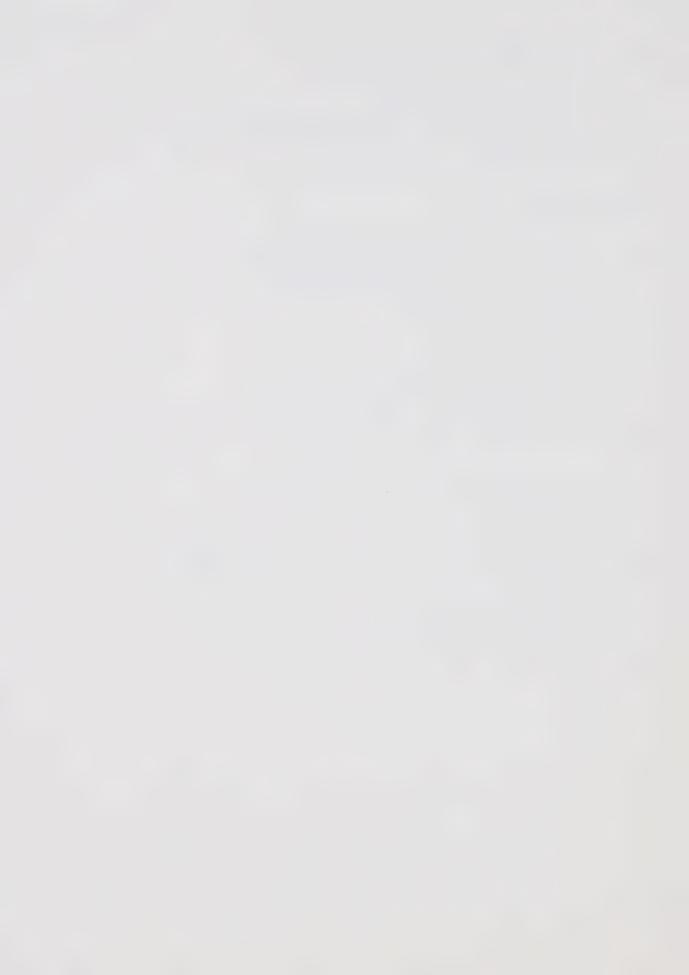
 τ_{o} = shear stress at slider

 τ_0 = dimensionless shear stress at slider, $\frac{\tau_0 h_0}{\mu_r U}$

μ = viscosity of lubricant

 $\frac{1}{\mu}$ = dimensionless viscosity of lubricant, μ/μ_r

 μ_r = reference viscosity of lubricant



CHAPTER I

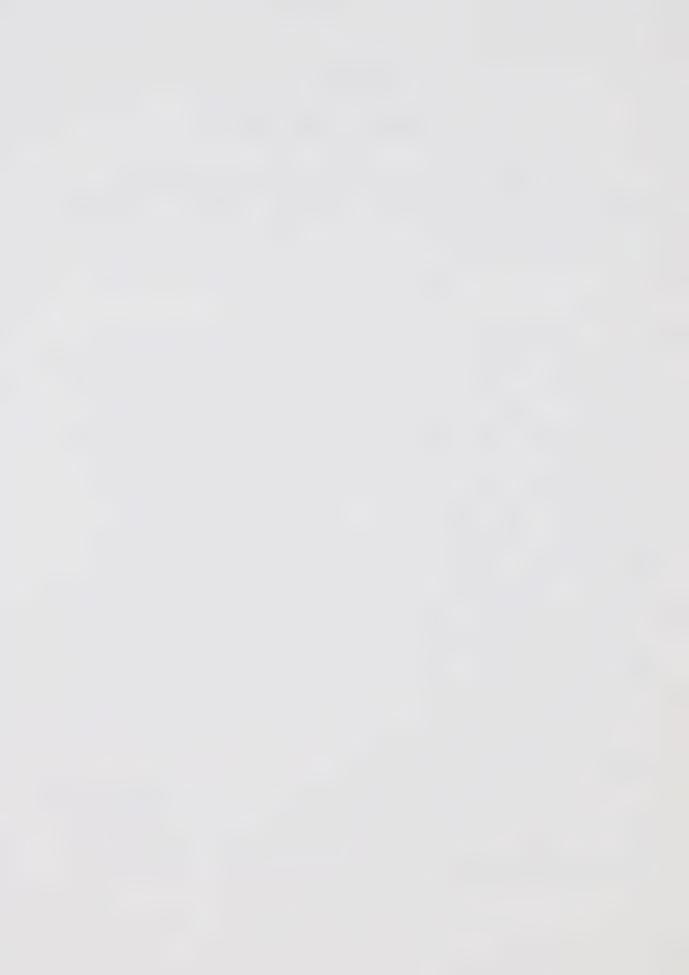
STATEMENT OF THE PROBLEM

The purpose of the present investigation, is to study the effects of various temperature boundary conditions, on the load-carrying capacity of a plane slider bearing.

DEFINITION OF PROBLEM

Up to now, not much work has been carried out on methods for increasing the load-carrying capacity of slider bearings. Some of the work done by Tahara [1] and a few others, have been concerned with removing the heat generated in a lubricating film, by use of a coolant forced through the bottom of the bearing pad. The reasoning was that cooling the lubricant would not only prevent overheating, but would also increase the load-carrying capacity of the bearing. The fact that cooling the lubricant increases its viscosity is well known, but it should also be borne in mind that a more viscous lubricant would also tend to increase the dissipative effects in the bearing. We can see therefore that the main factor contributing to the load capacity is not simply the bulk flow temperature.

It is possible to obtain a better understanding of the contributions to load capacity, if we consider the physical aspects of the operation of a slider bearing. The main



requirement for the operation of any bearing, is that the bearing must be able to support a load. In the case of fluid film bearings, this requirement means that the lubricant must be under pressure. For shafts operating at very low speeds, and under heavy loads, this pressure is usually supplied from outside; and these bearings are known as externally pressurized or hydrostatic bearings. In the case of bearings operating at higher speeds, and under average loads, the pressure is usually supplied by the revolving motion of the shaft which drags lubricant into the bearing. These types of bearings are usually referred to as hydrodynamic bearings, and are the ones of interest in this study.

When the lubricant enters the bearing, the tapered shape of the pad surface (See Fig. 1) forces the fluid close to it to flow parallel to this inclined surface. In reaction to this constraint, the fluid exerts a pressure on the bearing pad. This pressure builds up to a maximum around the middle of the bearing then decreases to the ambient pressure at the bearing outlet.

The amount of load a bearing can carry is influenced by the inlet to outlet ratio, h_i/h_o . It has been shown [2] that the load capacity rises to a maximum for $h_i/h_o = 2.2$ then falls gradually. For h_i/h_o fixed, the load which the



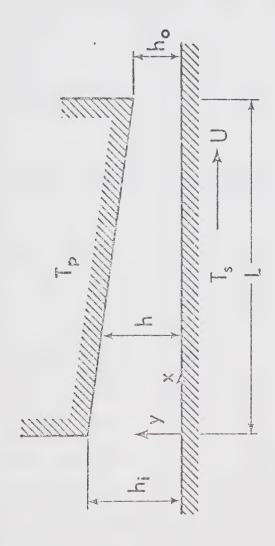


Fig. 1 Slider Bearing Geometry



bearing can support is determined by the thickness of the lubricant film. For the same load the thicker the film the larger the load the bearing can carry. This is because it will require a larger load on the bearing in order for the film thickness to return to its original value.

Our attempts at increasing the load capacity should therefore be concerned with increasing the thickness of the lubricant film for a given load. This can be accomplished most effectively by cooling the slider, or by cooling the bearing pad.

INERTIA EFFECTS AND TEMPERATURE VARIATION IN A SLIDER BEARING

The Reynolds equation is based on the assumption that the inertia forces are negligible compared to the viscous forces [3]. The importance of the inertia terms relative to the viscous terms in the equation of motion, can be characterized by a dimensionless parameter referred to as the modified Reynolds number, Re*.

In the operation of most bearings, Re*, is very small, therefore the inertia effects could be easily ignored.

However, for bearings operating at high speeds, or where the viscosity of the lubricant is very low (e.g. for gas bearings), Re* may reach values near to or exceeding unity. Thus, in such a case, the inertia forces become comparable in magnitude to the viscous forces and may no longer be ignored. If the



Reynolds number becomes greater than a certain critical value, turbulence will develop, and the governing equations will have to be correspondingly modified.

Another assumption made in classical hydrodynamic lubrication, is that the temperature variation in the lubricant film is negligible. The viscosity is then taken as being constant throughout the film, and equal to the inlet oil viscosity. This results in the uncoupling of the momentum and the energy equations, which greatly simplifies the solution of the problem. Under most operating conditions though, the energy generated by viscous dissipation causes a significant rise in the lubricant film temperature. This results in a corresponding decrease in viscosity. Hence, the solution assuming viscosity at the inlet oil temperature will be in error. Wilcock [4] and Rosenblatt [5] conclude from their experiments, that in fact the average value of viscosity corresponding to that of the outlet oil should be taken. Several authors have attempted to include the viscosity variation, by allowing the viscosity to vary in the X direction only. This results in a much simpler form of the momentum and the energy equations.

The temperature distribution within the bearing, depends largely on the thermal boundary conditions imposed on the film. If both boundaries were taken as adiabatic, all the heat generated by viscous dissipation would have to be carried out by the fluid. The effect of this would be to decrease the average lubricant viscosity, thus reducing the



load carrying capacity of the bearing. If the boundaries were not adiabatic though, some of the heat generated would be transferred across the bearing faces, and the resulting decrease in load carrying capacity would not be as great.

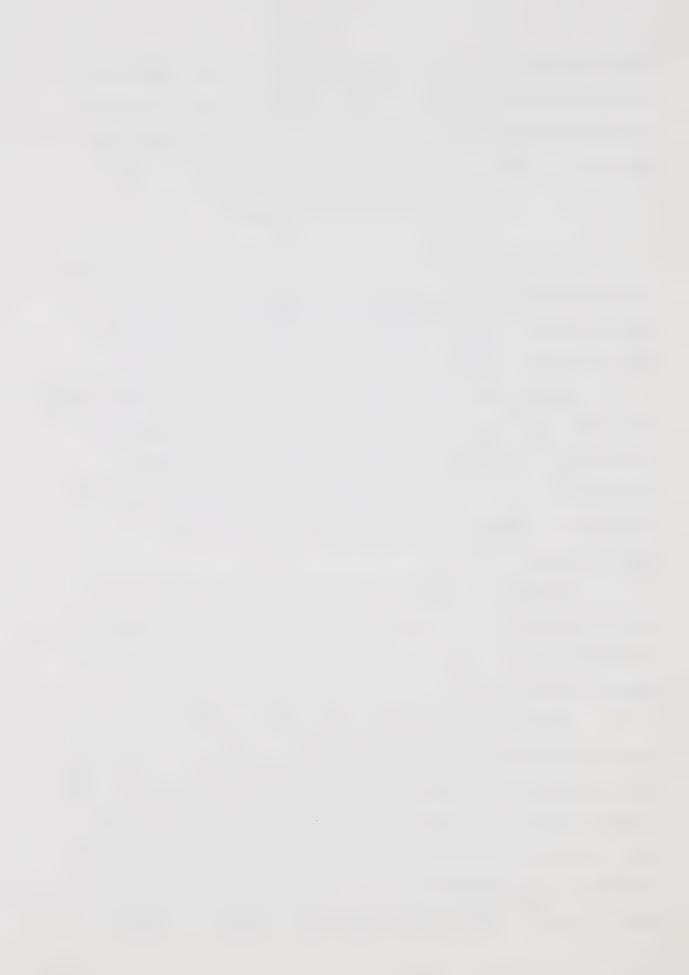
REVIEW OF RELEVANT LITERATURE

The equations of motion for the slider bearing, yield two non-linear partial differential equations; and over the years, several authors have investigated the influence of the non-linear inertia terms using approximate methods.

Slezkin and Targ [6] averaged the inertia terms across the film thickness. This allowed the resulting equation to be readily integrated, since the inertia terms became a function of x only. Other authors [7,8] have employed this technique to obtain solutions for various bearing configurations.

Kahlert [9] assumed that the inertia forces were small compared to the viscous forces. He then included the influence of the inertia terms by a small correction to the results obtained from the purely viscous consideration.

Snyder [10] obtained a more exact solution, by taking into account the variation of the inertia effects across the film as well as in the direction of flow. In his method, the stream function is expressed as a power series in δ , which is a function of film thickness; while the coefficients are assumed to be functions of η , which in turn is a function of both x and y. These coefficients are obtained by solving a



set of differential equations. In his solution, Snyder solved for only the first two terms of the power series. More recently, Rodkiewicz and Anwar [11] found that it was necessary to retain at least four terms of the series expansion, in order to improve the accuracy at higher modified Reynolds numbers.

In all of the previous references, the solutions were obtained assuming constant viscosity. Other researchers have taken into account the variation of the lubricant viscosity, for various boundary conditions on the film temperature.

Hunter and Zienkiewicz [12] considered two different boundary conditions on the temperature.

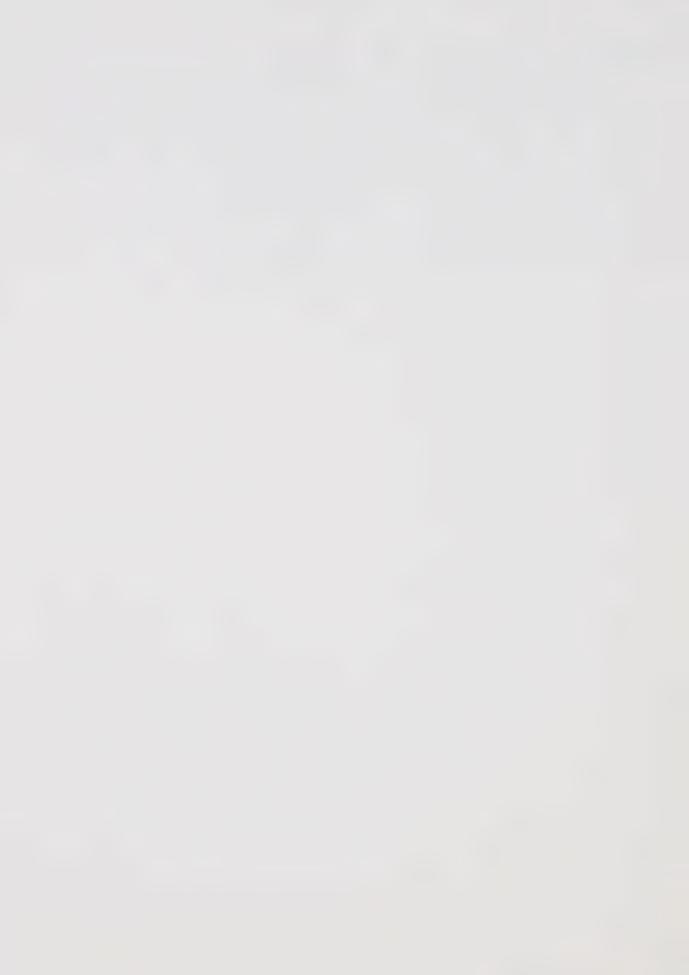
- (1) Both boundaries having the same temperature.
- (2) Both boundaries adiabatic.

In their analysis, they neglected the inertia terms, and also the lateral convection term in the energy equation.

Synder [13] studied the overall temperature variations across the lubricant film. The slider surface was taken as an isothermal surface, and the stationary surface as adiabatic. From his analysis, he concluded that the consequences of the variations of viscosity cannot be neglected for high Prandtl number lubricants. The most complete investigation so far has been carried out by Hahn and Kettleborough [14], who used matrix methods. They retained the inertia terms in the momentum equation, and the convective terms in the energy equation. Also, the viscosity of the lubricant was regarded as a function of temperature and pressure, and the density a



function of temperature. The temperature boundary conditions were obtained by equating the heat fluxes at the solid-liquid interfaces. They concluded that it was desirable to cool the bearing surfaces, since this would increase the load carrying capacity of the bearings. It was also found that the temperature at the moving surface was reasonably constant, even though the heat flux varied considerably.



CHAPTER II

THE GOVERNING EQUATIONS

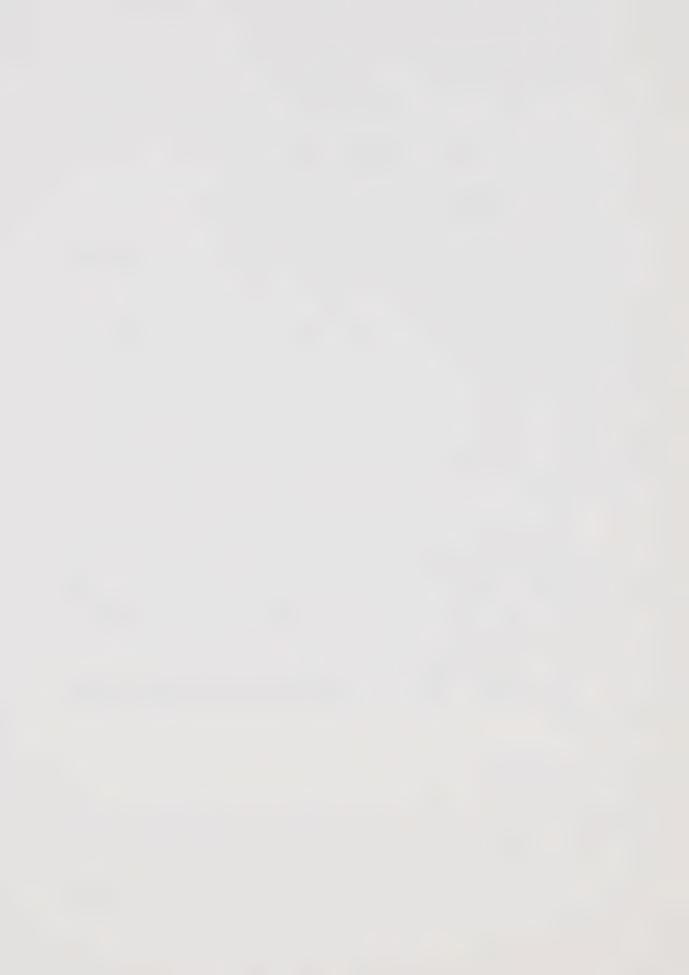
GENERAL FORM OF THE EQUATIONS

The equations governing the steady, laminar flow of an incompressible lubricant through an infinite slider bearing, as shown in Fig. I, are the momentum equations in the x and y directions, (Eqs. (2.1) and (2.2) respectively), the energy equation, Eq. (2.3), and the continuity equation, Eq. (2.4). In order to solve these equations, it is also necessary to specify the boundary conditions as presented in Eqs. (2.5).

For our problem, the boundary conditions on velocity are obtained by satisfying the conditions of no-slip at the pad and at the slider; while the boundary conditions on the temperature, are obtained from the compatibility conditions at the said two interfaces.

The general form of the equations may now be listed as follows:

Momentum equations



$$\rho \left[v \frac{\partial v}{\partial y} + u \frac{\partial v}{\partial x} \right] = -\frac{\partial p}{\partial y} + \frac{\partial v}{\partial y} \left(u \frac{\partial v}{\partial y} \right) + \frac{\partial v}{\partial x} \left(u \frac{\partial v}{\partial y} \right) + \frac{\partial v}{\partial x} \left(u \frac{\partial v}{\partial y} \right)$$
(2.2)

Energy equation

$$\rho \quad C_{p} \left[\begin{array}{cccc} u & \frac{\partial T}{\partial x} + v & \frac{\partial T}{\partial y} \end{array} \right] = \frac{\partial}{\partial x} \left(k & \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k & \frac{\partial T}{\partial y} \right) + \mu \left\{ 2 \left[\left(\frac{\partial u}{\partial x} \right)^{2} + \left(\frac{\partial v}{\partial y} \right)^{2} \right] + \left[\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]^{2} - \frac{2}{3} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right]^{2} \right\}$$

$$(2.3)$$

Continuity equation

$$\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial \mathbf{y}} = 0 \tag{2.4}$$

Boundary conditions:

y=0; u=U, v=0

y=h; u=o, v=o

y=o; T=T_S

y=h; T=T_p

$$\int_{0}^{L} \left(\frac{dp}{dx}\right) dx = 0$$
(2.5)

The equation used for the film thickness is

$$h = h_0 + (h_i - h_0) (L-x)/L$$
 (2.6)



REDUCTION OF THE GENERAL FORM OF THE EQUATIONS BY AN ORDER OF MAGNITUDE ANALYSIS

Because of the large number of terms in the Governing Equations (2.1) through (2.4), it would be very difficult to obtain a satisfactory solution. In order to simplify the problem, the given equations will be nondimensionalized, and an order of magnitude analysis carried out. It would then be possible to retain only the most important terms, and obtain solutions for the derived set of reduced equations.

Before proceeding with the nondimensionalization, a list of some of the usual assumptions made is in order:

- (1) The lubricant film is very thin i.e. $h/_{T_1} << 1$.
- (2) The density, thermal conductivity, and specific heat of the lubricant are constant.
- (3) The effects of thermal and elastic distortions are negligible.
 - (4) Cavitation effects may be ignored.
- (5) The temperature distribution at the inlet is linear.

Selecting appropriate reference quantities, the variables can be expressed as follows:

$$x = \bar{x}L$$

$$y = \bar{y}h$$

$$u = \bar{u}U$$

$$v = \bar{v}V$$

$$p = \bar{p} \rho U^2/Re^*$$

$$T = \bar{T}T_r$$

$$h = \bar{h}h_o$$

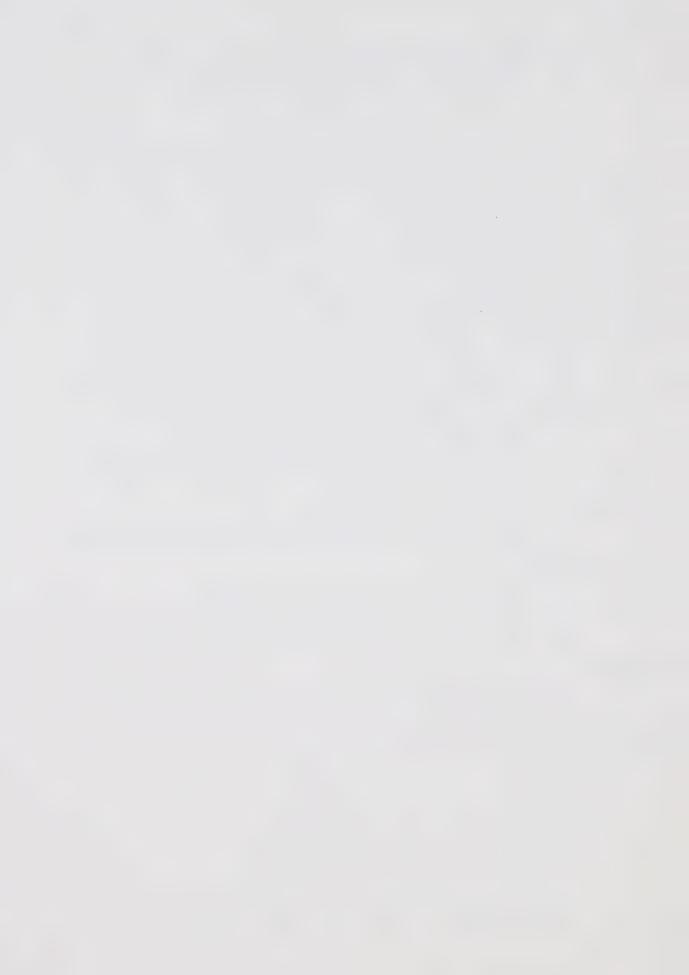
$$h_i = \bar{h}_r h_o$$

$$\mu = \bar{\mu} \mu_r$$

$$\psi = \bar{r} \mu_r$$

$$\psi = \bar{r} \mu_r$$

$$\psi = \bar{r} \mu_r$$



By substituting these transformed variables into the governing equations, and with some rearranging, it is possible to compare the relative magnitudes of the various terms.

Upon transforming the x derivative, we obtain

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \bar{x}} \quad \frac{\partial \bar{x}}{\partial x} + \frac{\partial}{\partial \bar{y}} \quad \frac{\partial \bar{y}}{\partial x}$$

$$= \frac{\partial}{\partial \bar{x}} \quad (\frac{1}{L}) + \frac{\partial}{\partial \bar{y}} \quad \frac{\partial}{\partial x} \quad (\frac{y}{h})$$

$$= \frac{1}{L} \quad \frac{\partial}{\partial \bar{x}} + y \quad (\frac{-1}{h}) \quad \frac{\partial h}{\partial x} \quad \frac{\partial}{\partial \bar{y}}$$

$$= \frac{1}{L} \quad \frac{\partial}{\partial \bar{x}} + (\frac{y}{h}) \quad (\frac{-1}{h}) \quad \frac{\partial h}{\partial x} \quad \frac{\partial}{\partial \bar{y}} ,$$

From Eq. (2.6),

$$h = h_{o} + (h_{i} - h_{o}) (L - x)/L$$

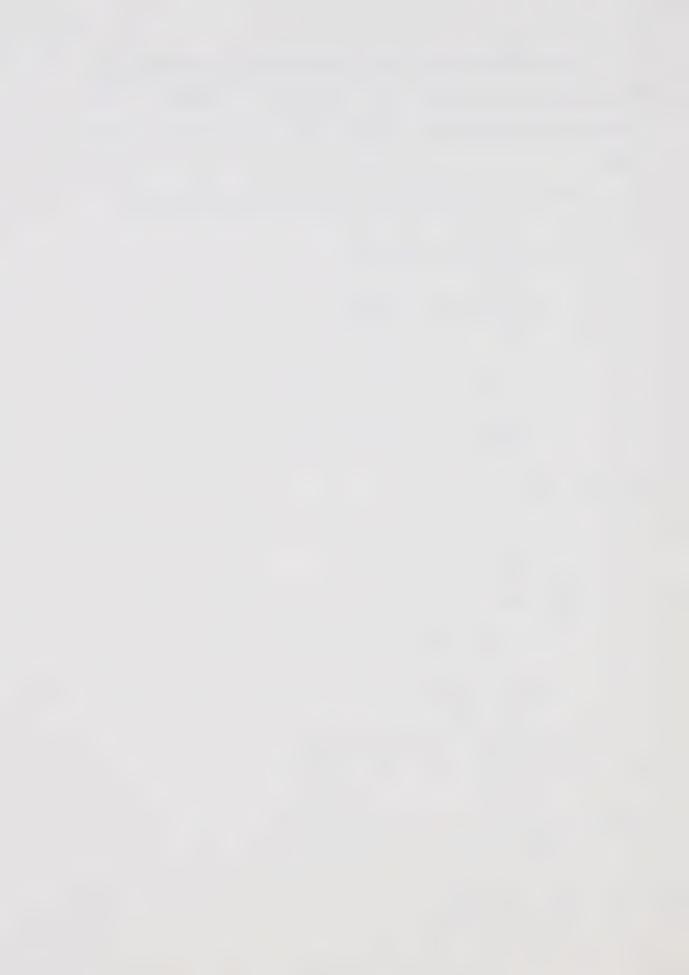
$$\frac{\partial h}{\partial x} = -(h_{i} - h_{o})/L$$

$$= -(h_{i}/h_{o} - 1)h_{o}/L$$

$$= -(\bar{h}_{r} - 1)h_{o}/L$$

$$\frac{\partial}{\partial x} = \frac{1}{L} \left[\frac{\partial}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r} - 1)}{\bar{h}} \frac{\partial}{\partial \bar{y}} \right]$$
Writing $\frac{\partial}{\partial x} = \frac{\partial}{\partial x} + \bar{y} \frac{(\bar{h}_{r} - 1)}{\bar{h}} \frac{\partial}{\partial \bar{y}}$

$$\frac{\partial}{\partial x} = \frac{1}{L} \frac{\partial}{\partial x^*} \tag{2.7}$$



Similarly for the y derivative,

$$\frac{\partial}{\partial y} = \frac{\partial}{\partial \bar{x}} \frac{\partial \bar{x}}{\partial y} + \frac{\partial}{\partial \bar{y}} \frac{\partial \bar{y}}{\partial y}$$

$$= \frac{\partial}{\partial \bar{x}} 0 + \frac{\partial}{\partial \bar{y}} (\frac{1}{h})$$

$$\frac{\partial}{\partial y} = \frac{1}{h_0 \bar{h}} \frac{\partial}{\partial \bar{y}}$$
(2.8)

For the continuity equation, we get

$$\frac{\mathbf{U}}{\mathbf{L}} \qquad \frac{\partial \overline{\mathbf{u}}}{\partial \mathbf{x}^*} \quad + \quad \frac{\mathbf{V}}{\mathbf{h}_0} \quad \frac{1}{\overline{\mathbf{h}}} \quad \frac{\partial \overline{\mathbf{v}}}{\partial \overline{\mathbf{y}}} \quad = \quad \mathbf{0}$$

i.e.
$$\frac{\partial \bar{u}}{\partial x} + (\frac{VL}{Uh_O}) \frac{1}{\bar{h}} \frac{\partial \bar{v}}{\partial \bar{y}} = 0$$

In the above equation, $\frac{\partial \bar{u}}{\partial x}$, $\frac{\partial \bar{v}}{\partial y}$, and \bar{h} are all of order [1]. Consequently, we must have $\frac{VL}{Uh}_{O} = 0$ [1] also. Choosing $\frac{VL}{Uh}_{O} = 1$ We can write $V = Uh_{O}/L$

The momentum equations become

$$\bar{h}^{2} \operatorname{Re}^{*} \left[\bar{u} \frac{\partial \bar{u}}{\partial x^{*}} + \frac{\bar{v}}{\bar{h}} \frac{\partial \bar{u}}{\partial \bar{y}} \right] = \bar{h}^{2} \left[-\frac{\partial \bar{p}}{\partial x^{*}} + 2\left(\frac{h_{o}}{L}\right)^{2} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{u}}{\partial x^{*}}\right) + \left(\frac{h_{o}}{L}\right)^{2} \frac{\partial}{\partial y} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial x^{*}}\right) \right] + \frac{\partial}{\partial \bar{y}} \left(\bar{\mu} \frac{\partial \bar{u}}{\partial y}\right)$$

$$= \left[-\bar{h} \frac{\partial \bar{p}}{\partial y} + \left(\frac{h_{o}}{L}\right)^{2} \frac{\partial}{\partial y} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \right] = \left[-\bar{h} \frac{\partial \bar{p}}{\partial y} + \left(\frac{h_{o}}{L}\right)^{2} 2 \frac{\partial}{\partial y} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial x^{*}}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{p}}{\partial y} + \left(\frac{h_{o}}{L}\right)^{2} 2 \frac{\partial}{\partial y} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial x^{*}}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{p}}{\partial y} + \left(\frac{h_{o}}{L}\right)^{2} 2 \frac{\partial}{\partial y} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial x^{*}}\right) \right]$$

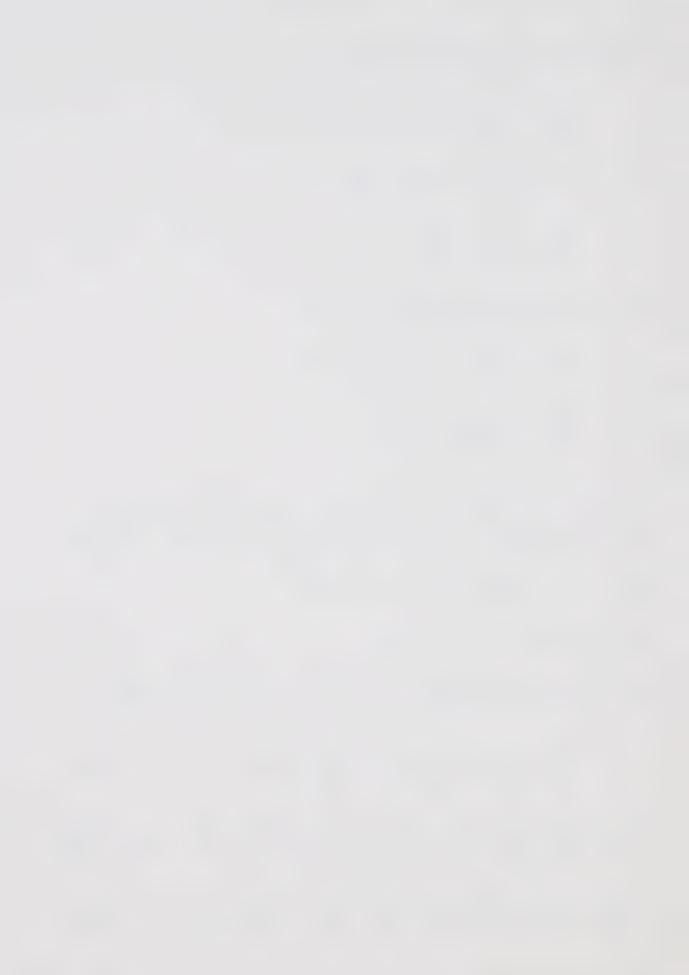
$$= \left[-\bar{h} \frac{\partial \bar{v}}{\partial y} + \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial x^{*}}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{v}}{\partial y} + \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\frac{h_{o}}{L}\right)^{4} \frac{\partial}{\partial x^{*}} \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{v}}{\partial y} + \left(\bar{\mu} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{v}}{\partial y} + \left(\bar{h} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) \right]$$

$$= \left[-\bar{h} \frac{\partial \bar{v}}{\partial y} + \left(\bar{h} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) + \bar{h}^{2} \left(\bar{v} \frac{\partial \bar{v}}{\partial y}\right) \right]$$



and the energy equation yields

$$\left[\bar{u} \frac{\partial \bar{T}}{\partial x^*} + \frac{\bar{v}}{\bar{h}} \frac{\partial \bar{T}}{\partial \bar{y}}\right] = \frac{1}{P Re^*} \left(\frac{h_0}{L}\right)^2 \frac{\partial^2 \bar{T}}{\partial x^{*2}} + \frac{1}{P Re^*} \frac{1}{h^2} \frac{\partial^2 \bar{T}}{\partial \bar{y}^2} + \frac{E}{Re^*} \left(\frac{h_0}{L}\right)^2 \bar{\mu} \left\{ \left(\frac{\partial \bar{u}}{\partial x^*}\right)^2 + \left(\frac{\partial \bar{v}}{\partial \bar{y}}\right)^2 \frac{1}{\bar{h}^2} \right] + \left[\left(\frac{h_0}{L}\right) \frac{\partial \bar{v}}{\partial x^*} + \left(\frac{L}{h_0}\right) \frac{\partial \bar{u}}{\partial \bar{y}} \right]^2 - \frac{2}{2} \left\{ \frac{\partial \bar{u}}{\partial x^*} + \frac{1}{\bar{h}} \frac{\partial \bar{v}}{\partial \bar{y}} \right\}^2 \right\}$$

$$(2.11)$$

One of our earlier assumptions was that the lubricating film was very thin, ie. h/L << 1. From this assumption, it follows that $(h/L)^2 << 1$, and L/h >> 1. With these facts in mind, it is possible to retain only those terms with the larger coefficients. We are thus able to obtain a set of reduced equations, which are to be solved for a given set of boundary conditions:

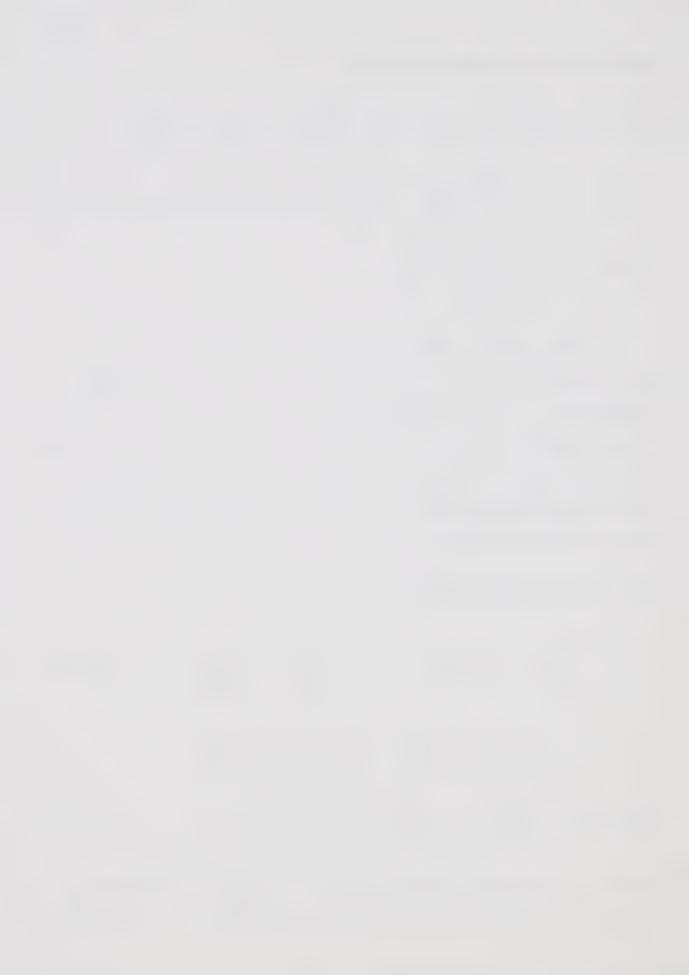
For the momentum equation in the \bar{y} direction we get

$$\frac{\partial \overline{p}}{\partial \overline{y}} = -\overline{h} \operatorname{Re}^{*} \left(\frac{h_{o}}{L}\right)^{2} \begin{bmatrix} \overline{v} & \overline{\partial v} \\ \overline{h} & \overline{\partial y} \end{bmatrix} + \overline{u} \frac{\partial \overline{v}}{\partial x}$$
 (2.12)

Now both $\frac{\overline{v}}{\overline{h}} \frac{\partial \overline{v}}{\partial \overline{y}} + \overline{u} \frac{\partial \overline{v}}{\partial x}$ and \overline{h} are of order [1].

Therefore
$$\frac{\partial \bar{p}}{\partial \bar{y}}$$
 is of order $\left[\text{Re}^* \left(\frac{h_o}{L} \right)^2 \right]$ (2.13)

which is very small, even for modified Reynolds numbers as large as 1. We see then that for our problem, the pressure



gradient in the \bar{y} direction is not important, and can be taken to equal 0.

$$\frac{\partial \bar{p}}{\partial \bar{y}} = 0 \tag{2.14}$$

Thus \bar{p} is not a function of \bar{y} , but of \bar{x} alone. The other equations when reduced give

$$\bar{h}^{2} \operatorname{Re}^{*} \left[\bar{u} \frac{\partial \bar{u}}{\partial x^{*}} + \frac{\bar{v}}{\bar{h}} \frac{\partial \bar{u}}{\partial \bar{y}} \right] = -\bar{h}^{2} \frac{\partial \bar{p}}{\partial \bar{x}} + \frac{\partial}{\partial \bar{y}} (\bar{\mu} \frac{\partial \bar{u}}{\partial \bar{y}})$$
 (2.15)

$$\bar{h}^2 P Re^* \left[\bar{u} \frac{\partial \bar{T}}{\partial x^*} + \frac{\bar{v}}{\bar{h}} \frac{\partial \bar{T}}{\partial \bar{y}} \right] = \frac{\partial^2 \bar{T}}{\partial \bar{y}^2} + P E \bar{\mu} \left(\frac{\partial \bar{u}}{\partial \bar{y}} \right)^2$$
 (2.16)

$$\bar{h} \frac{\partial \bar{u}}{\partial x} + \frac{\partial \bar{v}}{\partial \bar{y}} = 0$$
 (2.17)

In the above, the dimensionless parameters are:

$$Re^* = \frac{\rho UL}{\mu_r} \left(\frac{h_o}{L}\right)^2$$

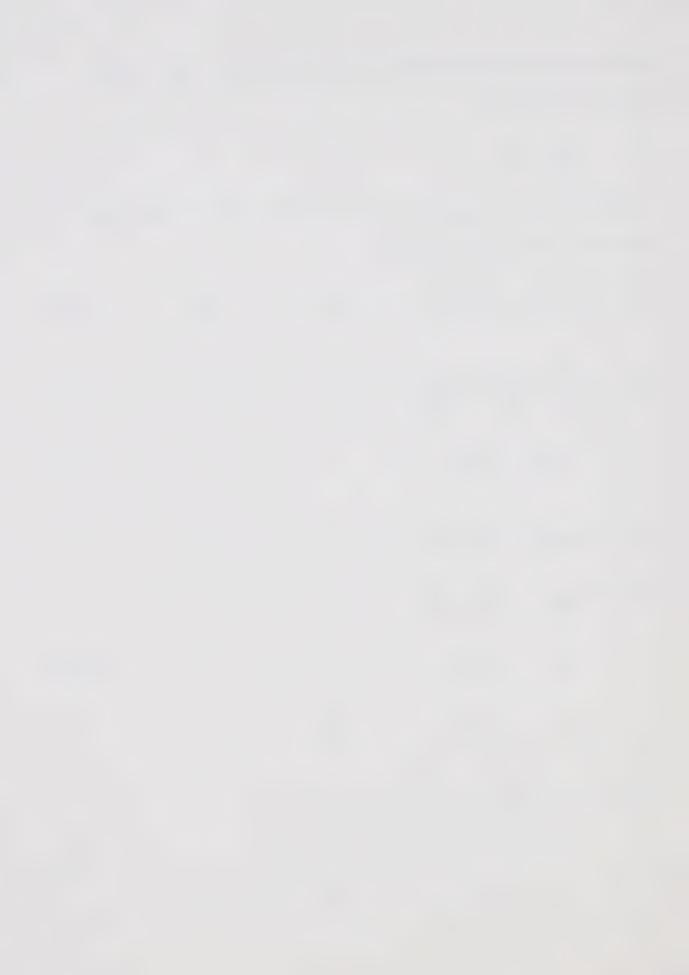
$$P = \frac{\mu_r Cp}{\kappa}$$

$$E = \frac{U^2}{C_p T_r}$$
(2.18)

and the boundary conditions become:

$$\vec{y} = 0; \vec{u} = 1; \vec{v} = 0$$

$$\vec{y} = 1; \vec{u} = 0, \vec{v} = 0$$
(2.19)



$$\int_{0}^{1} \frac{d\overline{p}}{d\overline{x}} d\overline{x} = 0$$
 (2.20)

$$\bar{T} (\bar{x},0) = \frac{2^{T_{s}/T_{p}}}{[1 + T_{s}/T_{p}]}$$

$$\bar{T} (\bar{x},1) = \frac{2}{[1 + T_{s}/T_{p}]}$$

$$\bar{T} (0,\bar{y}) = \bar{T} (0,0) + [\bar{T} (0,1) - \bar{T} (0,0)] \bar{y}$$
(2.21)

The expression derived for the dimensionless film thickness is,

$$\bar{h} = \bar{h}_r - \bar{x} [\bar{h}_r - 1] \qquad (2.22)$$

TRANSFORMATION OF THE GOVERNING EQUATIONS

In order to reduce the number of dependent variables, thus simplifying computations, we can resort to using the stream function. Writing,

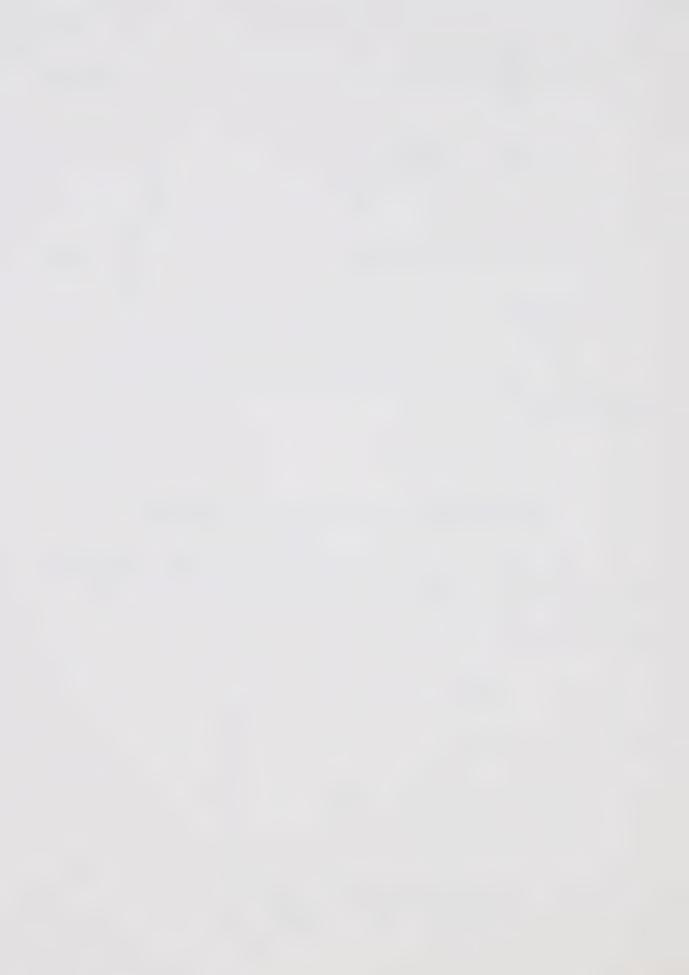
$$\Psi_{\mathbf{C}} = \int_{\mathbf{O}}^{\mathbf{h}(\mathbf{x})} \rho \mathbf{u} \, d\mathbf{y}$$

$$\overline{\Psi} = \Psi/\Psi_{\mathbf{C}}$$

$$\overline{\Psi}_{\mathbf{C}} = \Psi_{\mathbf{C}}/(\rho \mathbf{U} \mathbf{h}_{\mathbf{O}})$$

$$\overline{\mathbf{u}} = \frac{\overline{\Psi}}{\overline{\mathbf{h}}} \frac{\partial \overline{\Psi}}{\partial \overline{\mathbf{y}}}$$

$$\overline{\mathbf{v}} = -\overline{\Psi}_{\mathbf{C}} \left[\frac{\partial \overline{\Psi}}{\partial \overline{\mathbf{x}}} + \frac{(\overline{\mathbf{h}}_{\mathbf{r}} - \mathbf{1})}{\overline{\mathbf{h}}} \overline{\mathbf{y}} \frac{\partial \overline{\Psi}}{\partial \overline{\mathbf{y}}} \right]$$
(2.23)



The continuity equation is identically satisfied, and $\Psi_{_{\hbox{\scriptsize C}}}$ represents the mass flow through the bearing.

Expressions (2.15) and (2.16), (see Appendix A), and Equations (2.19) now become

$$\operatorname{Re}^{*} \overline{h} \overline{\Psi}_{C} \left[\frac{\partial \overline{\Psi}}{\partial \overline{y}} \left\{ \frac{\partial}{\partial \overline{x}} \left(\frac{\partial \overline{\Psi}}{\partial \overline{y}} \right) + \frac{(\overline{h}_{r} - 1)}{\overline{h}} \frac{\partial \overline{\Psi}}{\partial \overline{y}} \right\} - \frac{\partial \overline{\Psi}}{\partial \overline{x}} \frac{\partial^{2} \overline{\Psi}}{\partial \overline{y}^{2}} \right]$$

$$= -\frac{\overline{h}^{3}}{\overline{\Psi}_{C}} \frac{d\overline{p}}{d\overline{x}} + \frac{\partial}{\partial \overline{y}} \left(\overline{\mu} \frac{\partial^{2} \overline{\Psi}}{\partial \overline{y}^{2}} \right) \qquad (2.24)$$

$$\bar{h} \ \bar{\Psi}_{C} \ P \ Re^{*} \left[\begin{array}{ccc} \frac{\partial \bar{\Psi}}{\partial \bar{y}} & \frac{\partial \bar{T}}{\partial \bar{x}} & -\frac{\partial \bar{\Psi}}{\partial \bar{x}} & \frac{\partial \bar{T}}{\partial \bar{y}} \end{array} \right] = \frac{\partial^{2} \bar{T}}{\partial \bar{y}^{2}}$$

$$+ \ PE \ \left(\frac{\bar{\Psi}_{C}}{\bar{h}} \right)^{2} \ \bar{\mu} \ \left(\frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} \right)^{2}$$

$$\bar{Y} = 0; \ \bar{\Psi} = 0, \ \frac{\partial \bar{\Psi}}{\partial \bar{y}} = \frac{\bar{h}}{\bar{\Psi}_{C}}$$

$$(2.25)$$

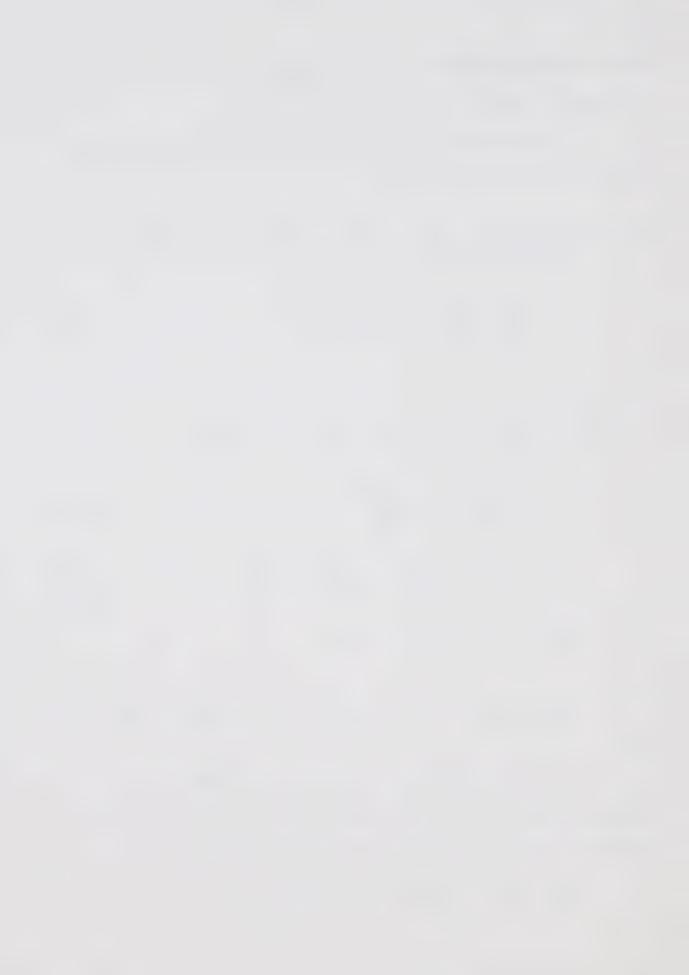
$$\overline{Y} = 1; \quad \overline{\Psi} = 1, \quad \frac{\partial \overline{\Psi}}{\partial \overline{Y}} = 0$$

$$(2.26)$$

Expressions (2.20) through (2.22) however, remain the same.

It can be seen from the above equations and the boundary conditions, that in general, the solution to our problem depends on the following dimensionless groups:

$$\bar{h}_r$$
, P Re*, P E, Re*, and T_s/T_p .



CHAPTER III

SOLUTION OF THE TRANSFORMED EQUATIONS

INTRODUCTION

Because of the non-linear nature of the momentum Equation (2.24), and the coupling with the energy Equation (2.25) through the viscosity, the solution of the problem can present some difficulty. For modified Reynolds numbers much less than unity [11], solutions were obtained neglecting the inertia terms; while for modified Reynolds numbers in the vicinity of unity, solutions were obtained including the inertia terms.

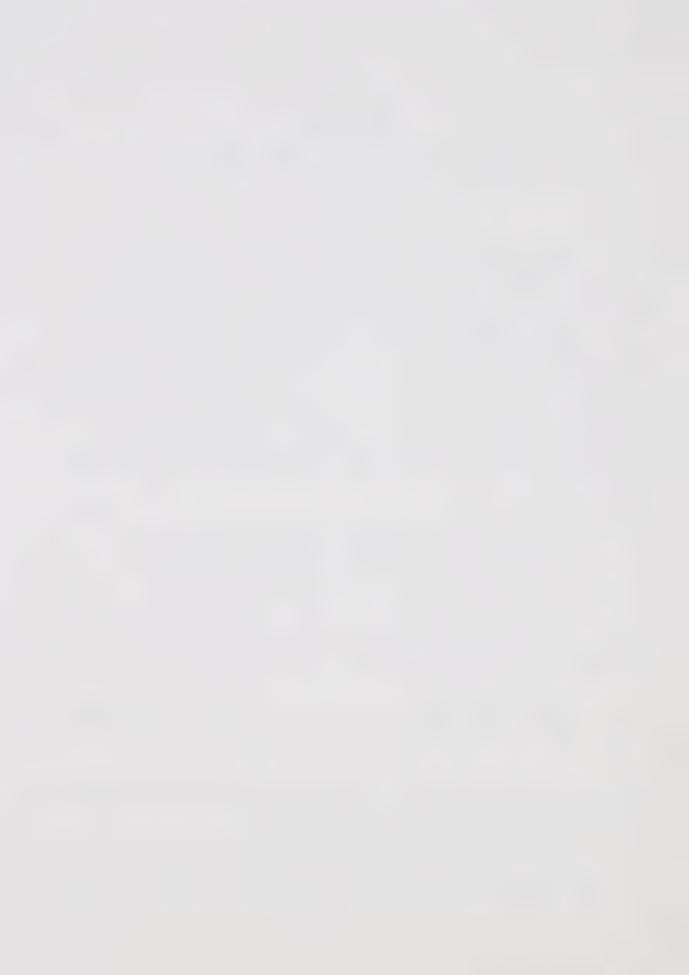
SOLUTION OF THE MOMENTUM EQUATION NEGLECTING
INERTIA TERMS AND FOR CONSTANT VISCOSITY

Neglecting the inertia terms, and for constant viscosity, the momentum Equation (2.24) becomes

$$\frac{\partial 3\overline{\Psi}}{\partial \overline{y}^3} = \frac{\overline{h}^3}{\overline{\Psi}_C} \frac{d\overline{p}}{d\overline{x}} \tag{3.1}$$

Upon integrating the above equation three times with respect to \bar{y} , we obtain the following expression

$$\overline{\Psi} = \frac{\overline{h}^3}{\overline{\Psi}_c} \frac{d\overline{p}}{d\overline{x}} \frac{\overline{y}^3}{6} + C_1 (\overline{x}) \frac{\overline{y}^2}{2} + C_2 (\overline{x}) \overline{y} + C_3 (\overline{x})$$
 (3.2)



The coeffs. $C_1(\bar{x})$, $C_2(\bar{x})$, and $C_3(\bar{x})$ of Equation (3.2) are determined from the following three boundary conditions.

$$\overline{y} = 0; \quad \overline{\Psi} = 0$$

$$\overline{y} = 1; \quad \overline{\Psi} = 1$$

$$\frac{\partial \overline{\Psi}}{\partial y} = 0$$
(3.3)

which yield

 $C_3(\bar{x}) = 0$

$$C_{1}(\bar{x}) = -2 \left[1 + \frac{\bar{h}^{3}}{\bar{\Psi}_{c}} \frac{d\bar{p}}{d\bar{x}} \frac{1}{3} \right]$$

$$C_{2}(\bar{x}) = 2 + \frac{\bar{h}^{3}}{\bar{\Psi}_{c}} \frac{d\bar{p}}{d\bar{x}} \frac{1}{6}$$

$$(3.4)$$

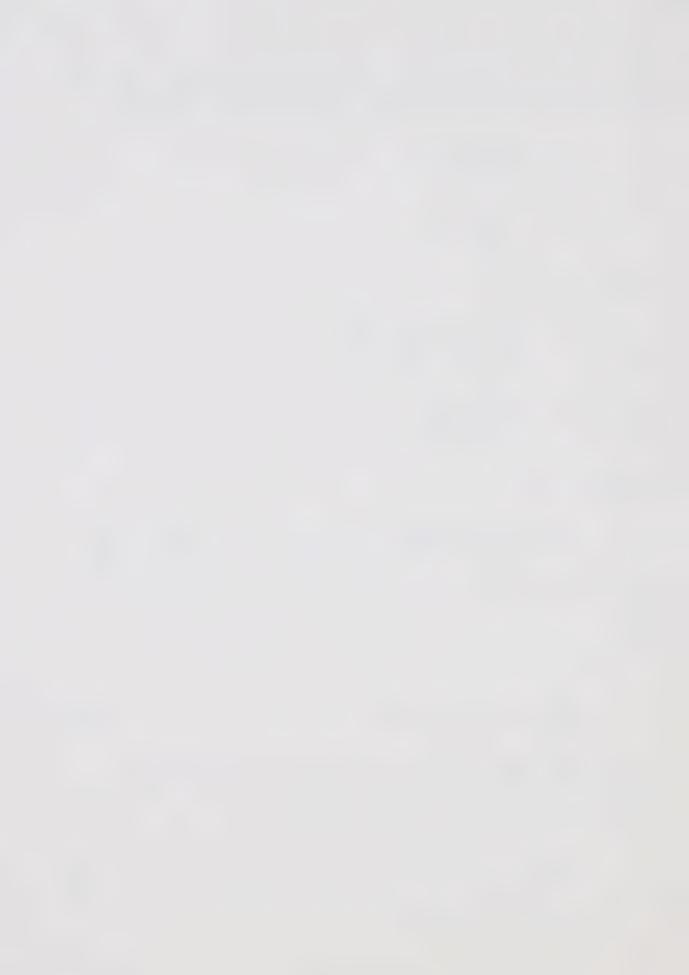
The fourth boundary condition, $\bar{y}=0$, $\frac{\partial \bar{\Psi}}{\partial \bar{y}}=\frac{\bar{h}}{\bar{\Psi}_C}$ allows us to obtain an expression for the pressure gradient, $\frac{d\bar{p}}{d\bar{x}}$.

$$\frac{d\overline{p}}{d\overline{x}} = D_1(\overline{x}) - D_2(\overline{x}) \overline{\Psi}_C$$
 (3.5)

where $D_1(\bar{x})$ and $D_2(\bar{x})$ are given by the expressions of Equation (3.6) below

$$D_1(\bar{x}) = 6.0/\bar{h}^2$$

$$D_2(\bar{x}) = 12.0/\bar{h}^3$$
(3.6)



The dimensionless mass flow, $\overline{\Psi}_{c}$, is found by substituting the expression for $\frac{d\overline{p}}{d\overline{x}}$ of Equation (3.5),

into the integral Equation (2.20), yielding

$$\overline{\Psi}_{c} = \int_{0}^{1} D_{1}(\overline{x}) d\overline{x} / \int_{0}^{1} D_{2}(\overline{x}) d\overline{x}$$
 (3.7)

SOLUTION OF THE MOMENTUM EQUATION NEGLECTING
INERTIA TERMS AND FOR VARIABLE VISCOSITY

When the inertia terms are neglected, but variable viscosity is preserved, the momentum Equation (2.24) yields.

$$\frac{\partial}{\partial \bar{y}} \left(\bar{\mu} \frac{\partial^2 \bar{\psi}}{\partial \bar{y}^2} \right) = \frac{\bar{h}^3}{\bar{\psi}_C} \frac{d\bar{p}}{d\bar{x}}$$
 (3.8)

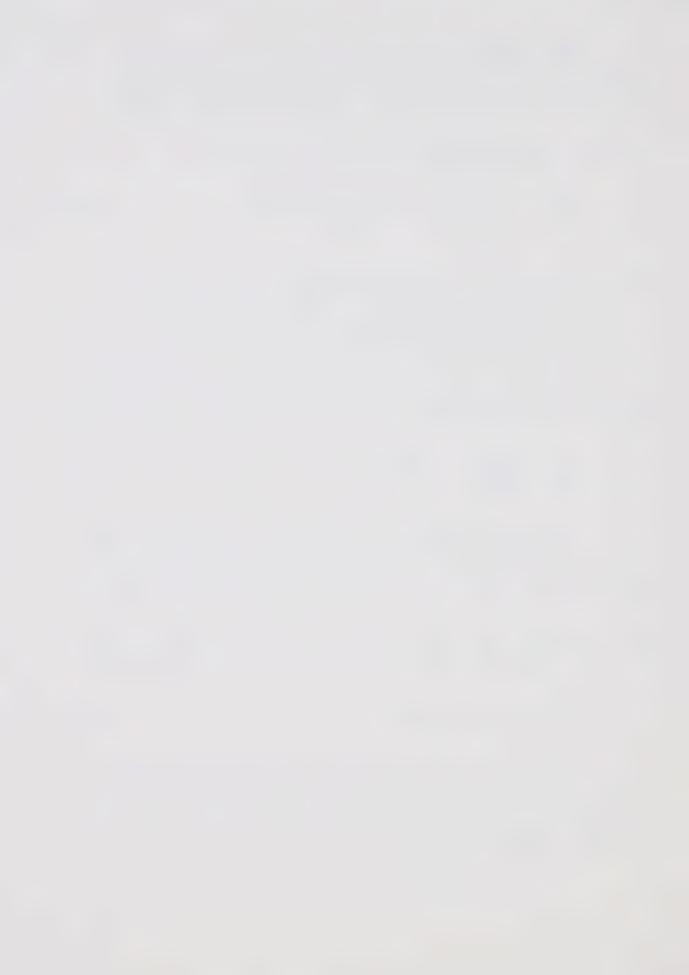
The above equation is integrated three times with respect to \bar{y} , whence the following equation is obtained.

$$\overline{\Psi} = \frac{\overline{h}^3}{\overline{\Psi}_c} \frac{d\overline{p}}{d\overline{x}} \int_{0}^{\overline{y}} \left(\int_{0}^{\overline{y}} \frac{\overline{y}}{\overline{\mu}} d\overline{y} \right) d\overline{y} + C_1(\overline{x}) \int_{0}^{\overline{y}} \left(\int_{0}^{\overline{y}} \frac{1}{\overline{\mu}} d\overline{y} \right) d\overline{y}$$

$$+ C_2(\overline{x}) \overline{y} + C_3(\overline{x})$$

$$(3.9)$$

The coeffs. $C_1(\bar{x})$, $C_2(\bar{x})$, and $C_3(\bar{x})$ of Equation (3.9) are determined from the boundary conditions as listed in (3.3). These become:



$$C_{1}(\bar{x}) = \begin{bmatrix} 1 - \frac{\bar{h}^{3}}{\bar{\Psi}_{c}} \frac{d\bar{p}}{d\bar{x}} & (A_{1}(\bar{x}, 1) - A_{2}(\bar{x}, 1) \end{bmatrix} / \begin{bmatrix} A_{3}(\bar{x}, 1) - A_{4}(\bar{x}, 1) \\ - \begin{bmatrix} \frac{\bar{h}^{3}}{\bar{\Psi}_{c}} \frac{d\bar{p}}{d\bar{x}} & A_{2}(\bar{x}, 1) + C_{1}(\bar{x}) & A_{4}(\bar{x}, 1) \end{bmatrix} / \begin{bmatrix} A_{3}(\bar{x}, 1) - A_{4}(\bar{x}, 1) \\ - \begin{bmatrix} \frac{\bar{h}^{3}}{\bar{\Psi}_{c}} \frac{d\bar{p}}{d\bar{x}} & A_{2}(\bar{x}, 1) + C_{1}(\bar{x}) & A_{4}(\bar{x}, 1) \end{bmatrix}$$

$$C_{2}(\bar{x}) = 0$$
(3.10)

The fourth boundary condition allows us to determine an expression for dp in the same form as Equation (3.5). $D_1(\bar{x})$, and $D_2(\bar{x})$ now become:

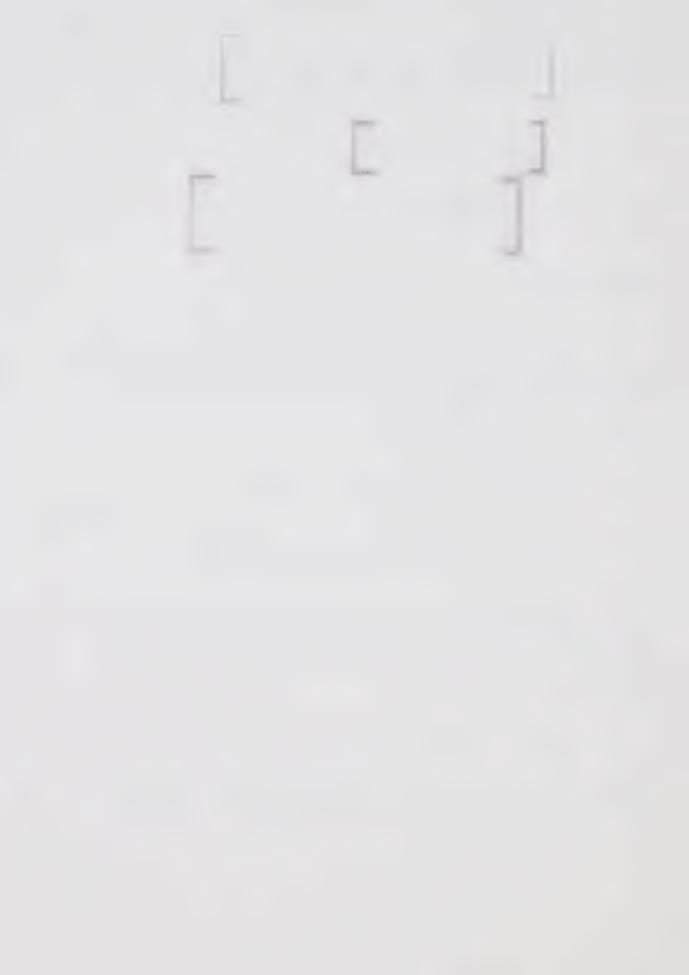
$$D_{1}(\bar{x}) = -1.0/\bar{h}^{2}[A_{2}(\bar{x},1) - B_{2}(\bar{x})]$$

$$D_{2}(\bar{x}) = B_{1}(\bar{x})/\bar{h}^{3}[A_{2}(\bar{x},1) - B_{2}(\bar{x})]$$
(3.11)

An expression for $\overline{\Psi}_{_{\mathbf{C}}}$ is likewise obtained, and retains the same form as it does in Equation (3.7). In the above,

$$B_{1}(\bar{x}) = A_{4}(\bar{x}, 1)/[A_{3}(\bar{x}, 1) - A_{4}(\bar{x}, 1)]$$

$$B_{2}(\bar{x}) = A_{4}(\bar{x}, 1)[A_{1}(\bar{x}, 1) - A_{2}(\bar{x}, 1)]/[A_{3}(\bar{x}, 1) - A_{4}(\bar{x}, 1)]$$
(3.12)



and

$$A_{1}(\bar{x}, 1) = \int_{0}^{1} (\int_{0}^{\bar{y}} \frac{\bar{y}}{\bar{\mu}} d\bar{y}) d\bar{y}$$

$$A_{2}(\bar{x}, 1) = \int_{0}^{1} \frac{\bar{y}}{\bar{\mu}} d\bar{y}$$

$$A_{3}(\bar{x}, 1) = \int_{0}^{1} (\int_{0}^{\bar{y}} \frac{1}{\bar{\mu}} d\bar{y}) d\bar{y}$$

$$A_{4}(\bar{x}, 1) = \int_{0}^{1} \frac{1}{\bar{\mu}} d\bar{y}$$

$$(3.13)$$

We are now in a position to evaluate $C_1(\bar{x})$ and $C_2(\bar{x})$, provided the viscosity distribution is known.

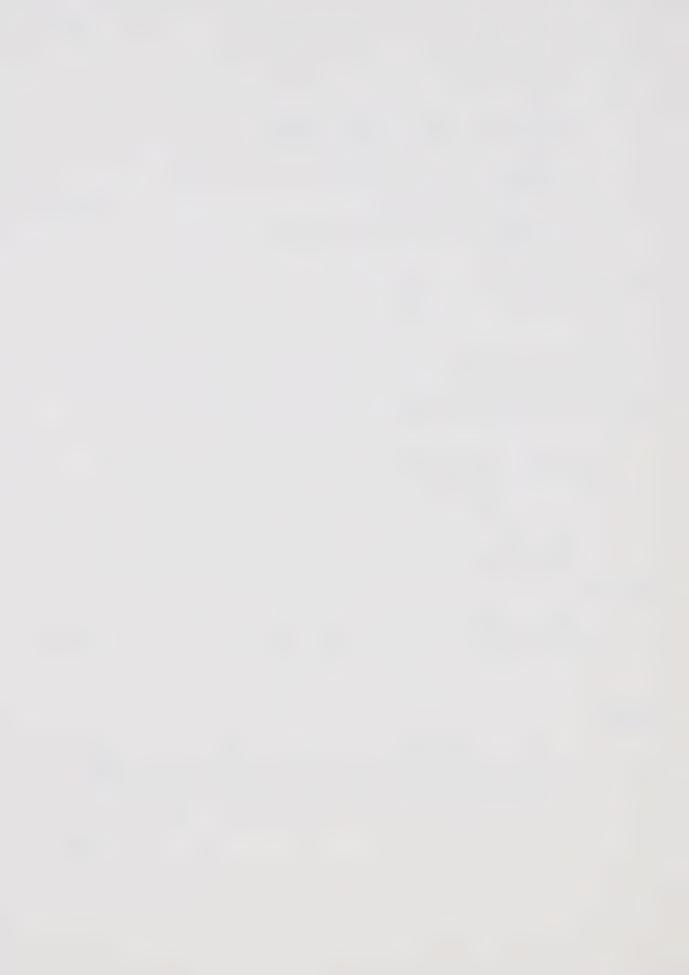
SOLUTION OF THE MOMENTUM EQUATION INCLUDING INERTIA TERMS AND FOR VARIABLE VISCOSITY

The momentum Equation (2.24) can be rewritten as follows:

$$\frac{\partial}{\partial \overline{y}} \left(\overline{\mu} \frac{\partial^2 \overline{\psi}}{\partial \overline{y}^2} \right) = F(\overline{\Psi}) + \frac{\overline{h}^3}{\overline{\Psi}_C} \frac{d\overline{p}}{d\overline{x}}$$
 (3.14)

where

$$F(\overline{\Psi}) = Re^* \overline{h} \quad \overline{\Psi}_C \left[\frac{\partial \overline{\Psi}}{\partial \overline{y}} \left(\frac{\partial}{\partial \overline{x}} \left(\frac{\partial \overline{\Psi}}{\partial \overline{y}} \right) + \frac{\overline{h}_r - 1}{\overline{h}} \frac{\partial \overline{\Psi}}{\partial \overline{y}} \right) - \frac{\partial \overline{\Psi}}{\partial \overline{x}} \frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2} \right]$$
(3.15)



(3.17)

Integrating Eq. (3.14) we obtain

$$\overline{\Psi} = \frac{\overline{h}^3}{\overline{\Psi}_C} \frac{d\overline{p}}{d\overline{x}} \int_0^{\overline{y}} \left(\int_0^{\overline{y}} \frac{\overline{y}}{\overline{\mu}} d\overline{y} \right) d\overline{y} + \int_0^{\overline{y}} \left(\int_0^{\overline{y}} \left(\frac{1}{\overline{\mu}} \int_0^{\overline{y}} F(\overline{\Psi}) d\overline{y} \right) d\overline{y} \right) d\overline{y}$$

$$+ \quad C_{1}(\bar{x}) \quad \int_{0}^{\bar{y}} \left(\int_{0}^{\bar{y}} \frac{1}{\bar{\mu}} d\bar{y} \right) d\bar{y} + C_{2}(\bar{x}) \quad \bar{y} + C_{3}(\bar{x})$$
 (3.16)

where,

$$C_{1}(\bar{x}) = \begin{bmatrix} 1 + A_{6}(\bar{x}, 1) - A_{5}(\bar{x}, 1) - \frac{\bar{h}^{3}}{\bar{\Psi}_{C}} & \frac{d\bar{p}}{d\bar{x}} & [A_{1}(x, 1) \\ - A_{2}(\bar{x}, 1)] \end{bmatrix} / \begin{bmatrix} A_{3}(\bar{x}, 1) - A_{4}(\bar{x}, 1) \end{bmatrix}$$

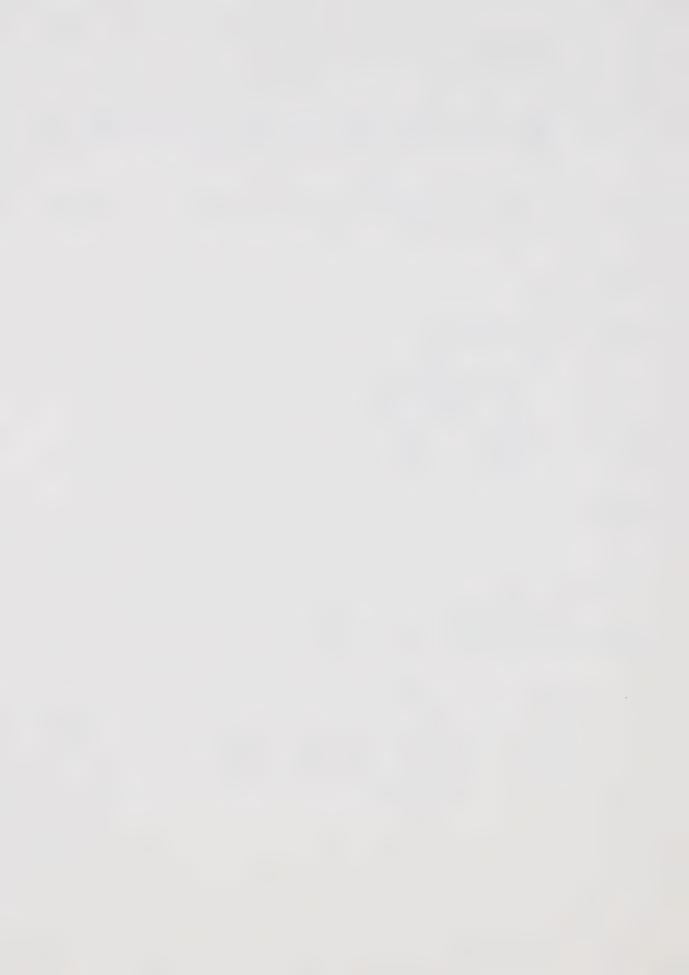
$$C_{2}(\bar{x}) = - \begin{bmatrix} A_{6}(\bar{x}, 1) + \frac{\bar{h}^{3}}{\bar{\Psi}_{C}} & \frac{d\bar{p}}{d\bar{x}} & A_{2}(\bar{x}, 1) + C_{1}(\bar{x}) & A_{4}(\bar{x}, 1) \end{bmatrix}$$

$$C_{3}(\bar{x}) = 0$$

The pressure gradient, $\frac{d\overline{p}}{dx}$, has the same form as expressed by Equation (3.5), where now

$$D_{1}(\bar{x}) = -1.0/\bar{h}^{2} [A_{2}(\bar{x},1) - B_{2}(\bar{x})]$$

$$D_{2}(\bar{x}) = B_{1}(\bar{x})/\bar{h}^{3} [A_{2}(\bar{x},1) - B_{2}(\bar{x})]$$
(3.18)



In the above,

$$B_{1}(\bar{x}) = A_{6}(\bar{x},1) + A_{4}(\bar{x},1) [1 + A_{6}(\bar{x},1) - A_{5}(\bar{x},1)] /$$

$$[A_{3}(\bar{x},1) - A_{4}(\bar{x},1)]$$

$$B_{2}(\bar{x}) = A_{4}(\bar{x},1) \cdot [A_{1}(\bar{x},1) - A_{2}(\bar{x},1)]/[A_{3}(\bar{x},1) - A_{4}(\bar{x},1)]$$
(3.19)

and,

$$A_{5}(\bar{x}, \underline{l}) = \int_{0}^{1} \left(\int_{0}^{\bar{y}} \left(\frac{1}{\mu} \int_{0}^{\bar{y}} F(\bar{y}) d\bar{y} \right) d\bar{y} \right) d\bar{y}$$

$$A_{6}(\bar{x}, \underline{l}) = \int_{0}^{1} \left(\frac{1}{\mu} \int_{0}^{\bar{y}} F(\bar{y}) d\bar{y} \right) d\bar{y}$$

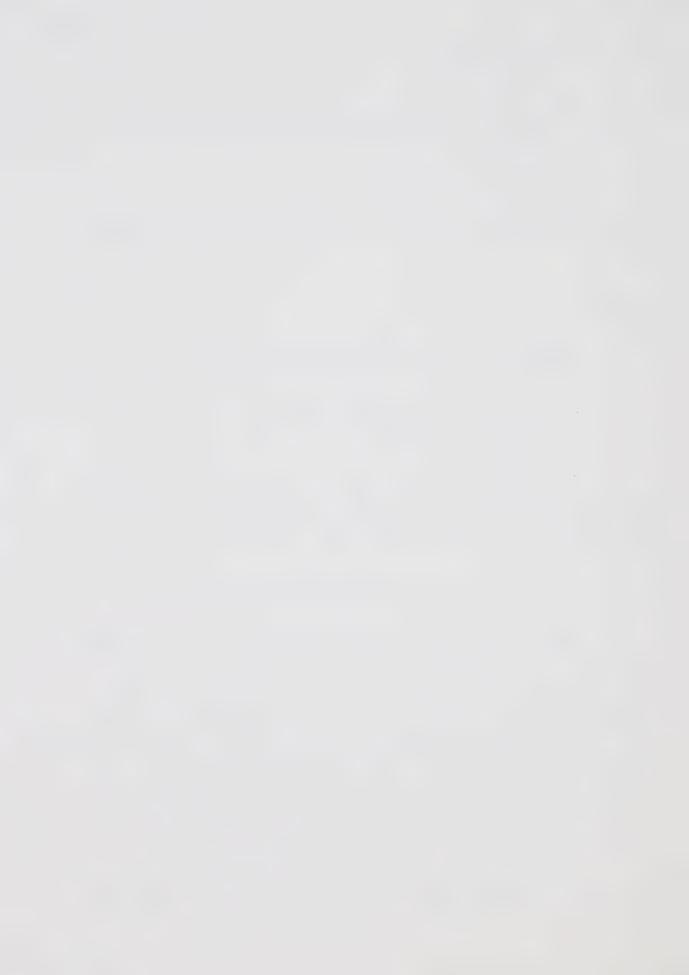
$$(3.20)$$

Thus, providing us with the viscosity distribution, would allow $C_1(\bar{x})$ and $C_2(\bar{x})$ to be evaluated.

SOLUTION OF THE ENERGY EQUATION

For the case of variable viscosity, it is necessary to obtain the viscosity distribution, before the stream function can be computed. This is accomplished by first solving the Energy Equation (2.25) together with the boundary conditions (2.21), using the Crank-Nicholson method. The viscosity distribution is then obtained by interpolation from a set of data which had been previously read in.

In the numerical process, (See Appendix B), the derivatives are replaced by the central finite difference



approximations, and the terms are rearranged to obtain the following equation.

$$a_{i,j}$$
 $\bar{T}_{i+1,j-1}$ + $b_{i,j}$ $\bar{T}_{i+1,j}$ + $c_{i,j}$ $\bar{T}_{i+1,j+1}$ = $d_{i,j}$ (3.21)

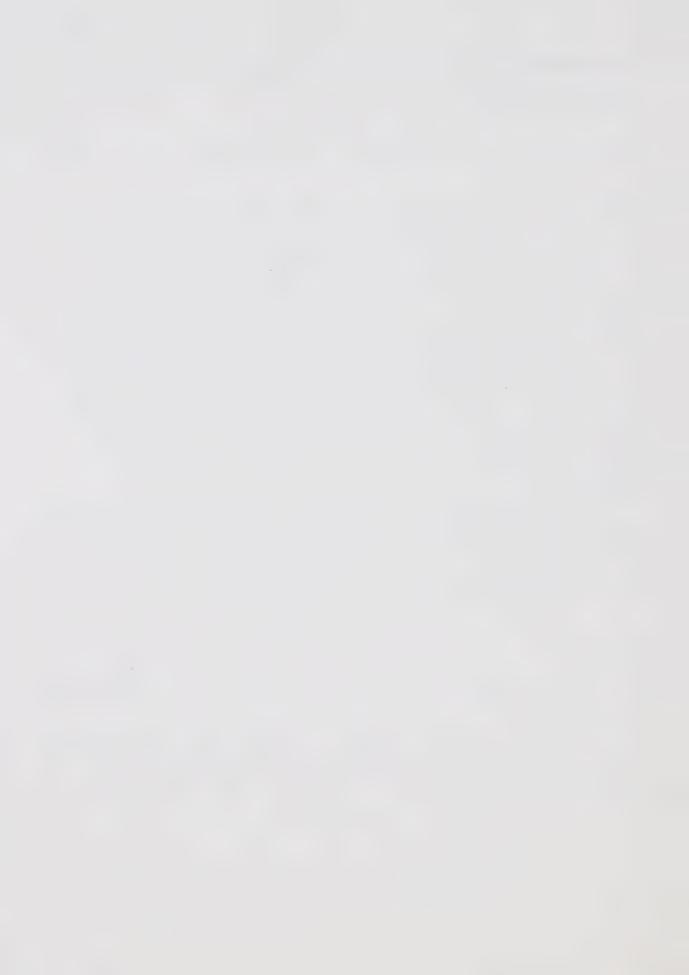
where a_{i,j}, b_{i,j}, c_{i,j} and d_{i,j} are defined in Appendix B. It should be noted that the coefficients a_{i,j}, b_{i,j}, and c_{i,j} are known from the solution of the momentum equation alone. However, d_{i,j} in addition depends on the temperature at the preceding section. The temperature distribution at the inlet is given by the last of Equations (2.21). Using these initial values, and marching from section to section along the bearing, one obtains the complete temperature distribution.

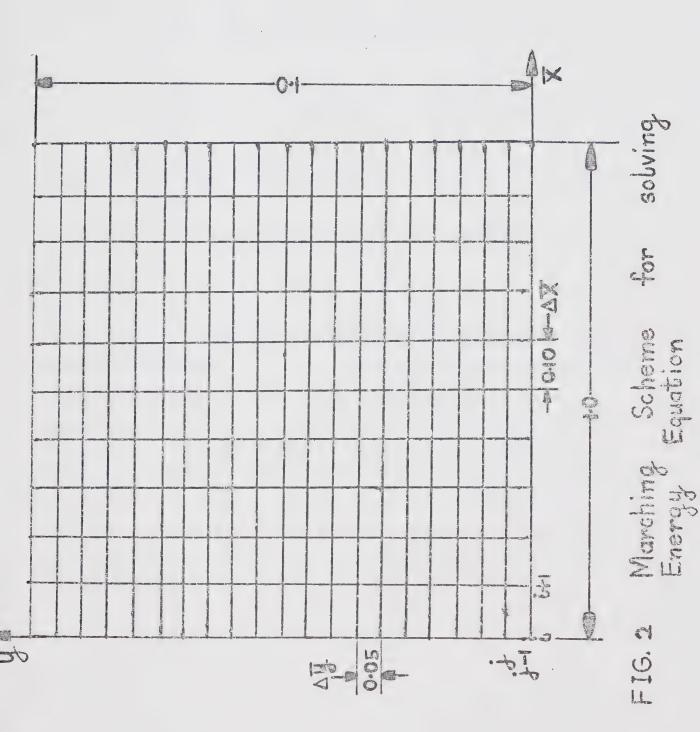
For the numerical procedure, the square grid presented below was employed, with the spacing interval in the \bar{x} and the \bar{y} directions taken as 0.1 and 0.05 respectively.

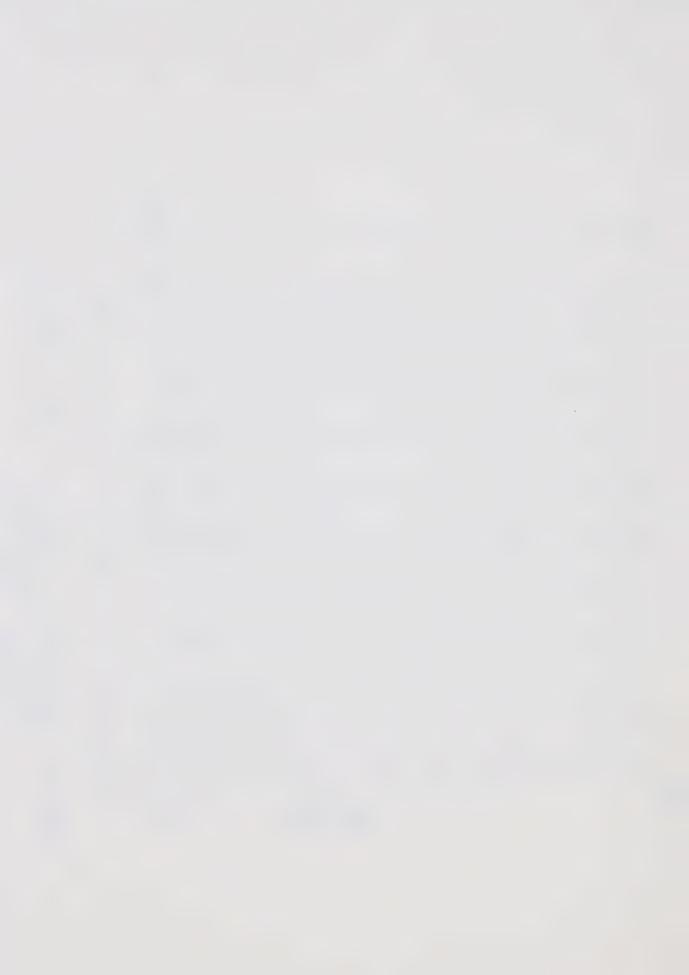
For i = 1, Equation (3.21) becomes,

$$a_{1,j}$$
 $\bar{T}_{2,j-1}$ + $b_{1,j}$ $\bar{T}_{2,j}$ + $c_{1,j}$ $\bar{T}_{2,j+1}$ = $d_{1,j}$ (3.22)

Using values of j from 2 to N-1, the above equation yields a linear system of N-2 equations with N-2 unknowns.







$$a_{1,2}\bar{T}_{2,1} + b_{1,2}\bar{T}_{2,2} + c_{1,2}\bar{T}_{2,3} = d_{1,2}$$

$$a_{1,3}\bar{T}_{2,2} + b_{1,3}\bar{T}_{2,3} + c_{1,3}\bar{T}_{2,4} = d_{1,3}$$

$$a_{1,4}\bar{T}_{2,3} + b_{1,4}\bar{T}_{2,4} + c_{1,4}\bar{T}_{2,5} = d_{1,4}$$

$$a_{1,N-3}\bar{T}_{2,N-4} + b_{1,N-3}\bar{T}_{2,N-3} + c_{1,N-3}\bar{T}_{2,N-2} = d_{1,N-3}$$

$$a_{1,N-2}\bar{T}_{2,N-3} + b_{1,N-2}\bar{T}_{2,N-2} + c_{1,N-2}\bar{T}_{2,N-1} = d_{1,N-2}$$

$$a_{1,N-1}\bar{T}_{2,N-2} + b_{1,N-1}\bar{T}_{2,N-1} + c_{1,N-1}\bar{T}_{2,N} = d_{1,N-1}$$

$$(3.23)$$

Since the boundary conditions $\overline{T}(I,1)$ and $\overline{T}(I,N)$ are known for $I=1,2,\ldots$ M, the system of Equations (3.23) can be rewritten in matrix form. The matrix is tridiagonal and of order N-2. It was solved directly, by using the method of triangular decomposition [15]. After $\overline{T}_{2,j}$ (j= 2,3, . . N-1) was evaluated, the temperature distribution throughout the grid was obtained by repeating the above procedure for each successive section.



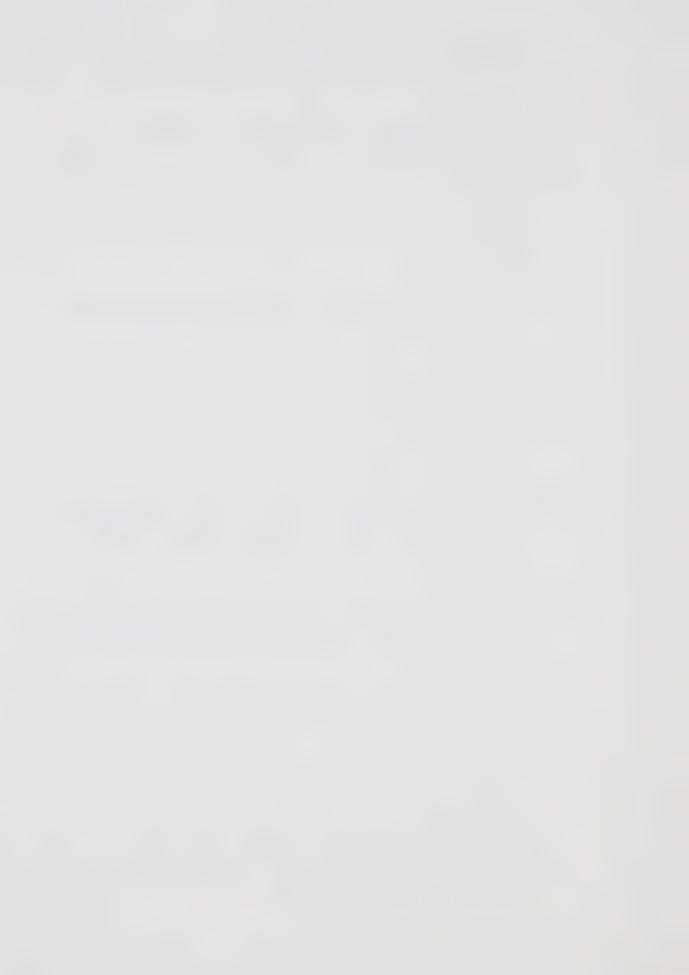
METHOD OF SOLUTION - STEP BY STEP

In the general case, the solution of our problem requires that we solve Eqs. (2.24) and (2.25), together with the boundary conditions as stated in Eqs. (2.21) and (2.26). Since Eqs. (2.24) and (2.25) are coupled through the viscosity, an iterative method is used, which involves a back and forth movement between these two equations, until the temperature distribution converges to within a prescribed error bound. Solutions are obtained for the case in which inertia terms are not important, and also for the case when these terms are important. For the latter case, the solution neglecting the inertia terms is used as a first approximation, then these terms are included by use of a correcting procedure. The method of solution is as outlined in the following steps.

- (1) Evaluate $D_1(\bar{x})$ and $D_2(\bar{x})$ by using Eqs. (3.6).
- (2) Find the mass flow by use of Eq. (3.7).
- (3) Use Eq. (3.5) to determine the pressure gradient, $\frac{d\bar{p}}{d\bar{x}}$.
- (4) Determine the value of the coeffs. $C_1(\bar{x})$ and $C_2(\bar{x})$ by using Eqs. (3.4).
- (5) From Eq. (3.2), evaluate the stream function distribution.
- (6) Obtain the temperature distribution by solving Eq. (2.25) for constant viscosity.



- (7) Evaluate $A_1(\bar{x},1)$ through $A_4(\bar{x},1)$ by use of Eqs. (3.13)
- (8) Use Eqs. (3.12) to find $B_1(\bar{x})$ and $B_2(\bar{x})$.
- (9) Determine $D_1(\bar{x})$ and $D_2(\bar{x})$ by use of Eqs. (3.11).
- (10) Find the mass flow by use of Eq. (3.7).
- (11) Use Eq. (3.5) to compute the pressure gradient, $\frac{d\overline{p}}{d\overline{x}}$.
- (12) Evaluate the coeffs. $C_1(\bar{x})$ and $C_2(\bar{x})$ by use of Eqs. (3.10).
- (13) Obtain the stream function distribution by using Eq. (3.9).
- (14) Determine the temperature distribution by solving Eq. (2.25).
- (15) If the convergence criteria on the temperature is satisfied after the first iteration go to step (17).
- (16) If the convergence criteria on the termperature is not satisfied, after the first iteration go to step (7).
- (17) Evaluate the bearing characteristics and print results.
- (18) If inertia terms are not important, go to step (33).
- (19) If inertia terms are important continue.
- (20) Use Eq. (3.15) to find the correction for the presence of inertia terms.



- (21) Evaluate $A_1(\bar{x},1)$ through $A_6(\bar{x},1)$ by use of Eqs. (3.13) and (3.20).
- (22) Use Eqs. (3.19) to find $B_1(\bar{x})$ and $B_2(\bar{x})$.
- (23) Compute $D_1(\bar{x})$ and $D_2(\bar{x})$ by using Eqs. (3.18).
- (24) Determine the mass flow by use of Eq. (3.7).
- (25) Use Eq. (3.5) to find the pressure gradient, hence determine the pressure distribution.
- (26) Evaluate the coeffs. $C_1(\bar{x})$ and $C_2(\bar{x})$ by use of Eqs. (3.17).
- (27) Obtain the stream function distribution by use of Eq. (3.16).
- (28) If the convergence criteria on the pressure is satisfied go to step (30).
- (29) Go to step (20).
- (30) Solve Eq. (2.26) for the temperature distribution.
- (31) If the convergence criteria on the temperature is not satisfied after the first iteration, go to step (20).
- (32) Evaluate the bearing characteristics and print results.
- (33) Solution completed.



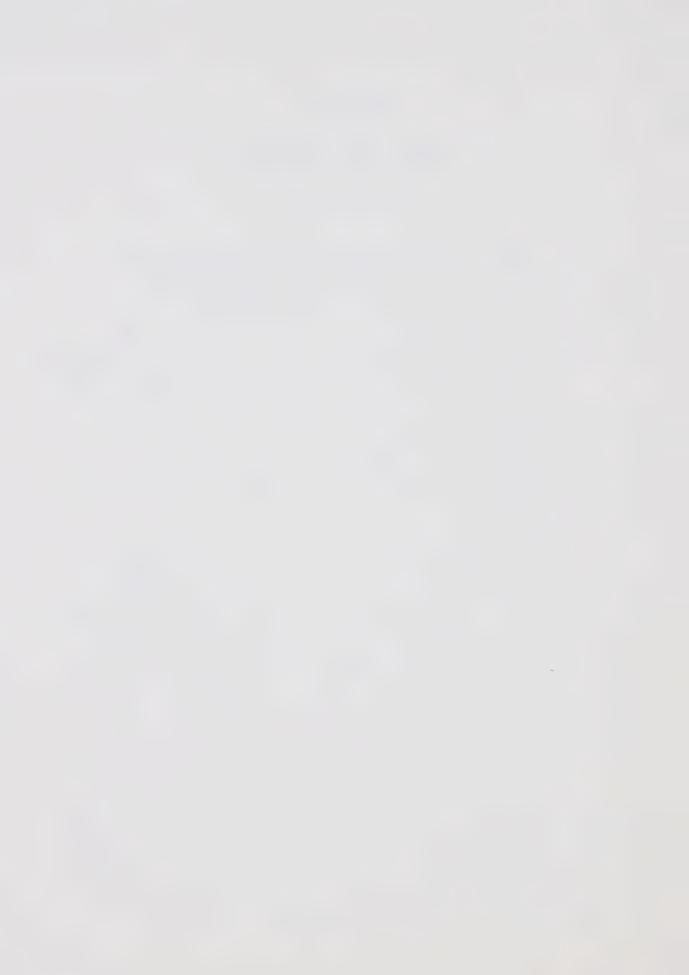
CHAPTER IV

RESULTS AND CONCLUSIONS

INTRODUCTION

In order to understand more fully the various factors which contribute to the load capacity, the Momentum Eq. (2.24) together with the Energy Eq. (2.25) are solved for several different cases, which are as follows:

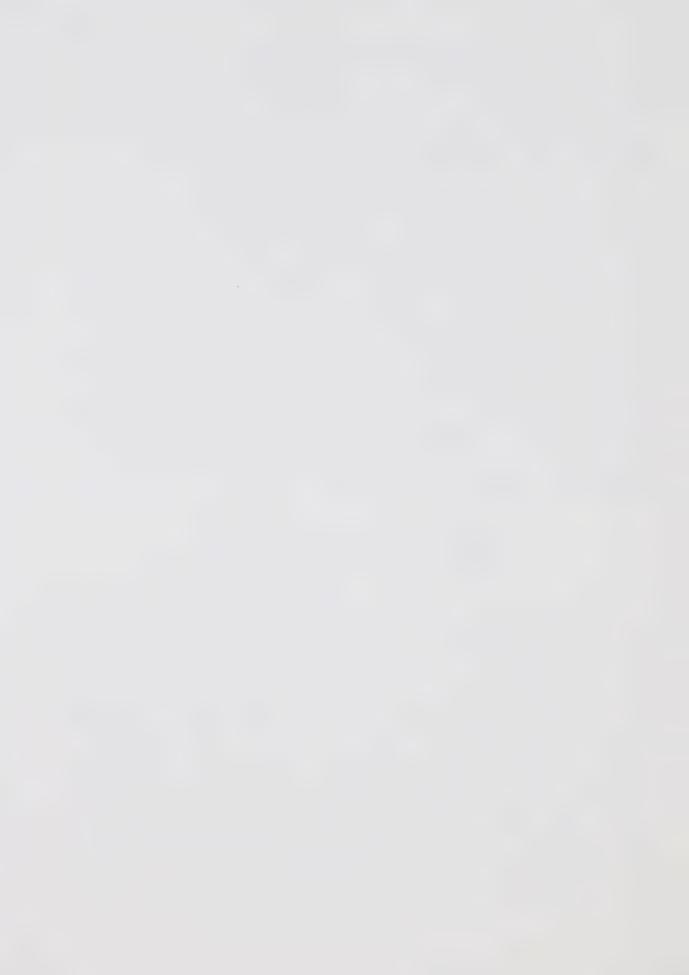
- (a) The momentum equation neglecting inertia terms, together with the energy equation are solved for various boundary conditions on temperature. Sample results are listed in Tables la through ld, and graphs are presented in Figs. 4 through 15.
- (b) Assuming constant viscosity, the momentum equation is first solved for various values of modified Reynolds number. Afterwards, it is solved together with the energy equation, for three different temperature boundary conditions, but this time retaining the viscosity variation with temperature. Tables 2a through 2c list some sample results, and graphs are presented in Figs. 16 through 23.
- (c) Considering variable viscosity, the momentum equation neglecting inertia terms, together with the energy equation, are solved for various values of inlet to outlet ratio, \bar{h}_r , Sample results are listed in tables 3a through 3c, and graphs are presented in Figs. 24 through 35.



- (d) Neglecting the inertia terms, the momentum equation together with the energy equation are solved for three different T_s/T_p ratios, and for constant Pe; while at the same time retaining the viscosity variation with temperature. In this case, the results obtained enable us to examine the effects of dissipation on the load capacity of the bearing. Graphs are plotted in Figs. 36 through 46, and sample results are listed in tables 4a through 4d.
- (e) In order to examine the effects of convection terms on the load capacity of the bearing, a method similar to that in (d) was undertaken, but this time keeping PE constant instead of Pe. Graphs illustrating results are then plotted in Figs. 47 through 57, while sample results are presented in tables 5a through 5e.

EFFECTS OF VARIOUS TEMPERATURE BOUNDARY CONDITIONS - NO INERTIA

Figs. 4 through 6 plot the velocity distributions for the following boundary conditions: (i) $T_s = 200^{\circ}F$, $T_p = 100^{\circ}F$, (ii) $T_s = 100^{\circ}F$, $T_p = 100^{\circ}F$ and (iii) $T_s = 50^{\circ}F$, $T_p = 100^{\circ}F$. All the dimensionless groups have the same values, and these boundary conditions were chosen to find out what happens to the load capacity when the slider is cooled. It is possible to get some idea of what the pressure distributions for the three different boundary conditions are like, by examining their velocity and temperature profiles.



If we first examine the shape of the velocity distribution at various sections, as illustrated in any of Figs. 4, 5, or 6, we see that the profile changes from concave inwards at the entrance to convex outwards at the exit. This is readily explained, because the pressure gradient, which is positive at the inlet, passes through zero around the mid-section of the bearing, then becomes negative at the exit. Also, by examining only the inlet and outlet velocity profiles of Figs. 4 through 6, we can tell which pressure distributions are higher. It is reasonable to expect that large positive pressure gradients at the bearing inlet would tend to cause backflow, while large negative pressure gradients at the exit would cause the velocity profile at this section to be more convex outwards.

These two effects can be clearly seen in Fig. 6. Note that the outlet velocity profile becomes more convex outwards as the slider is cooled, indicating an increased mass flow rate. The temperature distribution for the case $T_s = 200^{\circ}F$, $T_p = 100^{\circ}F$ appears in Fig. 7, whence the rise in temperature as the lubricant flows through the bearing is readily seen. Plots of the pressure distribution for the three cases appear in Fig. 8, and agree with what we were led to expect from observations just made.

Fig. 9 presents plots of the shear stress distribution at the slider for the three cases being studied. Since $\overline{\tau}=\frac{\partial \overline{u}}{h}$, then the shear stress at the slider depends on both the viscosity and the velocity gradient at the said interface.



Examination of Figs. 4 through 6 show that the magnitude of the belocity gradient at the slider decreases as the slider temperature decreases; but since the viscosity rises quite rapidly with decreasing temperature, it is very likely that the colder slider will cause larger shear stresses to be developed. This is indeed the case as can be seen from the curves plotted in Fig. 9.

Note that for the colder slider temperatures, the velocity gradient passes through zero, then becomes positive towards the bearing outlet. This explains why the shear stress curves cross each other, and approach zero at points at or just before the outlet.

Figs. 10 through 12 present curves of load capacity versus T_s/T_p for the following cases: (i) T_p fixed at 100°F, slider cooled. (ii) T_s fixed at 100°F, pad heated (iii) T_s+T_p fixed at 350°F, slider cooled and at the same time pad heated. Comparison of these curves show that providing Pe, PE, and \vec{h}_r are the same, the load capacity for each of the three cases just mentioned, and for the same T_s/T_p ratio are quite close, although the actual boundary conditions differ greatly. It can also be seen that the divergence becomes smaller in the range $0.5 \le T_s/T_p \le 2.0$, which includes the normal operating range of most bearings.

Figs. 13 and 14 present curves of drag versus T_s/T_p for the first two cases listed in the previous paragraph. Applying a similar reasoning, it is seen that the difference in drag is quite small for the range 0.5 $\frac{1}{2}$ $T_s/T_p \leq$ 2.0. The



actual divergence in load capacity, drag, etc. for the same T_s/T_p ratio is due to the differences in viscosity distribution which follows because of variations in the temperature boundary conditions. Fig. 15 shows the influence of the actual temperature boundary conditions on load capacity, for two different T_s/T_p ratios. It is seen that both larger and smaller values of T_s+T_p tend to cause greater divergence in the load capacity values, but this divergence is much more pronounced for the smaller T_s/T_p ratio.

INFLUENCE OF INERTIA TERMS

Figs. 16 and 17 present the velocity distributions for the cases where inertia terms are not included and where they are included respectively. It is seen that when the inertia terms are included, the velocity gradient at the inlet is close to zero near to the pad, but it is slightly greater than zero at a similar point for the inertia-less case. Thus the pressure gradient at the inlet when inertia terms are included, should be slightly larger than for the case of no inertia. However, the difference in the outlet velocity profiles is not easily discernible, so we would expect the pressure gradients at this section to be quite close.

Temperature distributions for the two cases being discussed are presented in Figs. 18 and 19 respectively. The temperature profiles are quite close, and there are no significant differences between the two. It is possible

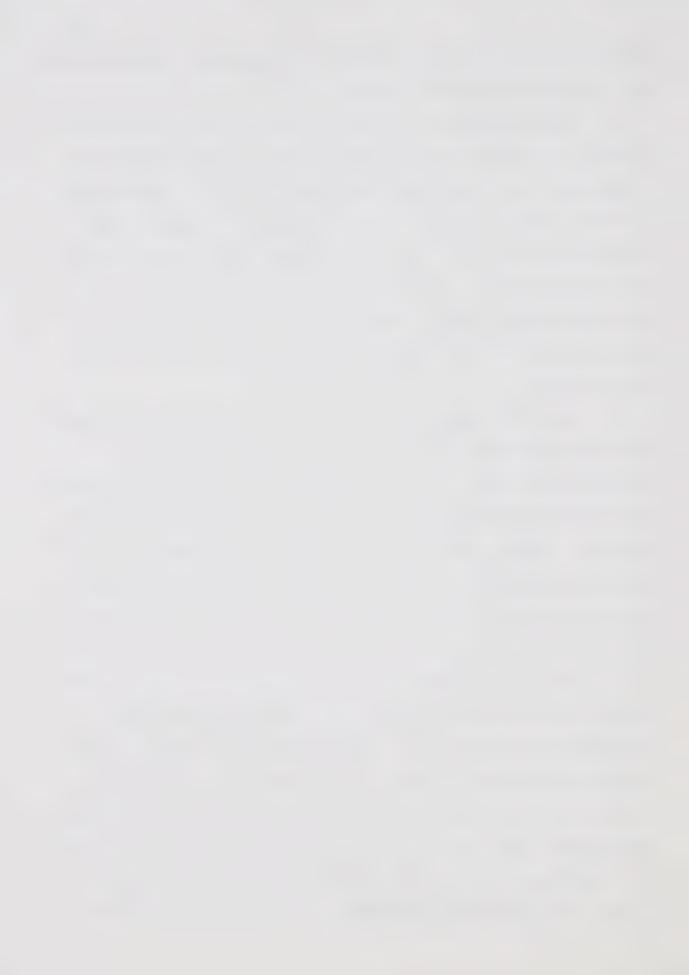


though for both cases, to observe the heating of the lubricant as it flows through the bearing.

Fig. 20 presents curves of the pressure distribution; whence it is seen that inclusion of the inertia terms gives a slightly higher pressure distribution, which in turn yields a larger load-capacity. Fig. 21 presents the shear stress distribution for Re* = 0.5 and for the cases with and without the inertia terms. It should be noted that although inclusion of the inertia terms gives a higher pressure distribution, it also causes slightly larger shear stresses at the slider.

Fig. 22 compares the results of the present work with those of Rodkiewicz and Anwar [11], and Woodhead and Kettleborough [15]. It is of interest to note that the curve for the present work is almost parallel to the one obtained in [11]. Taking the results of [15] as a standard, it is seen that the present results are quite good for small and for large values of Re*, and the error rises to a maximum of 1% for Re* around 0.6.

Fig. 23 presents curves showing the influence of the inertia terms on load capacity for different temperature boundary conditions, while table 2c lists the actual values of the percentage increase in load capacity. It should be noted that the largest errors made in neglecting the inertia terms occur when the bearing operates under normal conditions, ie. when $T_{\rm s}/T_{\rm p}$ > 1.0. For constant viscosity and for Re = 1.0, the percentage increase in load capacity is 7.95%,



which is a bit less than the value of 8.9% given in [11].

EFFECTS OF VARYING INLET TO OUTLET RATIO - NO INERTIA

Figs. 24 through 26 present the velocity distributions for the following cases respectively: (i) $\bar{h}_r = 1.75$ (ii) $\bar{h}_r = 2.25$ (iii) $\bar{h}_r = 2.75$. Notice that as \bar{h}_r increases, the backflow at the inlet of the bearing increases continuously, while the velocity profile at the outlet becomes more convex outwards. These observations would lead us to expect a rise in the pressure distribution as \bar{h}_r increases from 1.75 to 2.75. However, we must first take a look at the temperature distributions.

Figs. 27 through 29 present plots of the temperature idstributions for the three values of \bar{h}_r under consideration. The respective profiles are quite similar, so that the temperature distribution does not seem to have contributed much to the differences observed in the respective velocity distributions.

As shown by the curves of Fig. 30, the expectation of a continuous rise in the pressure profiles with \bar{h}_r is only partly correct. What can be readily seen is that for positive gradients, the smaller the value of \bar{h}_r the larger the pressure, while for negative gradients the reverse is now true.

Fig. 31 presents plots of the shear stress distribution for the values of \bar{h}_r under consideration. It should be noted that the magnitude of the shear stress decreases as

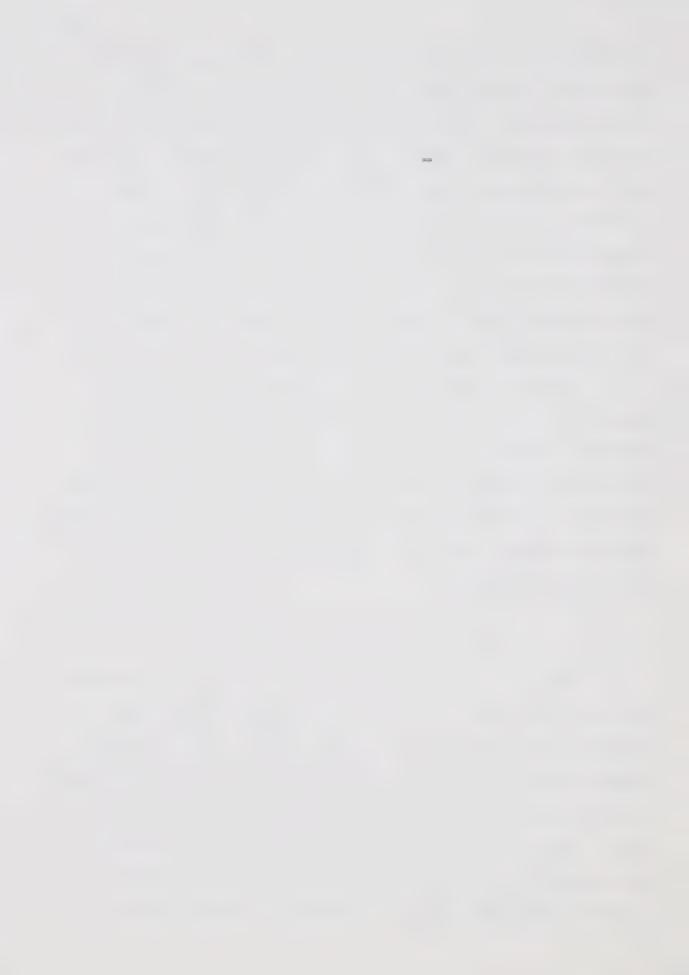


 \bar{h}_r increases. In dimensionless form, the shear stress at the slider can be represented as follows: $\bar{\tau}_o = (\bar{\mu} - \frac{\partial \bar{u}}{\partial \bar{y}})_{\bar{y}=0}$. Since the slider temperatures are all the same, and the sectional gradients $(\frac{\partial \bar{u}}{\partial \bar{y}})_{\bar{y}=0}$ for the three values of \bar{h}_r are not too different, then differences in the shear stress profiles will be influenced mainly by the variations in $1/\bar{h}$. Since \bar{h} is proportional to \bar{h}_r , then $1/\bar{h}$ α $1/\bar{h}_r$. So that increasing \bar{h}_r should cause numerically smaller values of shear stress at the slider. This is indeed the result, as can be seen from the curves of Fig. 31.

Figs. 32 through 34 plot curves of load capacity versus \bar{h}_r , for constant Pe, but for different temperature boundary conditions; while Fig. 35 compares curves with different temperature boundary conditions, but for constant Pe. For all these figures, it should be noted that the load capacity always rises to a maximum for $2.00 \le \bar{h}_r \le 2.25$, then falls gradually.

DISSIPATION EFFECTS - NO INERTIA

Figs. 36 through 38 plot the velocity distributions for PE = 1.27, 5.08 and 20.33 respectively; while other dimensionless groups have the same values. Upon examining these figures, we find that the velocity profiles become more convex outwards as PE increases, indicating a rise in mass flow. This trend might lead one to expect an increase in load capacity also, but this conclusion cannot be made without first examining the temperature distributions.

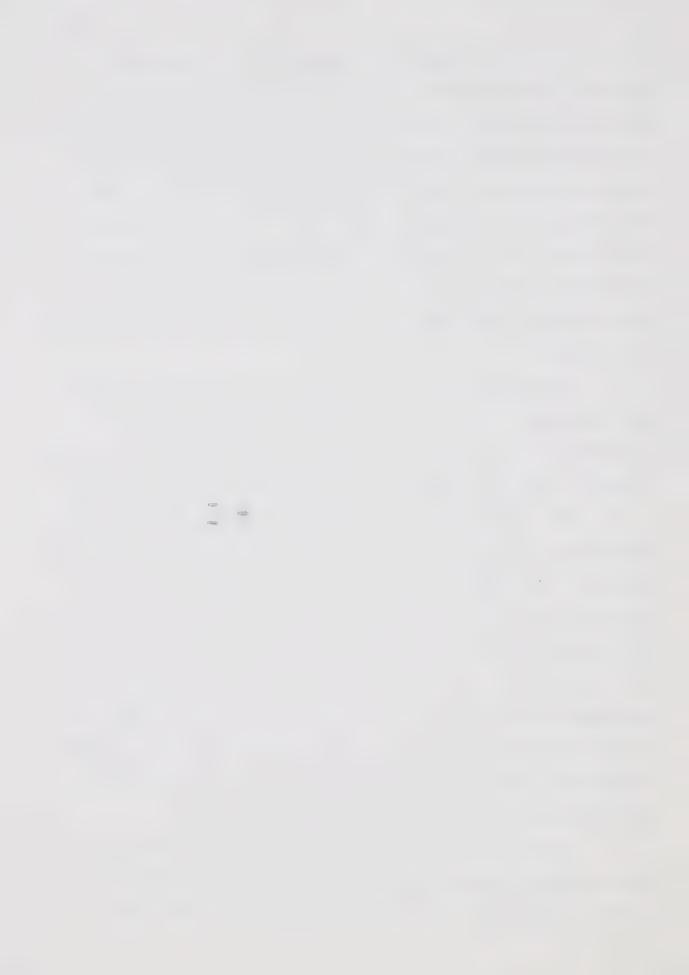


If we now examine the temperature distributions of Figs. 39 through 41, we find that the differences among the three are quite pronounced, with the temperature profiles rising continuously as PE increases. The pressure gradient is directly proportional to the lubricant viscosity, which decreases with increasing temperature. Thus the increasing mass flow as PE increases is counterbalanced by the drop in lubricant viscosity; and whether the load capacity rises or falls with PE, will depend on the combined influence of these two factors.

The curves of Fig. 42 show that the pressure profile gets smaller as PE increases. So that the reduction in viscosity seems to have had a much greater effect on the load capacity, than the small rise in mass flow of the lubricant.

The shear stress is given by $\bar{\tau}_0 = \frac{\partial \bar{u}}{\partial \bar{y}}$, and since the lubricant in contact with the slider has a constant viscosity, then the shear stress at the slider is proportional to the velocity gradient at the said interface. Examination of Figs. 36 through 38 show that the velocity gradient at the slider are all negative, and that the magnitude of the gradient at any section decreases as PE increases; so that the effect of increasing dissipation is to decrease the drag on the slider. Results for the shear stress are plotted in Fig. 43, and agree quite well with the observations just made.

Figs. 44 through 46 plot curves of load capacity versus PE for constant $P_{\rm e}$, but for different temperature boundary conditions. In all cases, it can be seen that



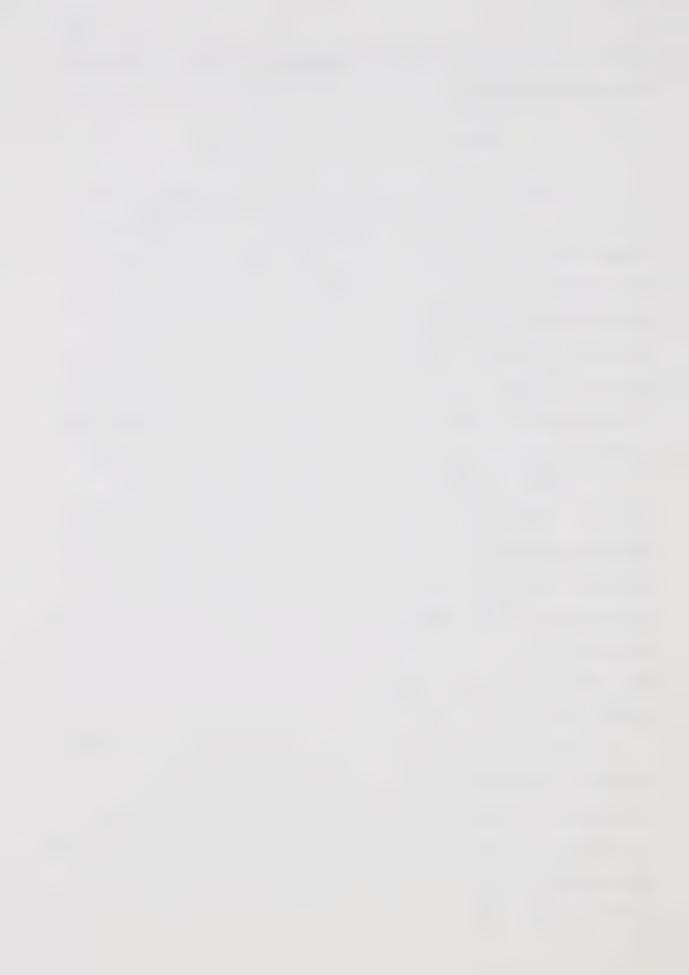
increasing PE, ie increasing dissipation, causes a reduction in the load-carrying capacity of a bearing.

CONVECTION EFFECTS - NO INERTIA

Figs. 47 through 49 present velocity distributions for Pe = 1.0, 5.0, and 20.0 respectively. Upon examining their velocity profiles, we find that there is not much difference among them, so that here the mass flow won't be important in explaining the variations in the pressure profiles. However, after examining the temperature distributions of Figs. 50 through 52, we find that the difference in the profiles is now quite pronounced, with the temperature profiles becoming smaller as P increases from 1.0 to 20.0.

These results agree with findings made by a few previous researchers. Rodkiewicz and Anwar [11] found that for a high Prandtl No. lubricant, neglecting the convective terms in the energy equation caused a considerable rise in the lubricant film temperature; and a similar finding was made by Snyder [10]. Both groups concluded that for high Prandtl No. flows, it was necessary to retain both of the convective terms in the energy equation

The pressure gradient is directly proportional to the lubricant viscosity, which increases with decreasing temperature. We should therefore expect that the pressure distribution curves would become larger as $P_{\rm e}$ increases. This expectation is proved correct by the results plotted on the curves of Fig. 53.



Again, since the viscosity is constant all along the slider, then the shear stress at the slider is proportional to the value of the velocity gradient, $\frac{\partial \bar{u}}{\partial \bar{y}}$, at the said interface. Figs. 47 through 49 show that the velocity gradients at the slider are all negative, and that the magnitude of the gradient at any section increases as Pe increases; so that the effect of increasing Pe is to increase the drag on the slider. Fig. 54 plots the shear stress distributions for the values of Pe under consideration, and it is seen that the results agree quite well with what we expected.

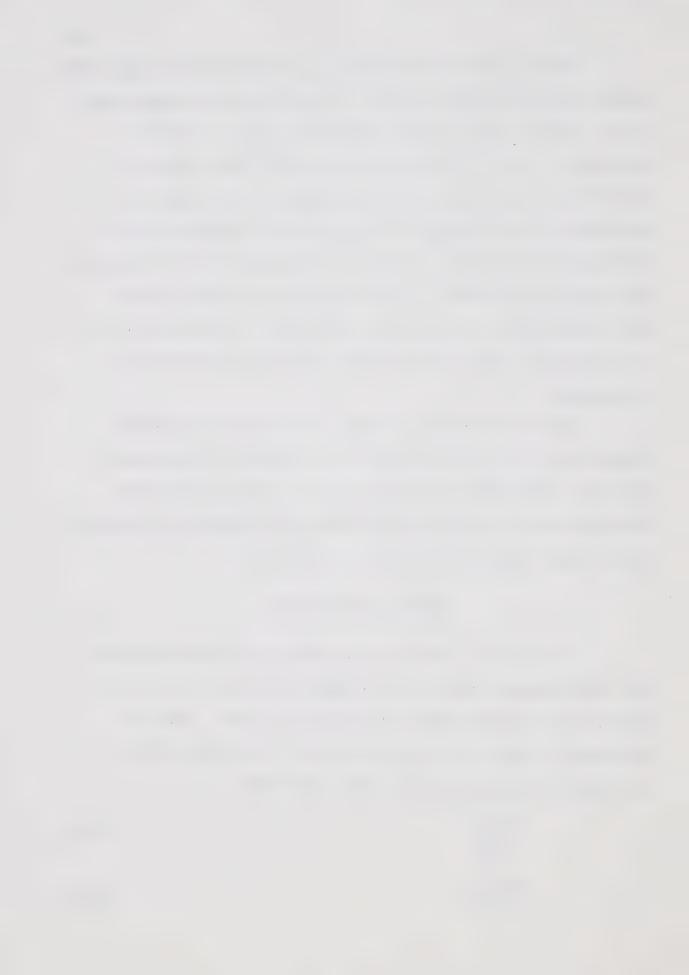
Figs. 55 through 57 plot curves of load capacity versus Pe for constant PE, but for different temperature boundary conditions. In all cases, it can be seen that increasing Pe, ie increasing convection, causes an increase in the load carrying capacity of a bearing.

SAMPLE CALCULATIONS

In order to indicate the physical significance of the dimensionless results, a sample calculation for the case of the cooled slider is presented below. This is followed by selected numerical results in tabular form. The following relationships have been used.

$$W = \frac{\overline{W}\mu_r^{UL}}{h^2_{\circ}}$$
 (4.1)

$$D = \frac{\overline{D}\mu_r^{UL}}{h_o}$$
 (4.2)



$$\Psi_{C} = \overline{\Psi}_{C} \rho Uh_{O}$$
 (4.3)

$$Pe = \frac{\rho C_p}{\kappa} \frac{Uh^2}{L}$$
 (4.4)

$$PE = \frac{U_r C_p}{\kappa} \frac{U^2}{C_p T_r}$$
 (4.5)

where L = 2",
$$\bar{h}_r$$
 = 2.0, ρ = 8.1875 x 10^{-5} $\frac{1bf - sec^2}{in^4}$,

$$C_p = 1.7886 \times 10^2 \frac{Btu - in}{lbf - sec^2 - {}^{\circ}F}$$
, and $\kappa = 1.7508 \times 10^{-6}$

$$\frac{Btu}{sec - {}^{\circ}F - in}$$
 were assumed.

Following are the three cases for the cooled slider considered:

(i) Assuming $T_s = 200^\circ F$, $T_p = 100^\circ F$, Pe = 20.0 and PE = 1.0, we obtain $T_r = (T_s + T_p)/2.0 = 150^\circ F$ and find respective absolute viscosity

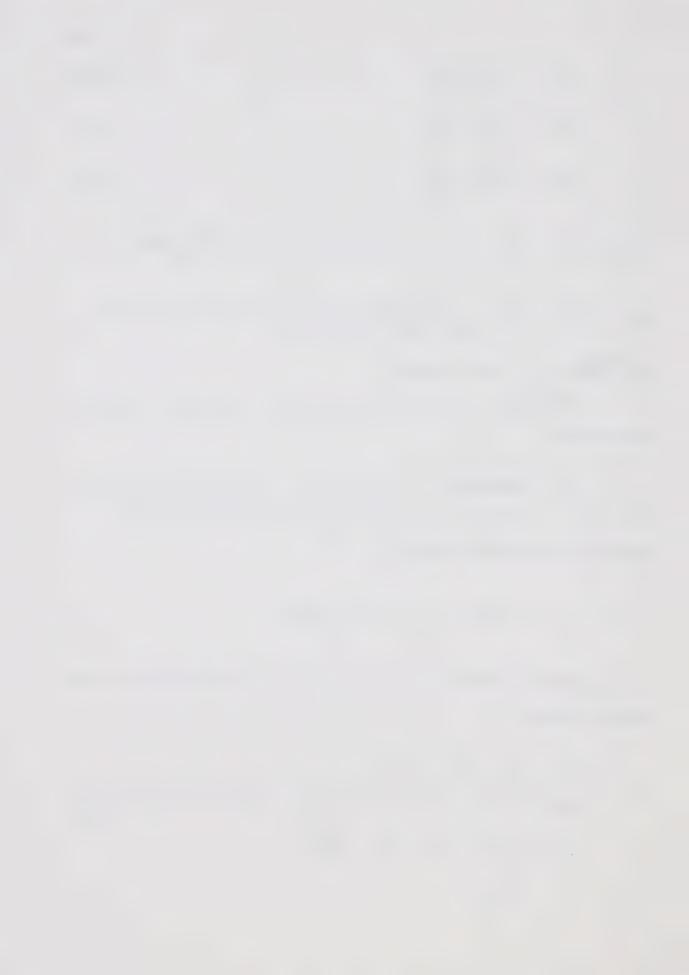
$$\mu_r = 0.3276 \times 10^{-5} \frac{1bf - sec}{in^2}$$

Having these, we find from (4.5) the velocity of the slider, namely,

$$U = 8.64 \times 10^2 \text{ in/sec}$$

Now from the above given value of the Peclect number

Pe =
$$20.0 = 8.37 \times 10^3 \frac{Uh_0^2}{L}$$



the value of h_{Ω} can be computed

$$h_0 = 2.35 \times 10^{-3}$$
 in

Under these conditions, from (4.1), (4.2), and (4.3) we obtain

$$W = 111.2 \text{ lbf/in}^{2}$$

$$D = -1.39 \text{ lbf/in}$$

$$\Psi_{C} = 3.11 \times 10^{-2} \frac{\text{lbm}}{\text{in - sec}}$$
(4.6)

(ii) Similarly for $T_s = 50$ °F, $T_p = 100$ °F, Pe = 20.0 and PE = 1.0 we obtain the following:

$$T_r = 75^{\circ}F$$
 $\mu_r = 0.25798 \times 10^{-4} \frac{lbf - sec}{in^2}$
 $U = 2.177 \times 10^2 in/sec$
 $h_o = 4.684 \times 10^{-3} in$

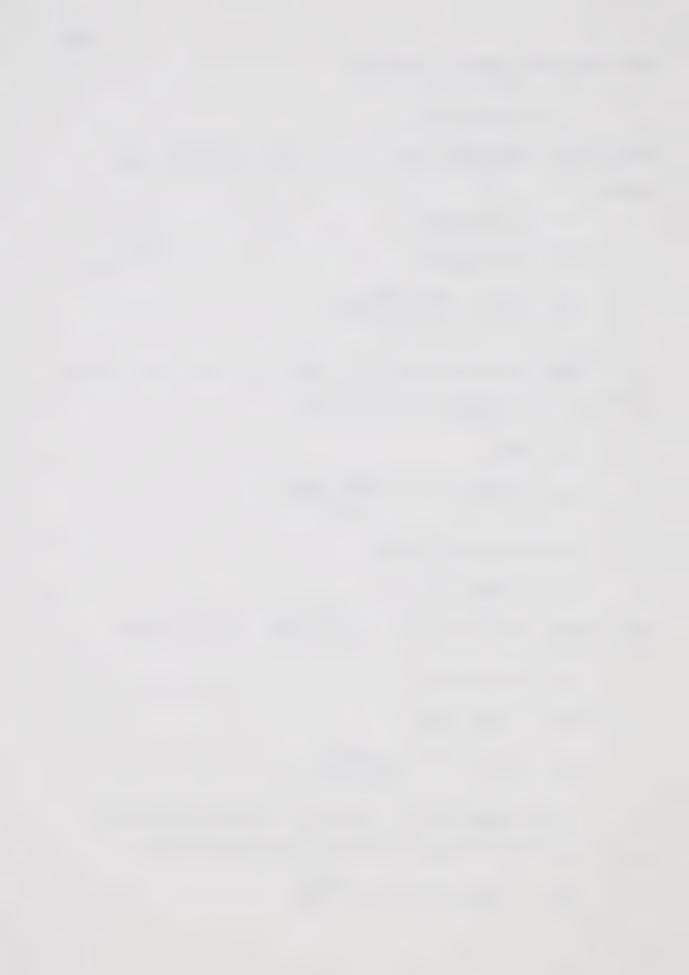
Under these conditions (4.1), (4.2) and (4.3) now yield

$$W = 113 \text{ lbf/in}^{2}$$

$$D = -1.945 \text{ lbf/in}$$

$$\Psi_{C} = 2.77 \times 10^{2} \frac{\text{lbm}}{\text{in - sec}}$$
(4.7)

(iii) Assuming $T_s = 50^\circ F$, $T_p = 100^\circ F$, Pe = 20.0 and $h_o = 2.34 \times 10^{-3}$ in, and using relationship (4.4) $Pe = 20.0 = 8.37 \times 10^3 \frac{Uh_o^2}{L}$



the value of U can be computed

$$U = 8.64 \times 10^2 \text{ in/sec}$$

 $T_r = 75$ °F, from which we find the respective absolute viscosity, namely,

$$\mu_{r} = 0.258 \times 10^{-4} \frac{1bf - sec}{in^{2}}$$

We can now compute the value of PE by using (4.5)

$$PE = 61.25 \frac{\mu_r U^2}{T_r} = 15.75$$

Under the above conditions, from the relationships (4.1), (4.2) and (4.3) we now obtain

$$W = 1,219 \text{ lbf/in}^{2}$$

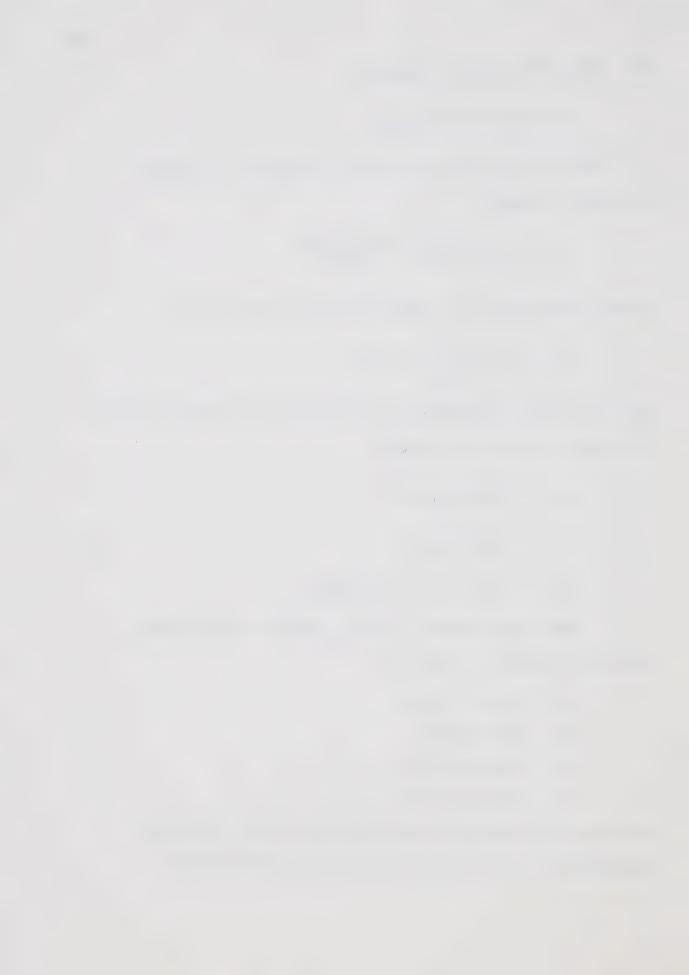
$$D = -9.42 \text{ lbf/in}$$

$$\Psi_{C} = 5.65 \times 10^{-2} \frac{\text{lbm}}{\text{in - sec}}$$
(4.8)

The above format has been used to obtain the following numerical results:

- (a) Slider cooled
- (b) Pad heated
- (c) Increasing PE
- (d) Increasing Pe

while the influence of the inertia terms on the load capacity of a slider bearing is also investigated.



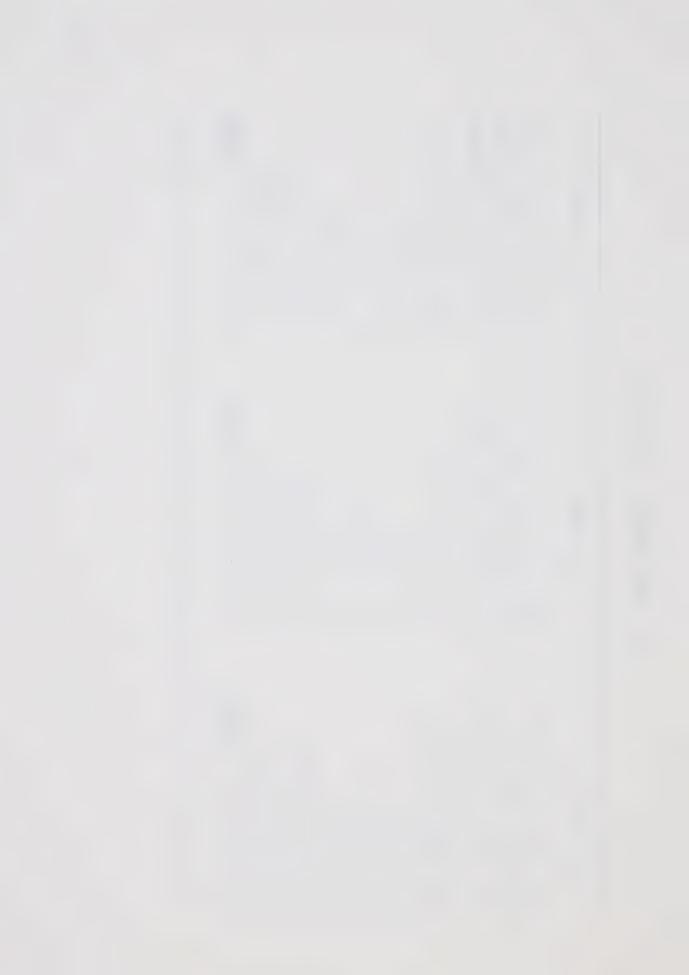
(a) Slider Cooled - $T_{\rm p} = 100^{\circ}{\rm F}$

T _S = 200°F	T _S = 50°F	T _S = 50°F
Pe = 20.0, $PE = 1.0$	Pe = 20.0, PE = 1.0	Pe = 20.0, PE = 15.75
$U = 8.643 \times 10^2 \text{ in/sec}$	$U = 2.177 \times 10^2 \text{ in/sec}$	$U = 8.643 \times 10^2 \text{ in/sec}$
$h_0 = 2.3537 \times 10^{-3} in$	$h_0 = 4.684 \times 10^{-3} in$	$h_0 = 2.3537 \times 10^{-3} in$
$\overline{W} = 0.10870$	$\overline{W} = 0.22013$	$\overline{W} = 0.15146$
$\bar{D} = -0.5782$	$\overline{D} = -0.81215$	$\vec{D} =49758$
$\overline{\Psi}_{\rm C} = 0.48381$	$\Psi_{\rm C} = 0.85908$	$\Psi_{\rm C} = 0.87790$
$W = 111.2 lbf/in^2$	$W = 113 lbf/in^2$	$W = 1,219 lbf/in^2$
D = -1.39 lbf/in	D = -1.945 lbf/in	D = -9.42 lbf/in
$\Psi_{\rm c} = 3.11 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm c} = 2.77 \times 10^{-2} \frac{1 \rm bm}{i n - sec}$	$\Psi_{c} = 5.65 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$



(b) Pad Heated - $T_s = 100$ °F

T = 50°F	T _p = 200°F	T _p = 200°F
Pe = 20.0 , PE = 1.0	Pe = 20.0, PE = 1.0	Pe = 20.0, PE = 0.06
$U = 2.178 \times 10^2 \text{ in/sec}$	$U = 8.643 \times 10^2 \text{ in/sec}$	$U = 2.178 \times 10^2 \text{ in/sec}$
$h_o = 4.685 \times 10^{-3} in$	$h_o = 2.3537 \times 10^{-3}$	$h_o = 4.685 \times 10^{-3} in$
$\bar{W} = 0.10995$	$\bar{W} = 0.23685$	$\overline{W} = 0.24782$
$\overline{D} = -0.58787$	$\overline{D} = -0.82949$	$\vec{D} = -0.87915$
$\Psi_{\rm c} = 0.4969$	$\overline{\Psi}_{\rm C} = 0.87827$	$\overline{\Psi}_{\rm C} = 0.87649$
$W = 56.50 \text{ lbf/in}^2$	$W = 242 lbf/in^2$	$W = 16.17 lbf/in^2$
D = -1.41 lbf/in	D = -1.995 lbf/in	D = -0.2675 lbf/in
$\Psi_{c} = 1.604 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{c} = 5.66 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm c} = 2.83 \times 10^{-2} \frac{1 \rm bm}{i n - sec}$



(c) Influence of PE - T_s = 110°F, T_p = 55°F

Pe = 20.0, PE = 1.27	Pe = 20.0, PE = 20.33	Pe = 80.0, PE = 20.33
$U_{r} = 2.9766 \times 10^{2} \text{ in/sec}$	$U_{\rm r}=1.19~{\rm x}~10^3~{\rm in/sec}$	$U_{\rm r} = 1.191 \times 10^3$
$h_o = 4.01 \times 10^{-3} \text{ in}$	$h_0 = 2.005 \times 10^{-3} in$	$h_o = 4.01 \times 10^{-3} in$
$\overline{W} = 0.10834$	W = 0.05622	$\bar{W} = 0.076768$
$\overline{D} = -1.644$	$\bar{D} = -0.3411$	$\overline{D} = -0.47113$
$\overline{\Psi}_{C} = 0.49419$	$\overline{\Psi}_{G} = 0.55075$	$\bar{\Psi}_{\rm C} = 0.52802$
$W = 77.7 lbf/in^2$	$W = 645 lbf/in^2$	$W = 220 lbf/in^2$
D = -1.644 lbf/in	D = -7.85 lbf/in	D = -5.39 lbf/in
$\Psi_{\rm c} = 1.89 \text{ x } 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm C} = 4.15 \times 10^{-2} \frac{1 \rm bm}{\rm in-sec}$	$\Psi_{\rm c} = 2.83 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$



(d) Influence of Pe - T_s = 150°F, T_p = 75°F

Pe = 1.0, PE = 6.1799	Pe = 2.50, PE = 6.1799	Pe = 2.5, PE = 38.6
$U_{\rm r} = 1.199 \times 10^3 \text{in/sec}$ $h_{\rm o} = 4.467 \times 10^{-4} \text{in}$	$U_{\rm r} = 1.199 \times 10^3 \text{in/sec}$ $h_{\rm o} = 7.065 \times 10^{-4} \text{in}$	$U_{\rm r} = 2.995 \times 10^3 {\rm in/sec}$ $h_{\rm o} = 4.467 \times 10^{-4} {\rm in}$
$\overline{W} = 0.065964$	$\overline{W} = 0.067969$	$\overline{W} = 0.030973$
$\overline{D} = -0.33806$	$\bar{D} = -0.35272$	$\bar{D} = -0.14462$
$\bar{\Psi}_{c} = 0.51777$	$\overline{\Psi}_{c} = 0.51907$	$\overline{\Psi}_{\rm C} = 0.57742$
$W = 6,262 lbf/in^2$	$W = 2580 \text{ lbf/in}^2$	$W = 7,340 \text{ lbf/in}^2$
D = -14.35 lbf/in	D = -9.47 lbf/in	D = -15.35 lbf/in
$\Psi_{c} = 0.877 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm C} = 1.39 \text{ x } 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm C} = 2.437 \times 10^2 \frac{1 \rm bm}{\text{in-sec}}$



$$-T_{s} = 200$$
°F, $T_{p} = 100$ °F, $Re^{*} = 0.5$

Inertia Terms Not Included	Inertia Terms Included
$\bar{W} = 0.12686$	$\bar{W} = 0.1333$
$\bar{D} = -0.6644$	$\bar{D} = -0.6876$
$\overline{\Psi}_{C} = 0.5389$	$\bar{\Psi}_{C} = 0.5261$
$W = 46.8 \text{ lbf/in}^2$	$W = 49.2 lbf/in^2$
D = -0.534 lbf/in	D = -0.553 lbf/in
$\Psi_{c} = 5.57 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$	$\Psi_{\rm c} = 5.43 \times 10^{-2} \frac{1 \text{bm}}{\text{in-sec}}$



SUMMARY OF CONCLUSIONS

The main conclusions of the analysis may now be listed as follows.

- (1) Decreasing the slider temperature to pad temperature ratio of a slider bearing causes an increase in both the dimensionless load capacity and the dimensionless drag, irrespective of whether the slider is cooled or the pad is heated. For the range $0.5 \le T_{\rm s}/T_{\rm p} \le 2.0$, the dimensionless values of the load capacity, drag, and mass flow depend strongly on the $T_{\rm s}/T_{\rm p}$ ratio, but weakly on the actual values of the temperature boundary conditions.
- (2) Although cooling the slider causes an increase in the load a bearing can carry, heating the pad for the case considered causes the bearing to be able to support less load. This difference is readily explained by using the following reasoning.

For a bearing operating at a fixed speed and having a constant film thickness, the load is proportional to the product of the dimensionless load capacity and the reference viscosity. When the slider is cooled, both the values of the dimensionless load capacity and the reference viscosity increase, thus causing an overall increase in the load which the bearing can carry. However, for the heated pad, although there is an increase in the dimensionless load capacity, the value of the reference viscosity decreases, which for the case under consideration causes a drop in the load which the bearing can support. For both cases, the rate of mass



flow through the bearing increases, while for the cooled slider alone there is an increase in the drag.

- (3) Neglecting the inertia terms in the momentum equation results in a smaller value being obtained for the load which the bearing can carry, and this error increases as Re * increases. The largest errors made in neglecting the inertia terms occur for the larger $T_{\rm s}/T_{\rm p}$ ratios. For $T_{\rm s}=200^{\circ}{\rm F},\ T_{\rm p}=100^{\circ}{\rm F},\ {\rm and}\ {\rm Re}^*=0.5,\ {\rm the\ value\ of\ the\ error}$ is approximately 5% of the value obtained when the inertia terms are included, and this error rises to approximately 10% of the true load for ${\rm Re}^*=1.0$.
- (4) When the inlet to outlet ratio, \bar{h}_r , of a plane slider bearing is increased, the load which the bearing can carry rises to a maximum then falls gradually. The observed maxima were in the range 2.00 $\leq \bar{h}_r \leq$ 2.25.
- (5) Increasing PE, brought about by varying the speed of the slider causes a drop in the dimensionless values of the load capacity and drag.

However, with our choice of reference temperature, and for the sample example presented, the load the bearing can carry increases about three times as PE goes from 1.27 to 20.33. This result can be explained by using the following reasoning. When a bearing operates at a varying speed and for a constant film thickness, the load it can carry is proportional to the product of the dimensionless load capacity and the slider velocity assuming that the reference viscosity remains constant. For the larger value of PE, although the



value of the dimensionless load capacity decreases, the higher velocity offsets this decrease thus resulting in a larger value for the load which the bearing is able to support. A similar argument can be used to explain the larger drag. The increased dissipation caused by higher velocities would give a lower reference viscosity than the one used in our calculations, so that the actual values of the load and drag would be smaller than those now evaluated.

(6) Increasing Pe at constant speed, brought about by an increase in the film thickness results in larger values for the dimensionless load capacity and drag. However, the actual load the bearing can carry decreases as Pe increases, and the drag behaves likewise. The reason for this drop in load capacity can be understood from the following argument. When a slider bearing operates at constant speed and for a varying film thickness ho, the load it can carry is proportional to the product of the dimensionless load capacity and $\frac{1}{h^2}$, assuming the reference viscosity remains constant. For the larger value of Pe, although the value of the dimensionless load capacity increases, $\frac{1}{h^2}$ decreases because of an increase in h . For the sample example presented this drop in $\frac{1}{h^2}$ offsets the rise in the dimensionless load capacity, resulting in a smaller value of load which the bearing can sustain. A similar reasoning can be used to explain the smaller value obtained for the drag. The reduced dissipation caused by the larger film



thickness would give a somewhat larger value for the reference viscosity, so that the actual magnitudes of the load and drag would be larger than those now obtained.

SUGGESTIONS FOR FUTURE RESEARCH

The present theoretical work has clearly shown that it is possible to considerably increase the load a slider bearing can carry by maintaining a low slider temperature to pad temperature ratio. It is suggested to design and build an apparatus to verify and find the range of applicability of the theory. The main feature of the design should be that a high viscosity layer next to the slider.

One of the assumptions made in Chapter II was that the effects of thermal and elastic distortions were to be neglected in the analysis. However, for extreme cases examined, the difference in the temperature boundary conditions were so large that this assumption may not be strictly correct. The net result of thermal distortion would be to cause changes in the clearance between the slider and the pad, which directly affects the lubricant film thickness, and thus would cause changes in the load capacity, drag, etc. It is proposed to find the conditions at which these effects can still be neglected.



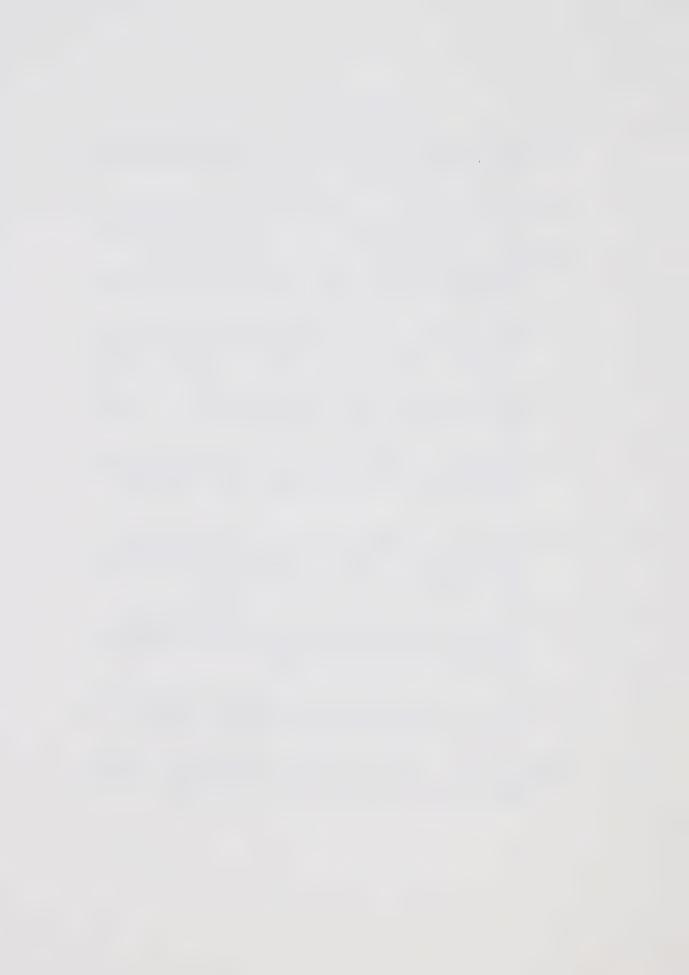


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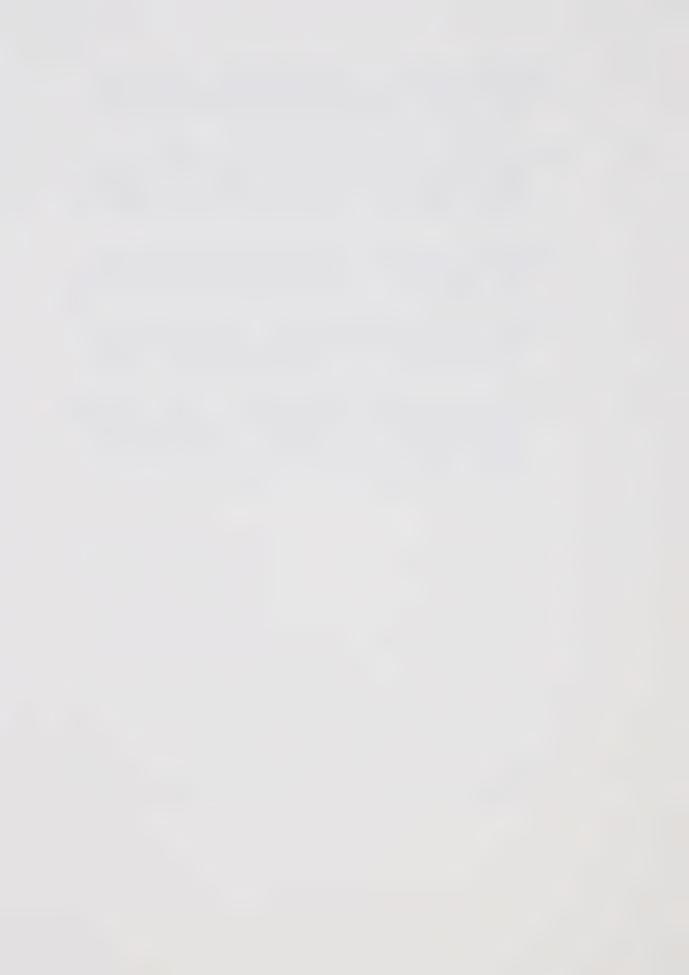
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APPENDIX A TRANSFORMATION OF THE REDUCED EQUATIONS

APPENDIX A

TRANSFORMATION OF THE REDUCED EQUATIONS

In order to simplify computations, the governing Equations (2.15) through (2.17) are transformed by use of the stream function.

Writing
$$\rho u = \frac{\partial \Psi}{\partial y}$$
, $\rho v = -\frac{\partial \Psi}{\partial x}$ and $\overline{\Psi} = \frac{\Psi}{\Psi_C}$; it is possible

for us to obtain expressions for $\bar{\mathbf{u}}$ and $\bar{\mathbf{v}}$ in terms of the stream function.

Now
$$\frac{\partial}{\partial x} = \frac{1}{L} \left[\frac{\partial}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \frac{\partial}{\partial \bar{y}} \right]$$

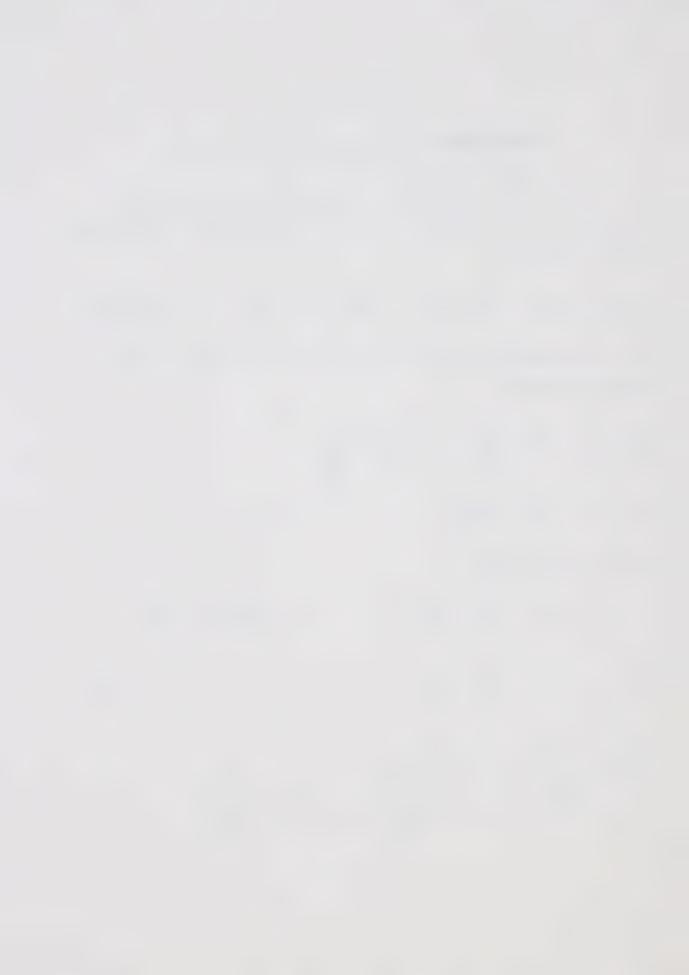
and
$$\frac{\partial}{\partial y} = \frac{1}{h_0} \frac{1}{h} \frac{\partial}{\partial y}$$

For the u component,

$$\rho \ U \, \overline{u} \ = \ \frac{\Psi_{C}}{h_{O}} \ \frac{\partial \overline{\Psi}}{\partial \overline{y}} \ \frac{1}{h} \quad \cdot \quad \overline{u} \ = \ \frac{\Psi_{C}}{\rho U h_{O}} \ \frac{1}{h} \ \frac{\partial \overline{\Psi}}{\partial \overline{y}}$$
ie.
$$\overline{u} \ = \ \frac{\overline{\Psi}_{C}}{h} \ \frac{\partial \overline{\Psi}}{\partial \overline{y}}$$

Similarly for the v component,

$$\rho \frac{\text{Uh}_{\text{O}}}{\text{L}} \quad \overline{\textbf{v}} \quad = \quad - \quad \frac{\Psi_{\text{C}}}{\text{L}} \quad \left(\frac{\partial \overline{\Psi}}{\partial \overline{\textbf{x}}} \quad + \quad \overline{\textbf{y}} \quad \frac{(\overline{\textbf{h}}_{\text{r-1}})}{\overline{\textbf{h}}} \quad \frac{\partial \overline{\Psi}}{\partial \overline{\textbf{y}}} \right)$$



$$\bar{v} = -\frac{\Psi_{c}}{\rho u h_{o}} \left(\frac{\partial \bar{\Psi}}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial \bar{y}} \right)$$

$$\bar{v} = -\bar{v}_{C} \left(\frac{\partial \bar{v}}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \frac{\partial \bar{v}}{\partial \bar{y}} \right)$$
 (A.2)

where $\overline{\Psi}_{C}$ is the dimensionless mass flow.

TRANSFORMATION OF THE MOMENTUM EQUATION

Substituting for \bar{u} and \bar{v} into Eq. (2.15) we obtain

$$\bar{h}^{2} \operatorname{Re}^{*} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \right) \frac{\partial \bar{\Psi}}{\partial \bar{y}} \frac{\partial}{\partial x} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial \bar{y}} \right) - \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \right) \frac{\partial \bar{\Psi}}{\partial \bar{x}} + \frac{(\bar{h}_{r-1})}{\bar{h}} \bar{y} \frac{\partial \bar{\Psi}}{\partial \bar{y}}$$

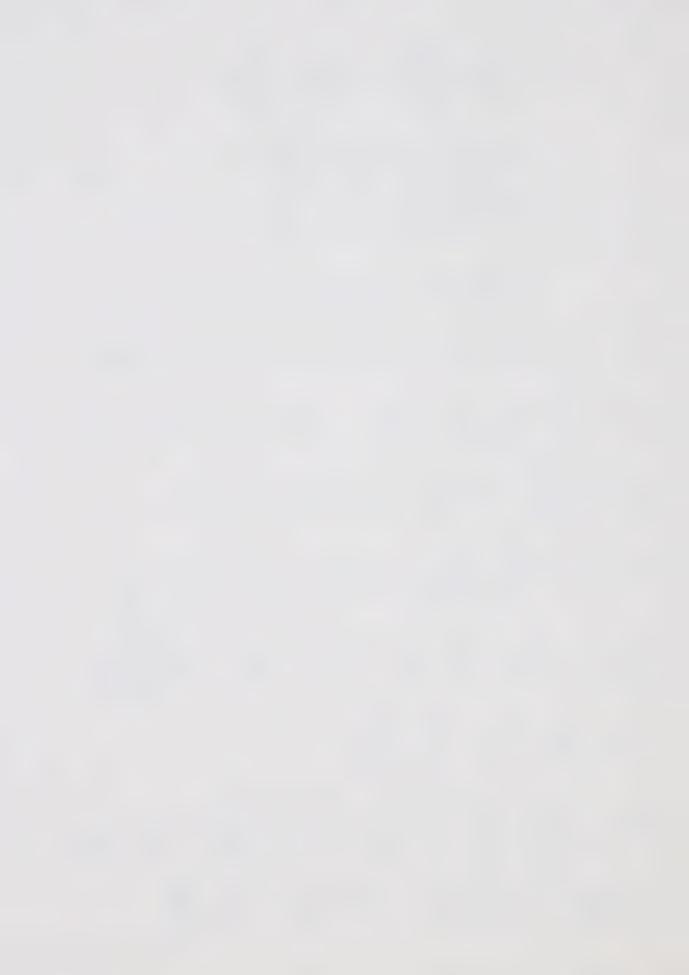
$$\frac{\partial}{\partial \bar{y}} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial \bar{y}} \right) = -\bar{h}^{2} \frac{\partial \bar{p}}{\partial x} + \frac{\partial}{\partial \bar{y}} \left[\bar{\mu} \frac{\partial}{\partial y} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) \right]$$

$$i.e. \quad \bar{h}^{2} \operatorname{Re}^{*} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) - \frac{\partial}{\partial x} \frac{\bar{\Psi}_{c}}{\partial y} \frac{\partial}{\partial x} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) + \frac{\partial}{\partial y} \bar{y} \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \frac{\partial}{\partial y} \right)$$

$$(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y}) - \frac{\partial \bar{\Psi}}{\partial x} \frac{\partial}{\partial y} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) - \frac{(\bar{h}_{r-1})}{\bar{h}} \bar{y} \frac{\partial}{\partial y} \frac{\partial}{\partial y} \frac{\partial}{\partial y} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) \right)$$

$$= - \bar{h}^{2} \frac{\partial \bar{p}}{\partial x} + \frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial}{\partial y} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial y} \right) - \frac{(\bar{h}_{r-1})}{\bar{h}} \bar{y} \frac{\partial}{\partial y} \frac{\partial}{\partial y} \frac{\partial}{\partial y} \left(\frac{\bar{\Psi}_{c}}{\bar{h}} \frac{\partial \bar{\Psi}_{c}}{\partial y} \right) \right)$$

$$\bar{h} \operatorname{Re}^{*} \bar{\Psi}_{C} = \begin{bmatrix} \frac{\partial \bar{\Psi}}{\partial \bar{y}} & \sqrt{\frac{\partial \bar{\Psi}}{\partial \bar{y}}} & \frac{\bar{\Psi}_{C}}{\bar{h}} & \frac{(\bar{h}_{r-1})}{\bar{h}} + \frac{\bar{\Psi}_{C}}{\bar{h}} & \frac{\partial}{\partial \bar{x}} & (\frac{\partial \bar{\Psi}}{\partial \bar{y}}) \end{pmatrix} + \frac{\bar{\Psi}_{C}}{\bar{h}} & \frac{(\bar{h}_{r-1})}{\bar{h}} \\ \bar{y} & \frac{\partial \bar{\Psi}}{\partial \bar{y}} & \frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} & -\frac{\bar{\Psi}_{C}}{\bar{h}} & \frac{\partial \bar{\Psi}}{\partial \bar{x}} & \frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} & -\frac{\bar{\Psi}_{C}}{\bar{h}} & \frac{(\bar{h}_{r-1})}{\bar{h}} & \bar{y} & \frac{\partial \bar{\Psi}}{\partial \bar{y}} & \frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} \end{bmatrix}$$



$$= -\bar{h}^2 \frac{\partial \bar{p}}{\partial \bar{x}} + \frac{\bar{\Psi}_C}{\bar{h}} \frac{\partial}{\partial \bar{y}} (\bar{\mu} \frac{\partial^2 \bar{\Psi}}{\partial \bar{y}^2})$$

i.e.
$$\bar{h} \operatorname{Re}^* \bar{\Psi}_{C} = \begin{pmatrix} (\frac{\partial \bar{\Psi}}{\partial \bar{y}})^2 & \frac{(\bar{h}_{r-1})}{\bar{h}} & + \frac{\partial \bar{\Psi}}{\partial \bar{y}} & \frac{\partial}{\partial \bar{x}} & (\frac{\partial \bar{\Psi}}{\partial \bar{y}}) & - & \frac{\partial \bar{\Psi}}{\partial \bar{x}} & \frac{\partial^2 \bar{\Psi}}{\partial \bar{y}^2} \end{pmatrix}$$

$$= -\frac{\bar{h}^3}{\bar{\Psi}_{C}} \frac{\partial \bar{p}}{\partial \bar{x}} & + & \frac{\partial}{\partial \bar{y}} & (\bar{\mu} & \frac{\partial^2 \bar{\Psi}}{\partial \bar{y}^2}) \qquad (A.3)$$

TRANSFORMATION OF THE ENERGY EQUATION

Likewise for the Energy Eq. (2.16) we get

$$\bar{h}^{2} P Re^{*} \left(\frac{\bar{\Psi}_{C}}{\bar{h}} \frac{\partial \bar{\Psi}}{\partial \bar{y}} \right) \left(\frac{\partial \bar{T}}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \frac{\partial \bar{T}}{\partial \bar{y}} \right) - \frac{\bar{\Psi}_{C}}{\bar{h}} \left(\frac{\partial \bar{\Psi}}{\partial \bar{x}} + \bar{y} \frac{(\bar{h}_{r-1})}{\bar{h}} \right)$$

$$\frac{\partial \bar{\Psi}}{\partial \bar{y}} \left(\frac{\partial \bar{\Psi}}{\partial \bar{y}} \right) = \frac{\partial^{2} \bar{T}}{\partial \bar{y}^{2}} + PE \left(\frac{\bar{\Psi}_{C}}{\bar{h}} \right)^{2} \bar{\mu} \left(\frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} \right)^{2}$$

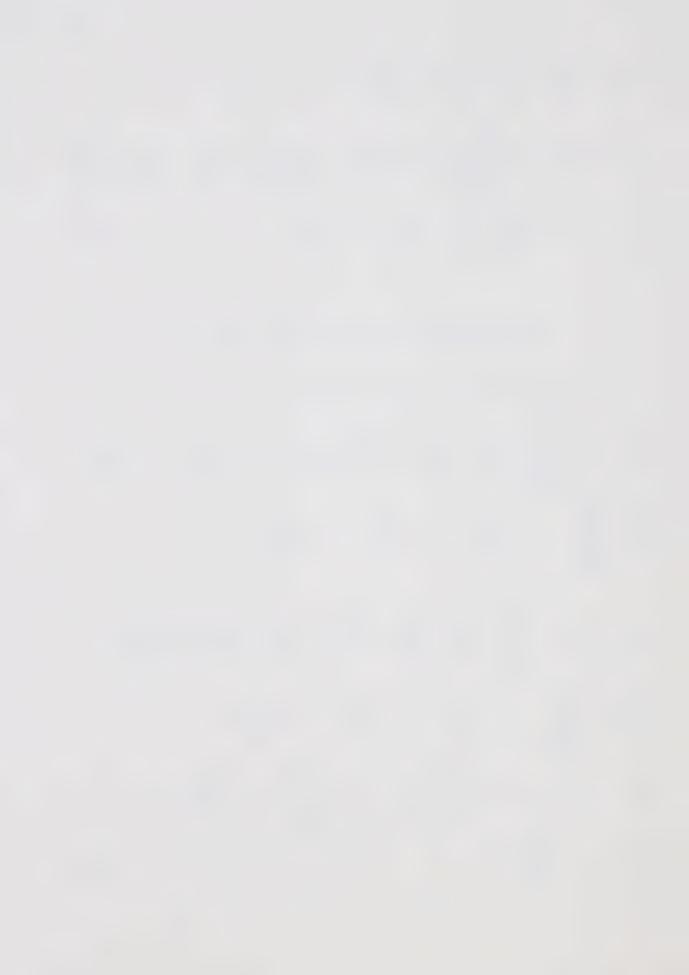
$$\bar{h} \bar{\Psi} P P Pe^{*} \left(\frac{\partial \bar{\Psi}}{\partial \bar{y}} \right) = \frac{\partial \bar{\Psi}}{\partial \bar{y}^{2}} + \frac{\partial \bar{\Psi}}{\partial \bar{y}^{2}} + \frac{\partial \bar{\Psi}}{\bar{y}^{2}} + \frac{\partial \bar{\Psi}}{\bar{$$

$$\overline{h} \ \overline{\Psi}_{C} \ P. \ Re^{*} \qquad \frac{\partial \overline{\Psi}}{\partial \overline{y}} \ \frac{\partial \overline{T}}{\partial \overline{x}} + \frac{\partial \overline{\Psi}}{\partial \overline{y}} \ \overline{y} \ \frac{(\overline{h}_{r-1})}{\overline{h}} \ \frac{\partial \overline{T}}{\partial \overline{y}} - \frac{\partial \overline{\Psi}}{\partial \overline{x}} \ \frac{\partial \overline{T}}{\partial \overline{y}} - \frac{\partial \overline{\Psi}}{\partial \overline{y}} \ \overline{y}$$

$$\frac{(\overline{h}_{r-1})}{\overline{h}} \quad \frac{\partial \overline{T}}{\partial \overline{y}} = \frac{\partial^2 \overline{T}}{\partial \overline{y}^2} + PE \left(\frac{\overline{\Psi}_{c}}{\overline{h}}\right)^2 \quad \overline{\mu} \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right)^2$$

i.e.
$$\overline{h} \overline{\Psi}_{C}$$
 P. Re* $\left[\frac{\partial \overline{\Psi}}{\partial \overline{y}} \frac{\partial \overline{T}}{\partial \overline{x}} - \frac{\partial \overline{\Psi}}{\partial \overline{x}} \frac{\partial \overline{T}}{\partial \overline{y}} \right] = \frac{\partial^{2} \overline{T}}{\partial \overline{y}^{2}} + PE$

$$(\frac{\overline{\Psi}_{C}}{\overline{h}})^{2} = \frac{\overline{\mu}}{\mu} \left(\frac{\partial^{2}\overline{\Psi}}{\partial \overline{y}^{2}}\right)^{2}$$
 (A.4)



APPENDIX B ENERGY EQUATION IN FINITE DIFFERENCE FORM



APPENDIX B

ENERGY EQUATION IN FINITE DIFFERENCE FORM

The energy Equation (2.25) is rewritten in finite difference form, by replacing the derivatives of the temperature by their central finite difference approximations. Let $\Delta \ \bar{\mathbf{x}}$ and $\Delta \bar{\mathbf{y}}$ represent the grid spacing in the $\bar{\mathbf{x}}$ and $\bar{\mathbf{y}}$ directions as shown in Fig. 3.

Considering the point i+1/2, j, the energy equation can be rewritten as follows:

$$\overline{h}_{i+1/2} \quad \overline{\Psi}_{c} \quad P \quad Re^{*} \quad \left[-\frac{\partial \overline{\Psi}}{\partial \overline{y}} \right]_{i+1/2,j} \quad \left(\frac{\partial \overline{T}}{\partial \overline{x}}\right)_{j} -\frac{\partial \overline{\Psi}}{\partial \overline{x}} \right]_{i+1/2,j} \quad \left(\frac{\partial \overline{T}}{\partial \overline{y}}\right)_{j+1/2,j} \\
= \left(\frac{\partial^{2}\overline{T}}{\partial \overline{y}^{2}}\right)_{i+1/2,j} + \left(\frac{\overline{\Psi}_{c}}{\overline{h}_{i+1/2}}\right)^{2} \quad P \cdot E \quad \overline{\mu}_{i+1/2,j} \quad \left(\frac{\partial^{2}\overline{\Psi}}{\partial \overline{y}^{2}}\right)_{j+1/2,j} \quad \left(\frac{\partial^{2}\overline{\Psi}}{\partial \overline{y}^{2}}\right)_{j+1/2,j} \\
(B.1)$$

Where,

$$\bar{h}_{i+1/2} = (\bar{h}_i + \bar{h}_{i+1})/2.0$$
 (B.2)

$$(\frac{\partial \overline{\Psi}}{\partial y})_{i+1/2,j} = \frac{1}{2} \left((\frac{\partial \overline{\Psi}}{\partial y})_{i,j} + (\frac{\partial \overline{\Psi}}{\partial y})_{i+1,j} \right)$$
(B.3)

$$(\frac{\partial \overline{\Psi}}{\partial \overline{x}}) = \frac{1}{2} \left(\frac{\partial \overline{\Psi}}{\partial \overline{x}}) + (\frac{\partial \overline{\Psi}}{\partial \overline{x}}) \right)$$
(B.4)



$$\bar{\mu}_{i+1/2,j} = \frac{1}{2} \left(\bar{\mu}_{i,j} + \bar{\mu}_{i+1,j} \right)$$
 (B.5)

$$\begin{bmatrix}
(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}} \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

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\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
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\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
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\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

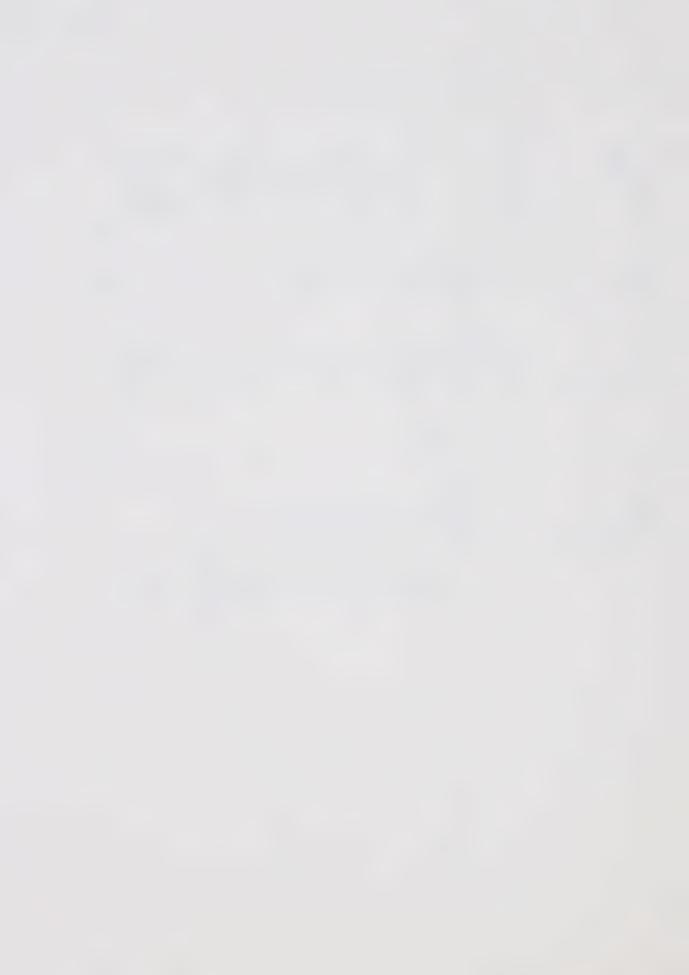
$$= \begin{bmatrix}
\frac{1}{2} & \left(\frac{\partial^2 \overline{\Psi}}{\partial \overline{y}^2}\right) \\
\underline{\partial^2 \overline{\Psi}}
\end{bmatrix}$$

$$(\frac{\partial \overline{T}}{\partial \overline{x}})_{i+1/2,j} = \frac{\overline{T}_{i+1,j} - \overline{T}_{i,j}}{\Delta \overline{x}} + O[\Delta \overline{x}^2]$$
(B.7)

$$(\frac{\partial \bar{T}}{\partial \bar{y}})_{i+1/2,j} = \frac{1}{2} \left[\frac{\bar{T}_{i,j+1} - \bar{T}_{i,j-1}}{2\Delta \bar{y}} + \frac{\bar{T}_{i+1,j+1} - \bar{T}_{i+1,j-1}}{2\Delta \bar{y}} \right] + 0 \left[\Delta_{v}^{-2} \right]$$
(B.8)

$$\frac{(\frac{\partial^{2}\overline{T}}{\partial y^{2}})}{\partial y^{2}}_{i+1/2,j} = \frac{1}{2} \left(\frac{\overline{T}_{i,j+1}^{-2}\overline{T}_{i,j}^{+}\overline{T}_{i,j-1}}{\Delta y^{2}} + \frac{\overline{T}_{i+1,j+1}^{-2}\overline{T}_{i+1,j}^{+}\overline{T}_{i+1,j-1}}{\Delta y^{2}} + o[\Delta y^{2}] \right)$$

(B.9)



For i = 1,

$$(\frac{\partial \overline{\Psi}}{\partial \overline{x}})_{i,j} = \begin{bmatrix} 4 \overline{\Psi}_{i+1,j} & -3\overline{\Psi}_{i,j} & -\overline{\Psi}_{i+2,j} \end{bmatrix} / 2\Delta \overline{x} + 0[\Delta \overline{x}^2]$$

For i = M

$$(\frac{\partial \overline{\Psi}}{\partial \overline{x}})_{i,j} = \left(\overline{\Psi}_{i-2,j} + 3\overline{\Psi}_{i,j} - 4\overline{\Psi}_{i-1,j}\right) / 2.\Delta \overline{x} + 0[\Delta \overline{x}^{2}] \quad (B.10)$$

For 1 < i < M

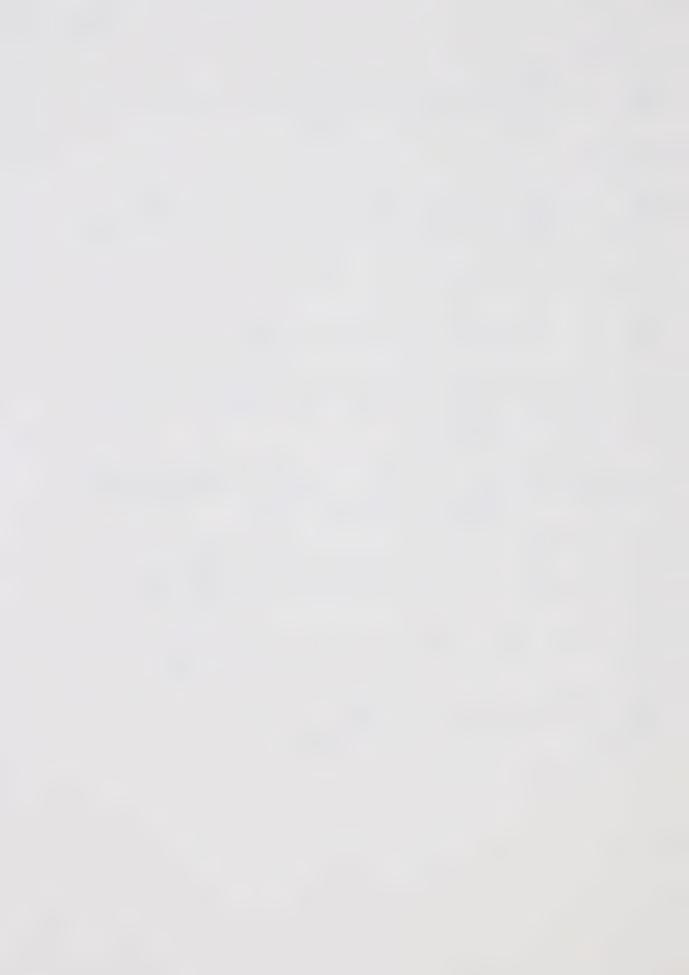
$$(\frac{\partial \overline{\Psi}}{\partial \overline{x}})_{i,j} = (\overline{\Psi}_{i+1,j} - \overline{\Psi}_{i-1,j}) / 2\Delta \overline{x} + O[\Delta \overline{x}^2]$$

Now substituting Equations (A.2) through (A.9) into Equation (A.1) we obtain,

$$\frac{\bar{h}_{i+1/2} \bar{\Psi}_{c} P \cdot Re^{*}}{\Delta \bar{x}} \left(\frac{\partial \bar{\Psi}}{\partial \bar{y}_{i+1/2,j}}\right) \left(\bar{T}_{i+1,j} - \bar{T}_{i,j}\right) - \frac{\bar{h}_{i+1/2,j} \bar{\Psi}_{c} PRe^{*}}{4\Delta \bar{y}}$$

$$\left(\frac{\partial \bar{\Psi}}{\partial \bar{x}}\right)_{i+1/2,j} \left(\bar{T}_{i,j+1} - \bar{T}_{i,j-1} + \bar{T}_{i+1,j+1} - \bar{T}_{i+1,j-1}\right) = \frac{1}{2\Delta \bar{y}^{2}}$$

$$\left(\bar{T}_{i,j+1} - 2\bar{T}_{i,j} + \bar{T}_{i,j-1} + \bar{T}_{i+1,j+1} - 2\bar{T}_{i+1,j} + \bar{T}_{i+1,j-1}\right) + \left(\bar{\Psi}_{c} - \bar{T}_{c} - \bar{T}$$



After rearranging the terms, the previous equation becomes

$$\begin{split} \bar{T}_{i+1,j-1} & \left[\frac{\bar{h}_{i+1/2, \overline{\Psi}_{C}}}{4\Delta \bar{y}} + \frac{\partial \bar{\Psi}}{\partial z} \right] + \bar{T}_{i+1,j} \\ & \left[\frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{\Delta \bar{x}} + \frac{\partial \bar{\Psi}}{\partial \bar{y}} \right] + \frac{1}{P \cdot Re^* \Delta \bar{y}^2} - \bar{T}_{i+1,j+1} + \frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{4\Delta \bar{y}} \\ & \left(\frac{\partial \bar{\Psi}}{\partial \bar{x}} \right)_{i+1/2,j} + \frac{1}{2PRe^* \Delta \bar{y}^2} = \bar{T}_{i,j-1} + \frac{1}{2PRe^* \Delta \bar{y}^2} - \frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{4\Delta \bar{y}} \\ & \left(\frac{\partial \bar{\Psi}}{\partial \bar{x}} \right)_{i+1/2,j} + \bar{T}_{i,j} + \frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{\Delta \bar{x}} + \frac{\partial \bar{\Psi}}{\partial \bar{y}} + \frac{1}{2PRe^* \Delta \bar{y}^2} - \frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{4\Delta \bar{y}} + \frac{1}{2PRe^* \Delta \bar{y}^2} \\ & + \bar{T}_{i,j+1} + \frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{4\Delta \bar{y}} + \frac{\partial \bar{\Psi}}{\partial \bar{x}} + \frac{\partial \bar{\Psi}}{\partial \bar{x}} + \frac{\partial \bar{\Psi}}{\partial z} + \frac{\partial \bar{\Psi}}$$

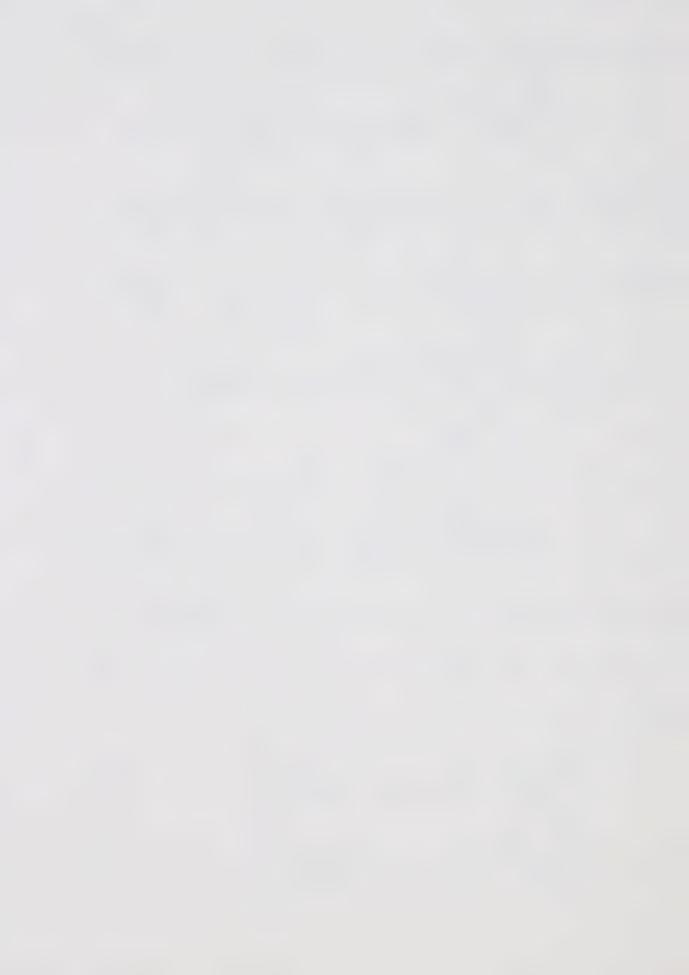
The above equation can finally be rewritten as follows

$$a_{i,j} = \bar{T}_{i+1,j-1} + b_{i,j} = \bar{T}_{i+1,j} + C_{i,j} = \bar{T}_{i+1,j+1} = d_{i,j}$$
 (B.11)

where

$$\mathbf{a}_{i,j} = \begin{bmatrix} \frac{\overline{h}_{i+1/2}\overline{\Psi}_{C}}{\overline{h}_{i+1/2}} & (\frac{\partial\overline{\Psi}}{\partial\overline{x}}) & -\frac{1}{2PRe^{*}\Delta\overline{y}^{2}} \\ \frac{1}{2PRe^{*}\Delta\overline{y}^{2}} & \frac{1}{2PRe^{*}\Delta\overline{y}^{2}} \end{bmatrix}$$
 (B.12)

$$b_{i,j} = \begin{pmatrix} \frac{\bar{h}_{i+1/2} \bar{\Psi}_{c}}{\Delta \bar{x}} & (\frac{\partial \bar{\Psi}}{\partial \bar{y}}) & + \frac{1}{PRe^* \Delta \bar{y}^2} \end{pmatrix}$$
(B.13)



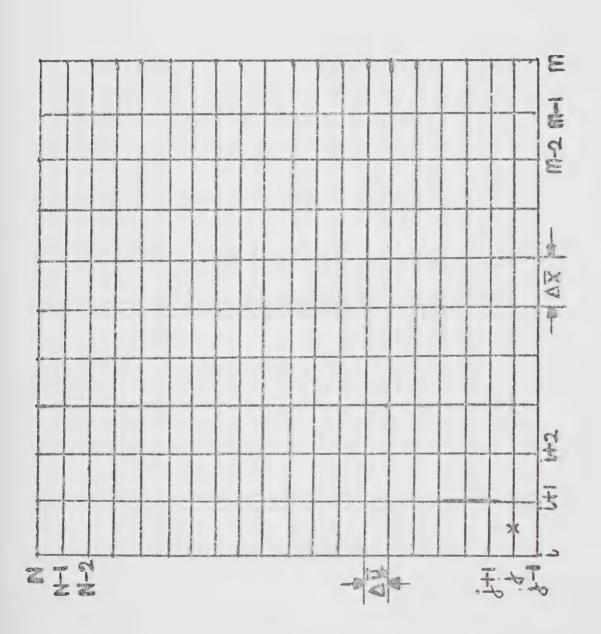
$$c_{i,j} = - \left[\frac{\bar{h}_{i+1/2} \bar{\Psi}_{C}}{4 \Delta \bar{y}} \left(\frac{\partial \bar{\Psi}}{\partial \bar{x}} \right)_{i+1/2,j} + \frac{1}{2P \cdot Re^* \Delta \bar{y}^2} \right]$$
 (B.14)

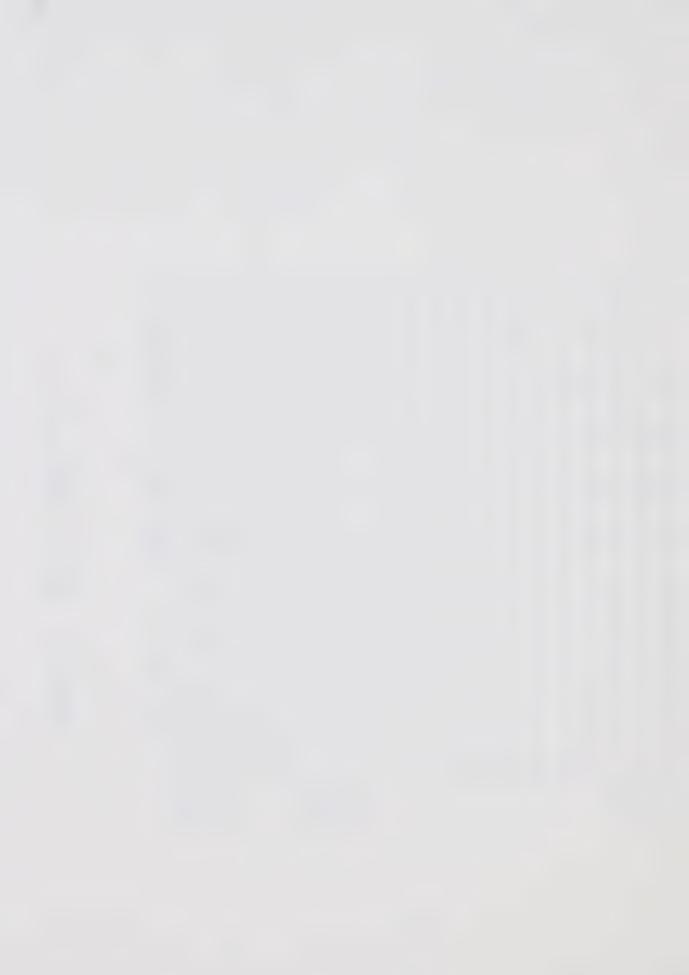
$$d_{i,j} = -a_{i,j} \bar{T}_{i,j-1} + \left(b_{i,j} - \frac{2}{P \cdot Re^* \Delta y^2}\right) \bar{T}_{i,j} - c_{i,j}$$

$$\bar{T}_{i,j+1} + \frac{E}{Re^*} (\frac{\bar{\mu}_{i,j}^{+\bar{\mu}_{i+1,j}}}{8}) \left(\frac{\partial^2 \bar{\psi}}{\partial \bar{y}^2})_{i+1/2,j} + \frac{\bar{\psi}_c}{\bar{h}_{i+1/2}}\right)^2$$

(B.15)







APPENDIX C EQUATIONS FOR BEARING CHARACTERSTICS



APPENDIX C

BEARING CHARACTERISTICS

By substituting dimensionless variables for the dimensional ones, it is possible to obtain dimensionless equations for all the characteristics of the bearing operation.

Dimensionless Mass Flow

$$\Psi_{c} = \int_{0}^{h} \rho u \, dy \qquad (C.1)$$

After substituting dimensionless variables in the above equation we obtain

$$\Psi_{C} = (\rho U h_{O}) \bar{h} \int_{O}^{1} \bar{u} d\bar{y}$$

$$\frac{\Psi_{C}}{(\rho U h_{C})} = \bar{h} \int_{0}^{1} \bar{u} d\bar{y}$$

$$\overline{\Psi}_{C} = \overline{h} \int_{0}^{1} \overline{u} d\overline{y}$$
 (C.2)

Dimensionless Load Capacity

$$W = \int_{0}^{L} p \, dx \qquad (C.3)$$

Again nondimensionalizing we have,

$$W = \frac{\rho U^2 L}{Re^* L} \int_0^1 \bar{p} d\bar{x}$$

$$W = \frac{\mu_r UL}{h_o^2} \int_0^1 \bar{p} d\bar{x}$$



$$\frac{Wh_o^2}{\mu_r^{UL}} = \int_0^1 \vec{p} d\vec{x}$$

i.e.
$$\overline{W} = \int_0^1 \overline{p} d\overline{x}$$
 (C.4)

Dimensionless Shear Stress at Slider

$$\tau_{o} = \mu \left(\frac{\partial u}{\partial y}\right)_{y=0} \tag{C.5}$$

$$ie. \qquad \tau_{o} = \frac{U^{\mu} r}{h_{o}} \frac{\overline{\Psi}_{c}}{\overline{h}^{2}} \left[\overline{\mu} \left(\frac{\partial^{2} \overline{\Psi}}{\partial \overline{y}^{2}}\right) \right] \overline{y}=0$$

$$\frac{\tau_{o} h_{o}}{\mu_{r} U} = \frac{\overline{\Psi}_{c}}{\overline{h}^{2}} \left[\overline{\mu} \left(\frac{\partial^{2} \overline{\Psi}}{\partial \overline{y}^{2}}\right) \right] \overline{y}=0$$

$$\bar{\tau}_{O} = \frac{\bar{\Psi}_{C}}{\bar{h}^{2}} \left(\bar{\mu} \frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} \right) = 0$$
 (C.6)

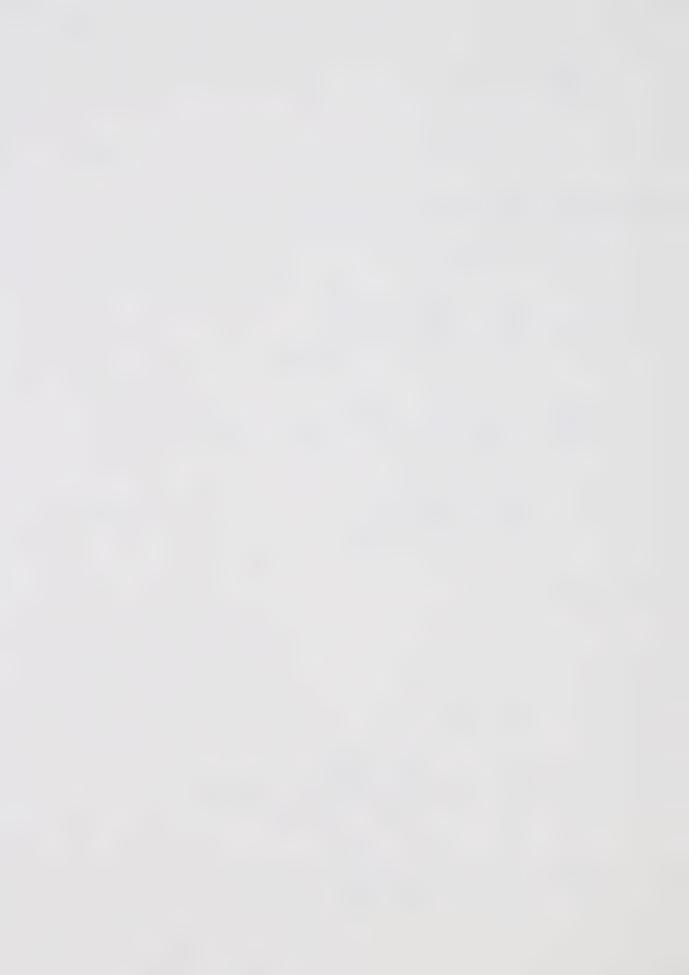
Dimensionless Drag

$$D = \int_{0}^{L} \tau_{y=0} dx \qquad (C.7)$$

$$D = \int_{0}^{L} (\mu \frac{\partial u}{\partial y})_{y=0} dx$$

$$D = \frac{\mu_{r}UL}{h_{o}} \overline{\Psi}_{c} \int_{0}^{1} (\frac{\partial^{2}\overline{\Psi}}{\partial y^{2}}) \frac{1}{\overline{h}^{2}} d\overline{x}$$

$$\frac{D^{h_{o}}}{\mu_{r}UL} = \overline{\Psi}_{c} \int_{0}^{1} (\overline{\mu} \frac{\partial^{2}\overline{\Psi}}{\partial y^{2}}) \frac{1}{\overline{h}^{2}} d\overline{x}$$



$$\bar{D} = \bar{\Psi}_{C} \int_{0}^{1} \left[\bar{\mu} \frac{\partial^{2} \bar{\Psi}}{\partial \bar{y}^{2}} \right]_{\bar{y}=0} \frac{1}{\bar{h}^{2}} d\bar{x}$$
 (C.8)

Dimensionless Heat Convected into Bearing

$$Q_{\underline{i}} = \int_{0}^{h} \rho C_{\underline{p}} \mu_{\underline{i}} T_{\underline{i}} dy \qquad (C.9)$$

$$Q_{\underline{i}} = \rho C_{\underline{p}} T_{\underline{r}} U h_{\underline{0}} \overline{\Psi}_{\underline{C}} \frac{\overline{h}}{\overline{h}} \int_{0}^{1} (\overline{T} \frac{\partial \overline{\Psi}}{\partial \overline{y}}) d\overline{y}$$

ie.
$$\frac{Q_{i}}{(\rho C_{p} T_{r} U h_{o})} = \overline{\Psi}_{c} \int_{0}^{1} (\overline{T} \frac{\partial \overline{\Psi}}{\partial \overline{Y}}) d\overline{y}$$

$$\bar{Q}_{i} = \bar{\Psi}_{C} \int_{0}^{1} (\bar{T} \frac{\partial \bar{\Psi}}{\partial \bar{y}}) d\bar{y}$$
 (C.10)

Dimensionless Heat Convected out of Bearing

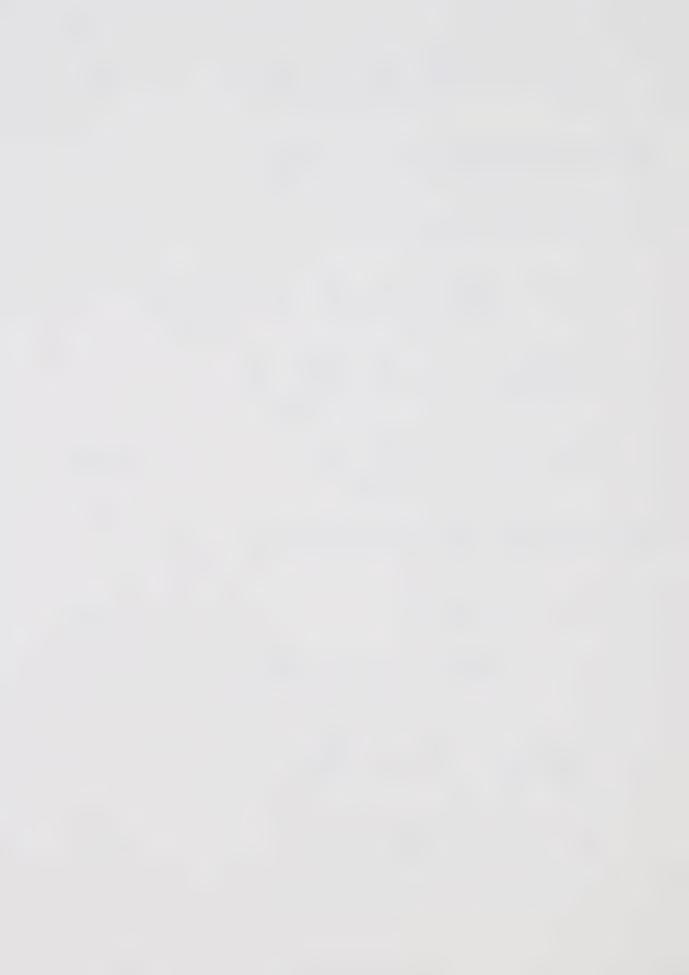
$$Q_{e} = \int_{0}^{h} \rho C_{p} u_{e} T_{e} dy$$

$$Q_{e} = (\rho C_{p} T_{r} U h_{o}) \overline{\Psi}_{c} \frac{\overline{M}}{\overline{M}} \int_{0}^{1} (\overline{T} \frac{\partial \overline{\Psi}}{\partial \overline{Y}}) d\overline{Y}$$

$$Q_{e} = (\rho C_{p} T_{r} U h_{o}) \overline{\Psi}_{c} \frac{\overline{M}}{\overline{M}} \int_{0}^{1} (\overline{T} \frac{\partial \overline{\Psi}}{\partial \overline{Y}}) d\overline{Y}$$

$$\frac{Q_{\rm e}}{[\rho C_{\rm p} T_{\rm r} U h_{\rm o}]} \ = \ \overline{\Psi}_{\rm c} \ \int_{\rm o}^{1} \ (\overline{T} \ \frac{\partial \overline{\Psi}}{\partial \overline{y}}) \ \overline{x} = 1$$

$$\bar{Q}_{e} = \bar{\Psi}_{C} \int_{0}^{1} (\bar{T} \frac{\partial \bar{\Psi}}{\partial \bar{y}}) d\bar{y}$$
 (C.12)



Dimensionless Heat Flux Across Pad

$$q_{p} = - [K \frac{dT}{dy}]$$

$$y=h$$
(C.13)

$$= - \frac{KT_r}{h_o} \frac{1}{\bar{h}} (\frac{d\bar{T}}{d\bar{y}})_{\bar{y}=1}$$

$$\frac{q_p^h \circ}{KT_r} = - \frac{1}{\bar{h}} (\frac{d\bar{T}}{d\bar{y}})$$

$$\bar{q}_{p} = -\frac{1}{\bar{h}} \left(\frac{d\bar{T}}{d\bar{y}}\right). \tag{C.14}$$

Dimensionless Heat Flux Across Slider

$$q_{s} = -K \left(\frac{dT}{d\bar{y}}\right)_{y=0}$$

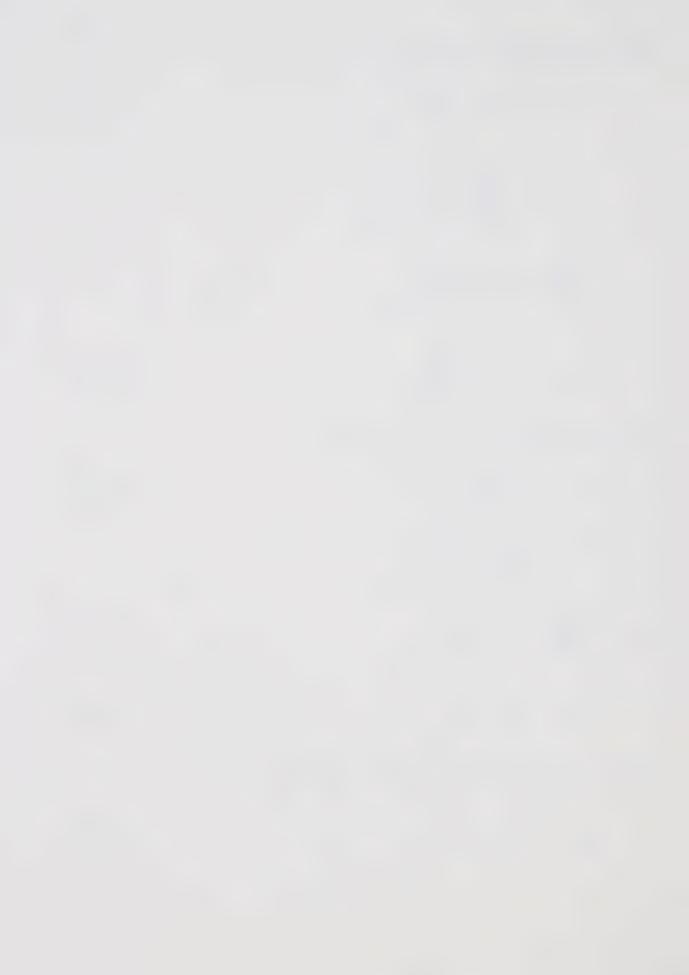
$$= \frac{KT_{r}}{h_{o}} \frac{1}{\bar{h}} \left(\frac{d\bar{T}}{d\bar{y}}\right)_{\bar{y}=0}$$
(C.15)

i.e.
$$\frac{q_s h_o}{KT_r} = \frac{1}{\bar{h}} \cdot (\frac{d\bar{T}}{d\bar{y}})_{\bar{y}=0}$$

$$\bar{q}_{S} = \frac{1}{\bar{h}} \left(\frac{d\bar{T}}{d\bar{y}} \right) \tag{C.16}$$

Dimensionless Heat Conducted Through Pad

$$Q_{p} = \int_{0}^{L} q_{p} dx \qquad (C.17)$$



$$= \frac{LKT_r}{h_o} \int_0^1 \bar{q}_p d\bar{x}$$

$$\frac{Q_{p} h_{o}}{LKT_{r}} = \int_{o}^{1} \overline{q}_{p} d\overline{x}$$

$$\bar{Q}_{p} = \int_{0}^{1} \bar{q}_{p} d\bar{x} \qquad (C.18)$$

Dimensionless Heat Conducted Through Slider

$$Q_{s} = \int_{0}^{L} q_{s} dx \qquad (C.19)$$

$$= \frac{LKT_{r}}{h_{o}} \int_{0}^{1} \bar{q}_{s} d\bar{x}$$

$$\frac{Q_s h_o}{LKT_r} = \int_0^1 \bar{q}_s d\bar{x}$$

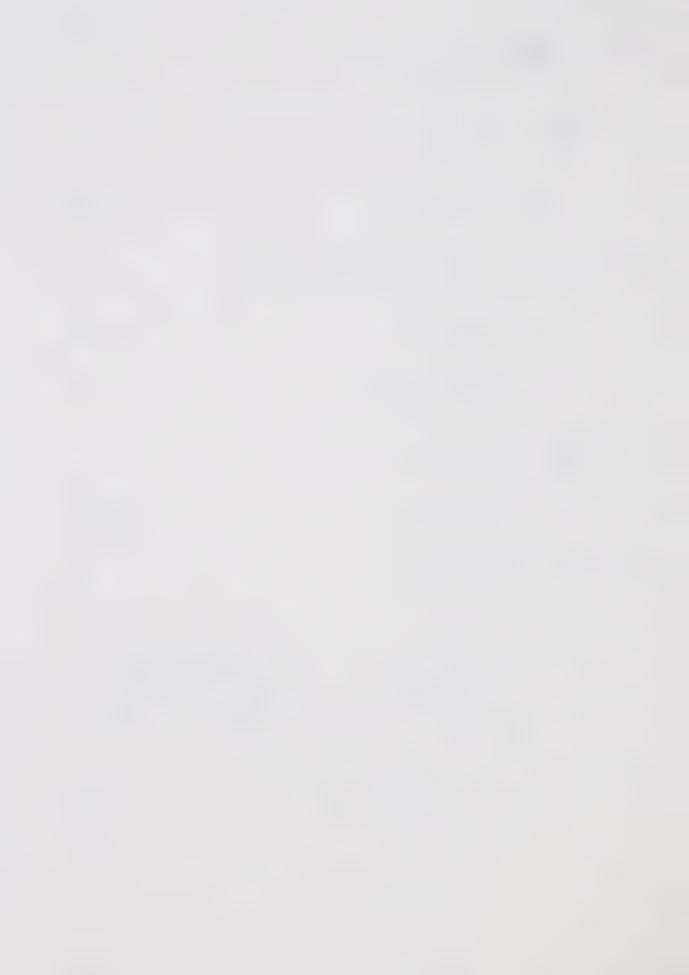
$$\bar{Q}_s = \int_0^1 \bar{q}_s d\bar{x}$$
(C.20)

Average Flow Temperature

$$T_{b} = \int_{0}^{L} \frac{\int_{0}^{h} u \rho \ T \ dy}{\int_{0}^{h} \rho u \ dy} \ dx = \int_{0}^{1} \frac{\rho U T_{r} h_{o} \ \bar{h} \int_{0}^{1} \bar{u} \bar{d} \bar{y}}{\rho U h_{o} \ \bar{h} \int_{0}^{1} \bar{u} d \bar{y}} \ d\bar{x}$$

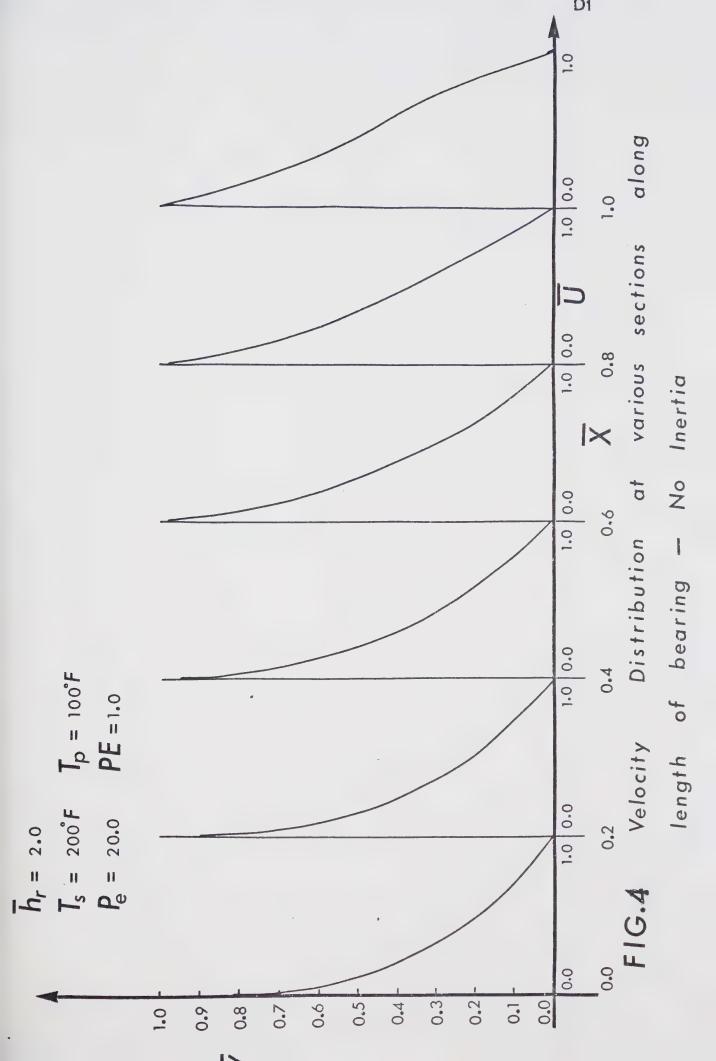
$$\int_{0}^{L} dx = \int_{0}^{L} d\bar{x}$$

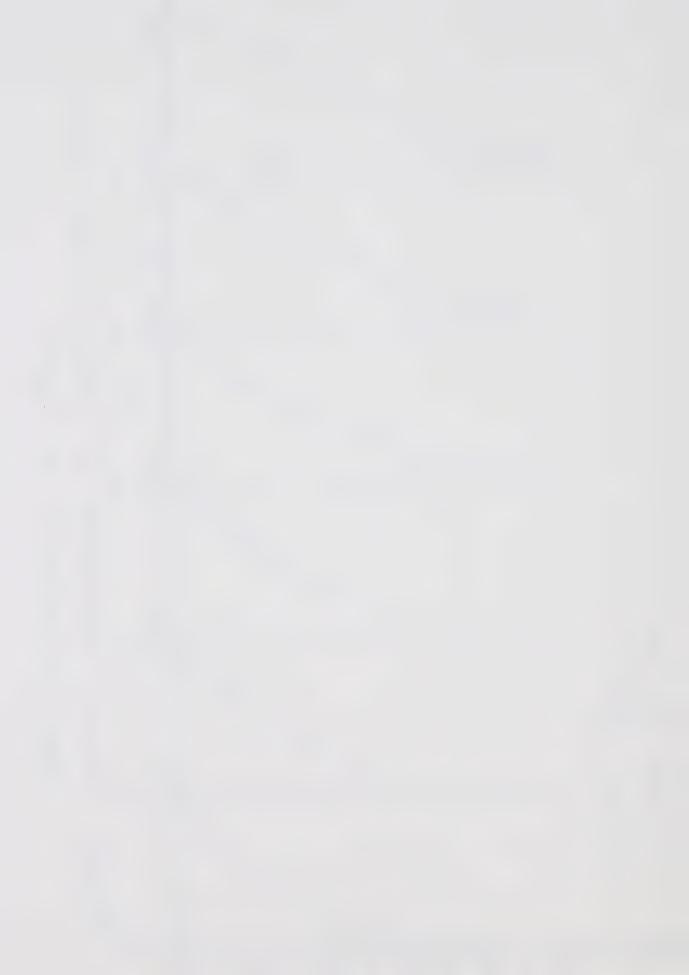
$$T_{b} = T_{r} \int_{0}^{1} \frac{\int_{0}^{1} \overline{u} \overline{d} \overline{y}}{\int_{0}^{1} \overline{u} \overline{d} \overline{y}} d\overline{x}$$
 (C.21)

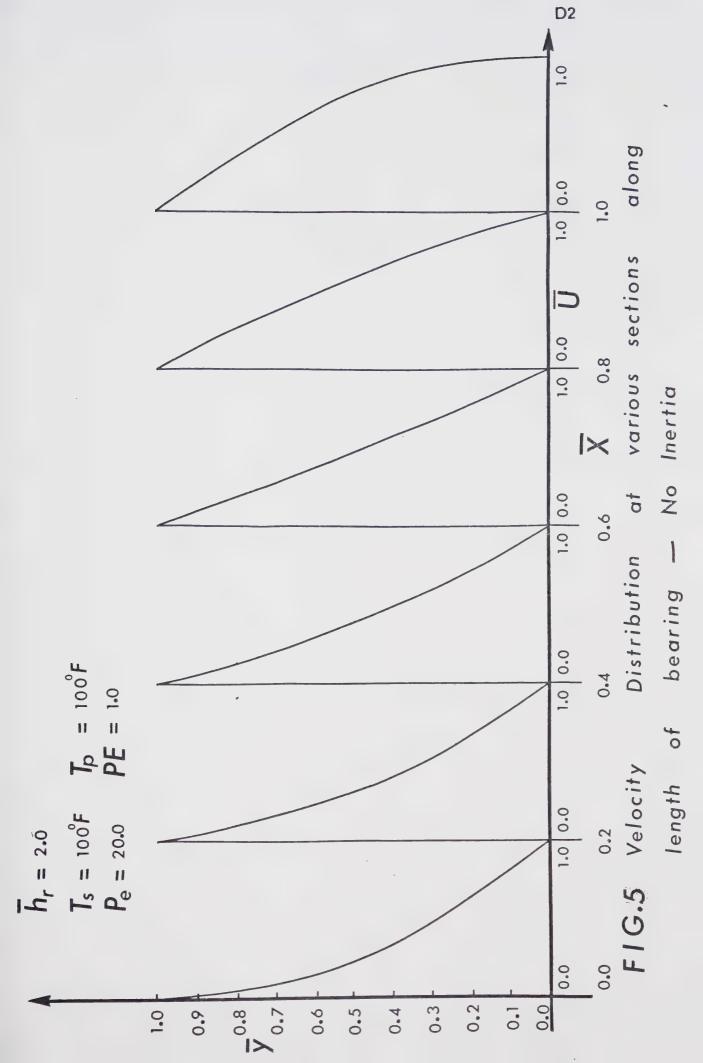


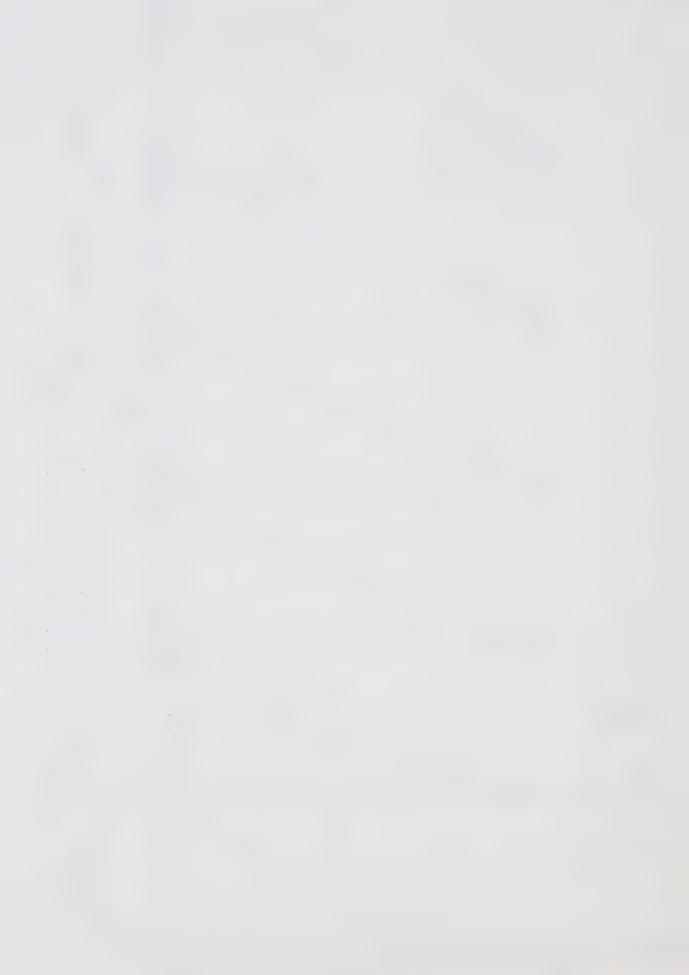
APPENDIX D
FIGURES FOR CHAPTER IV

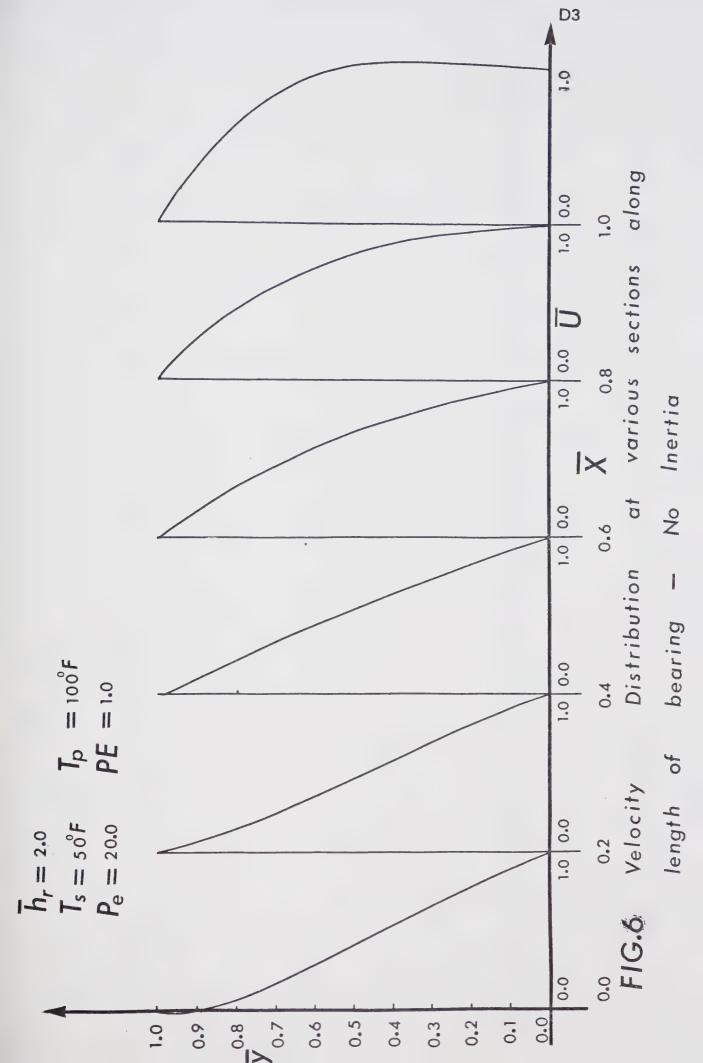


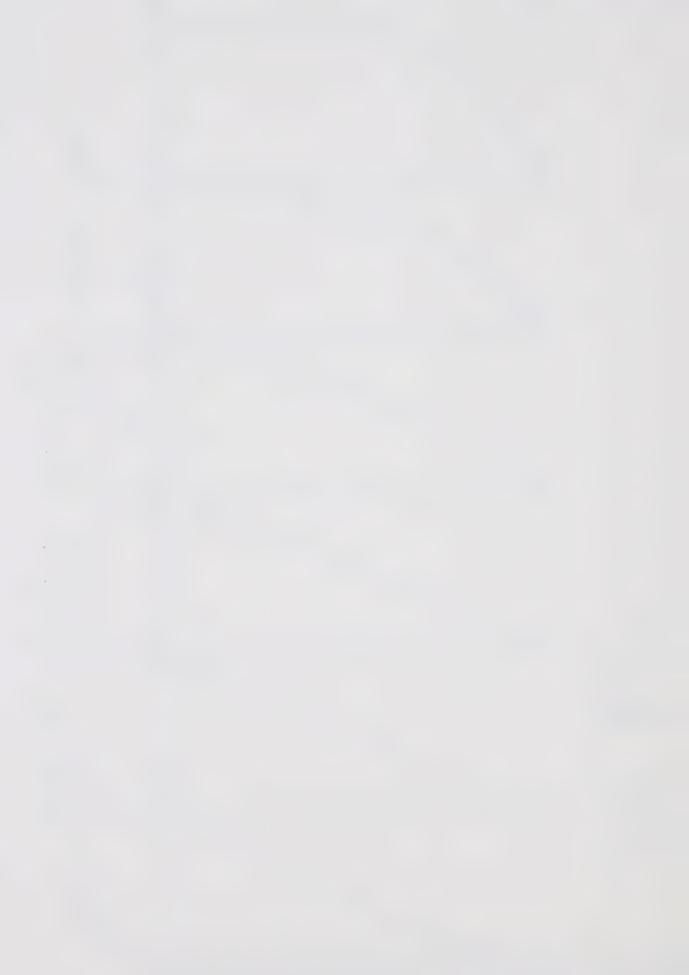


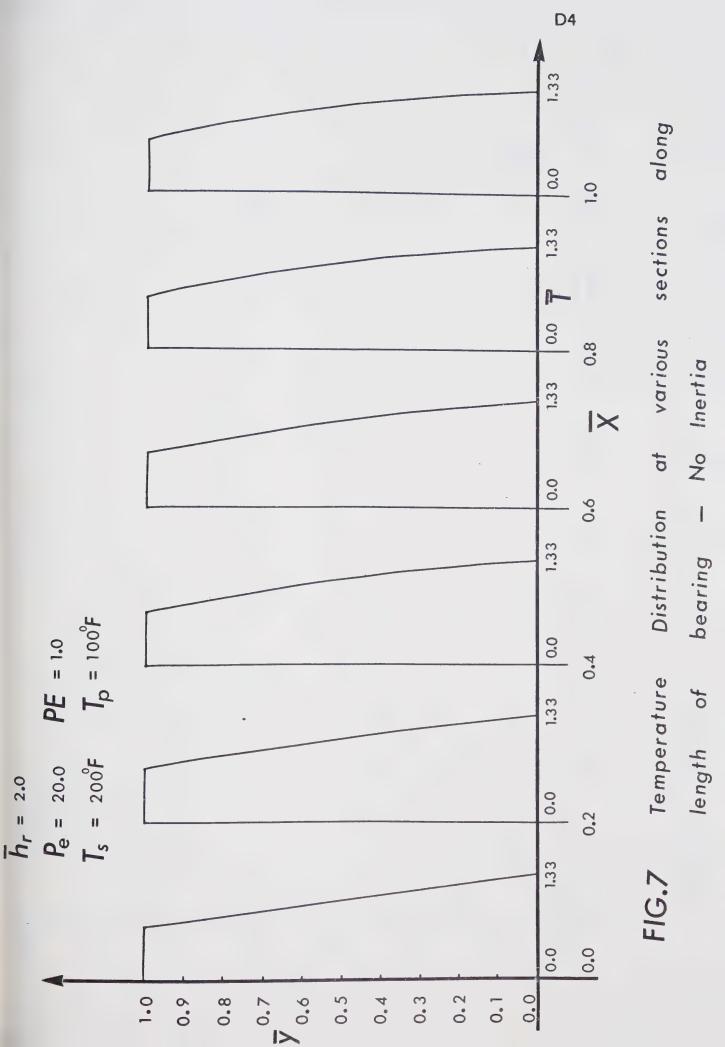


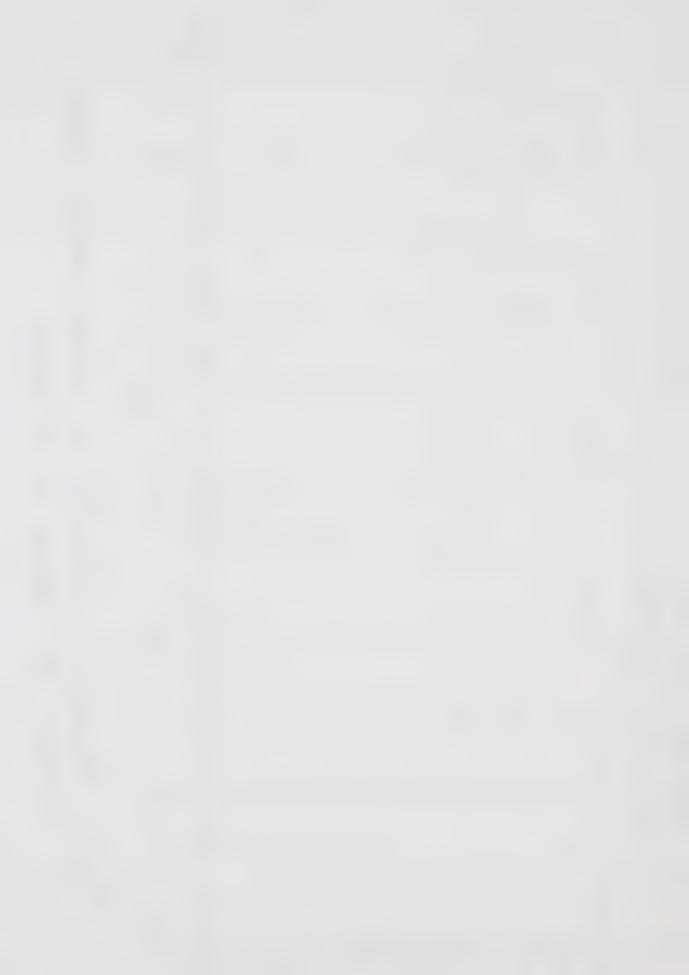


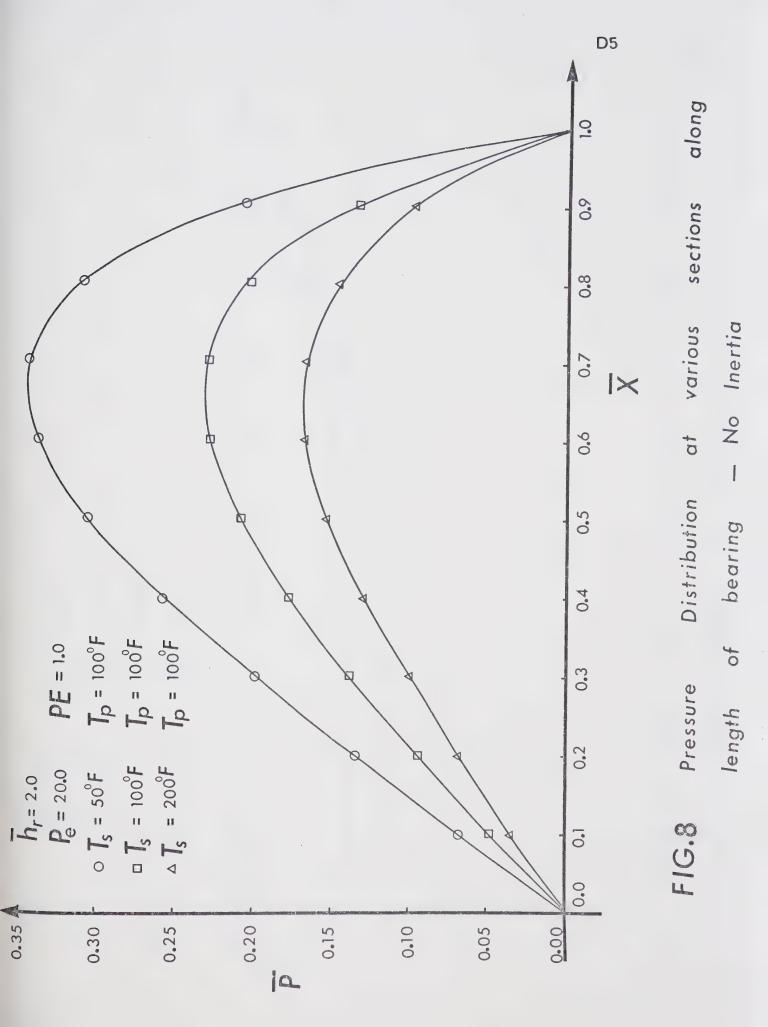


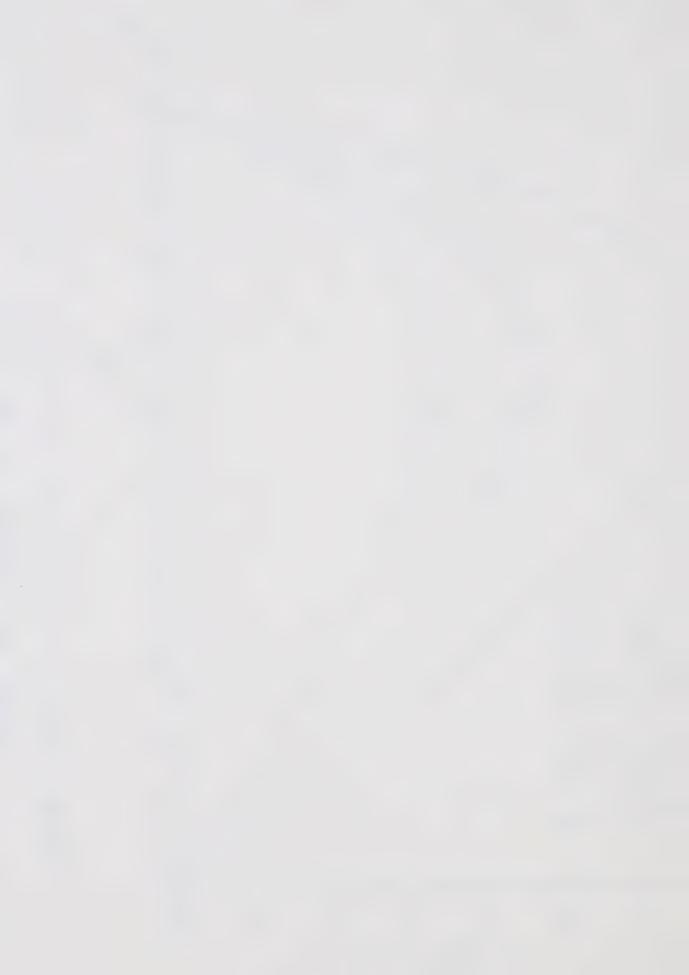


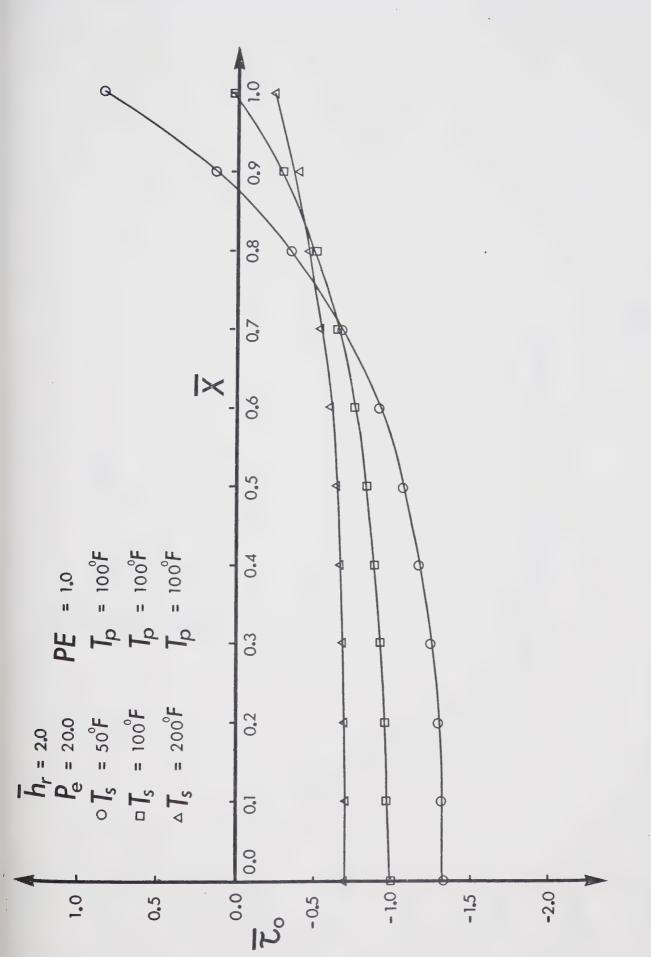




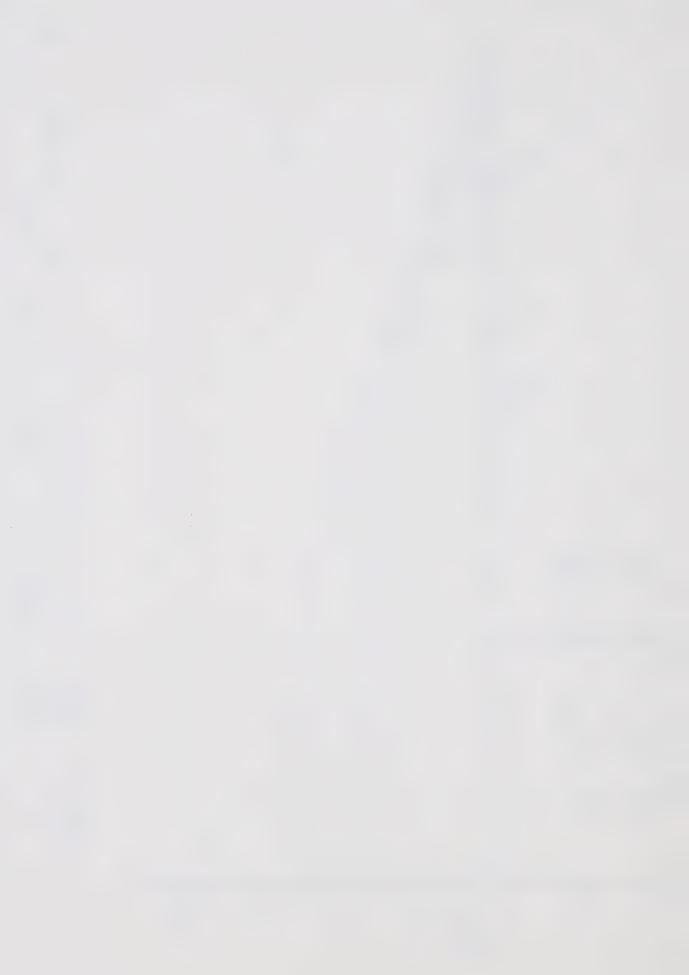


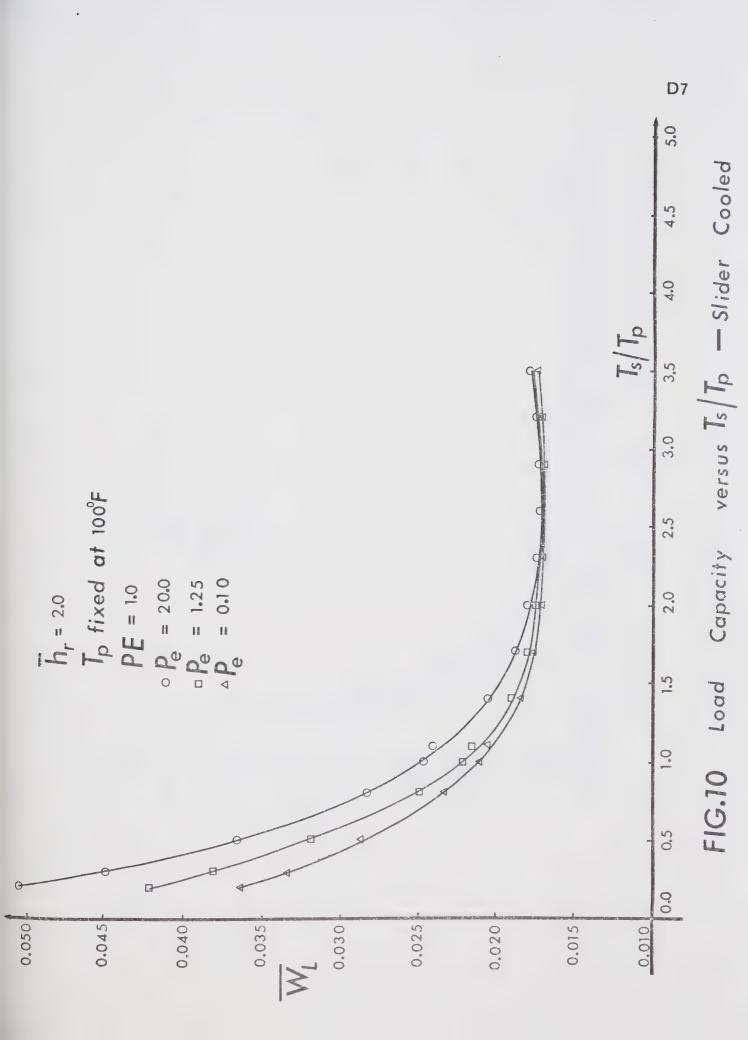




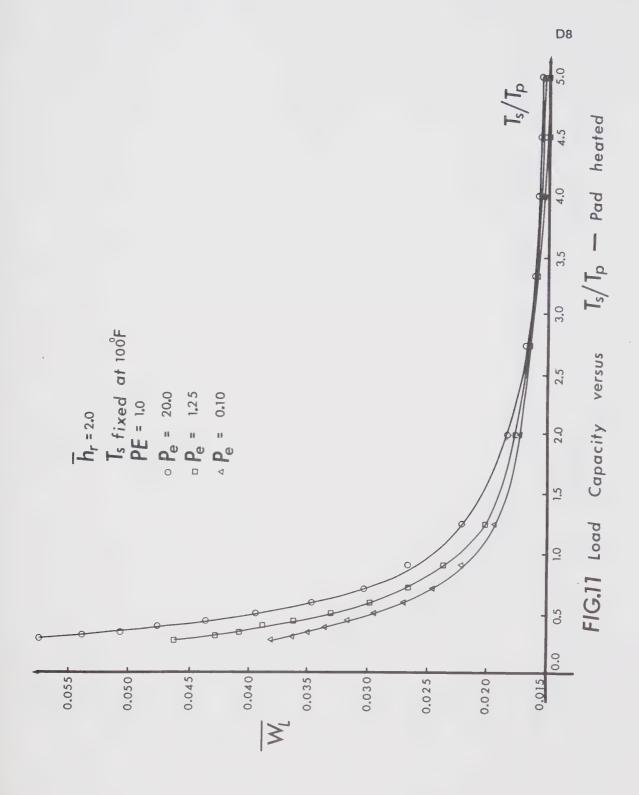


various sections No Inertia at 1 Distribution of slider Stress along length Shear

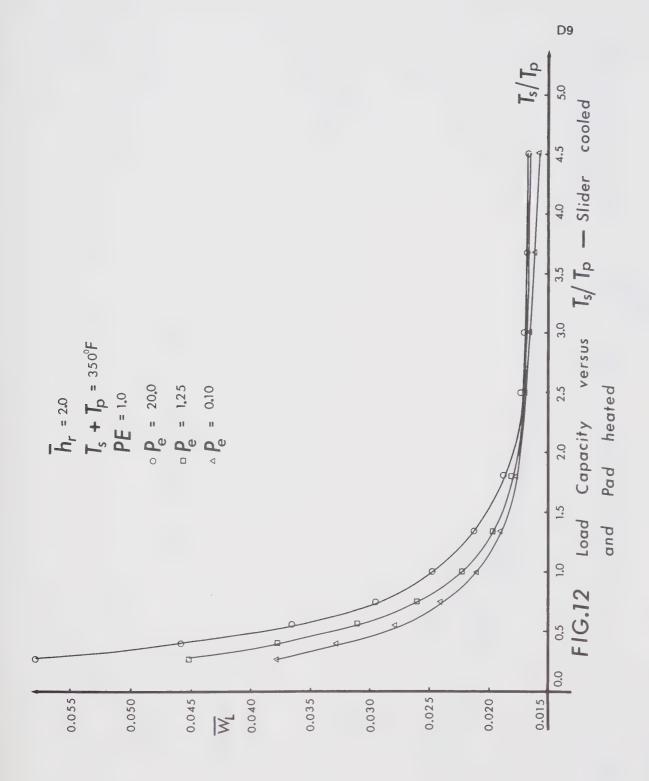


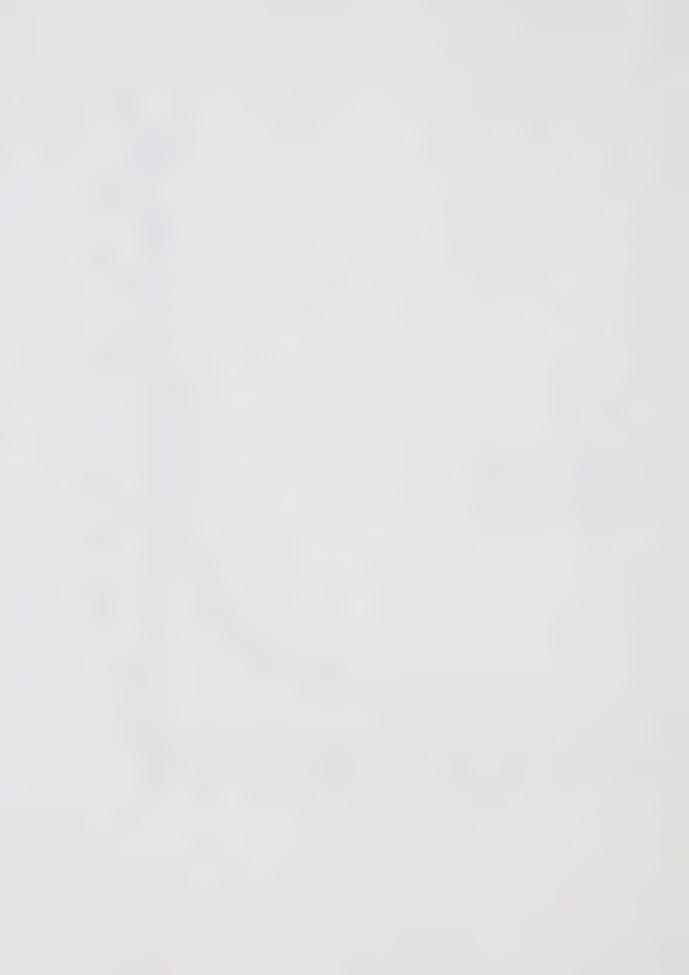


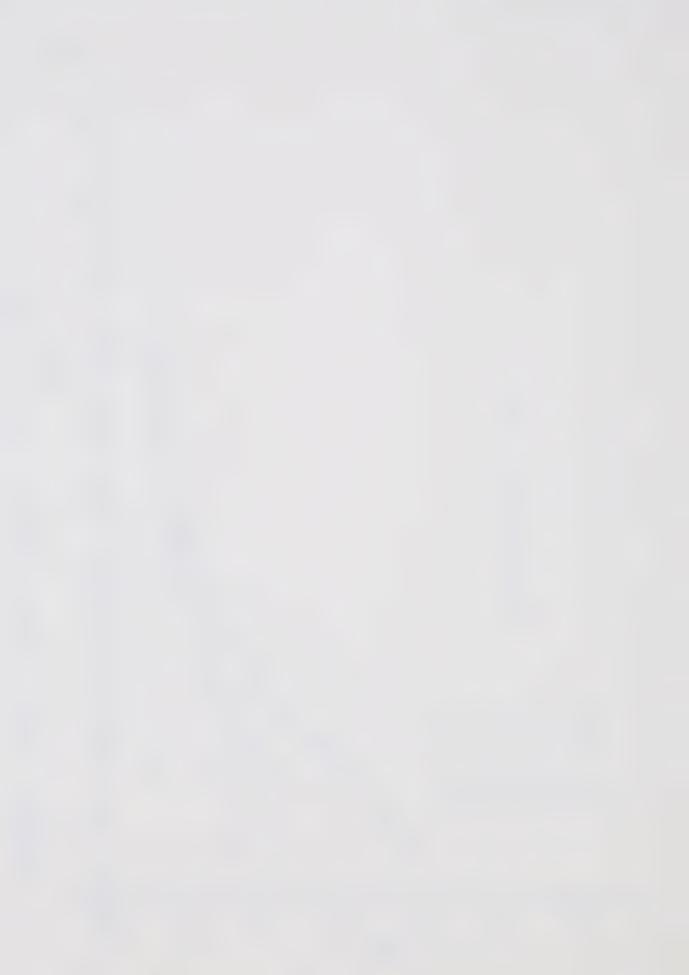


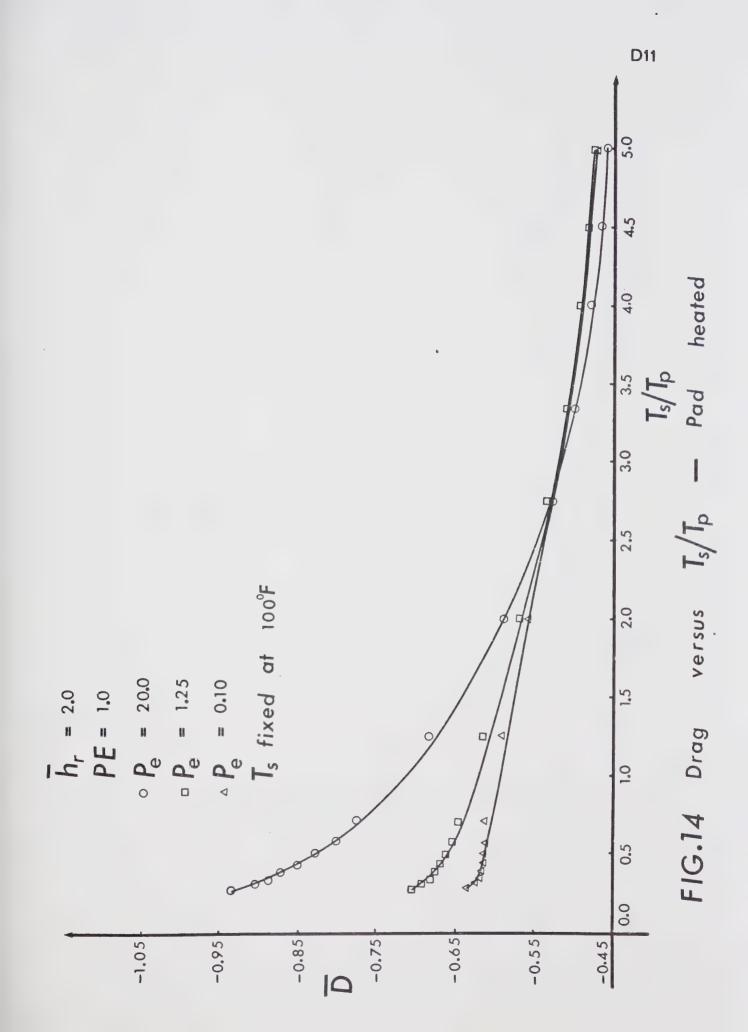


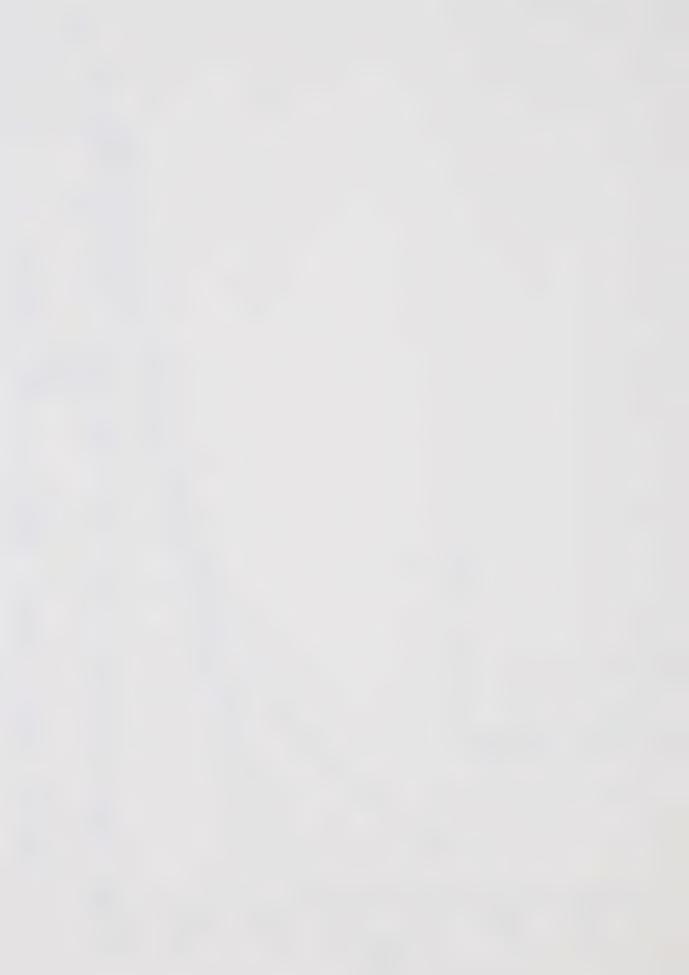


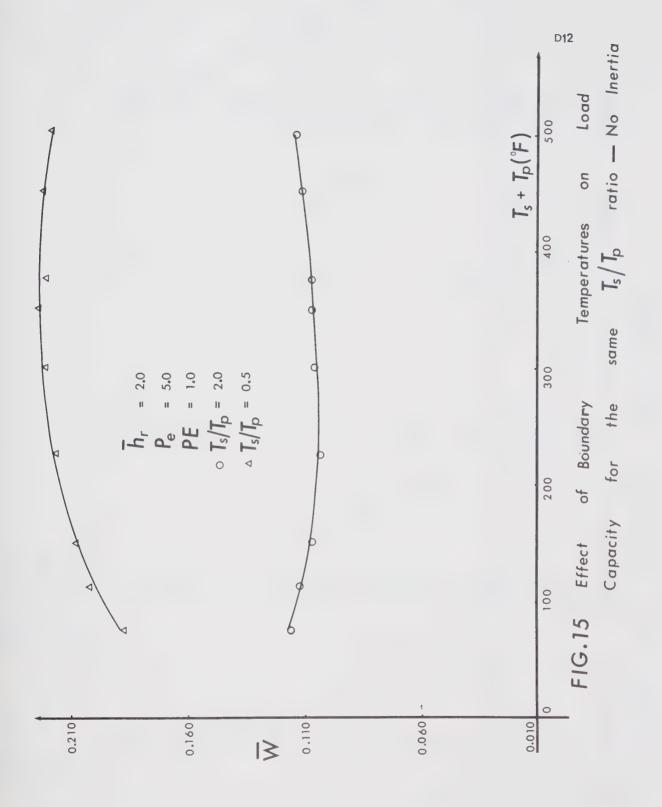


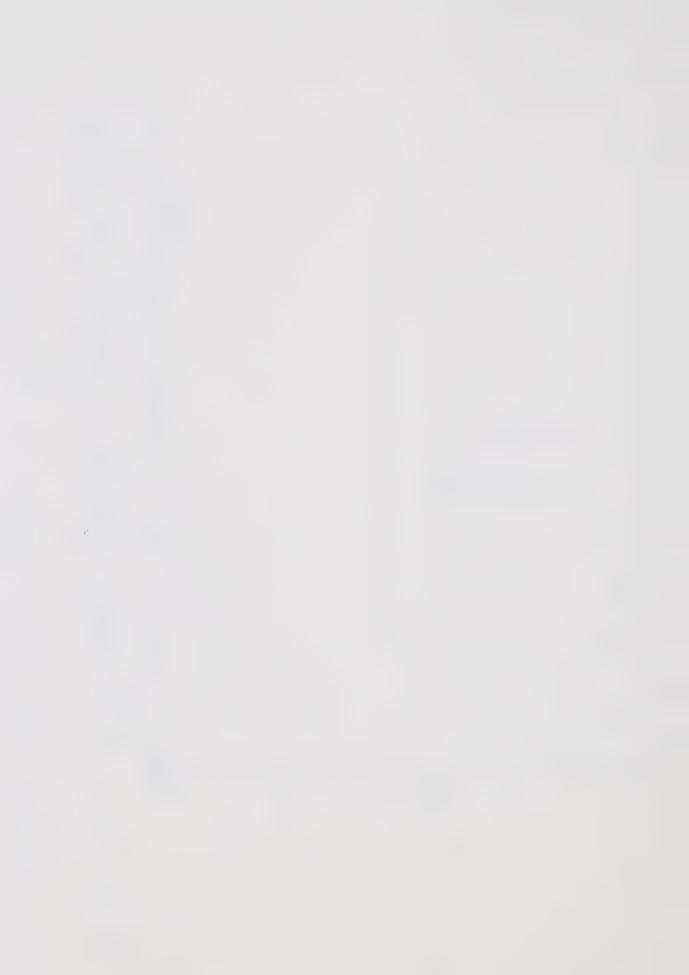


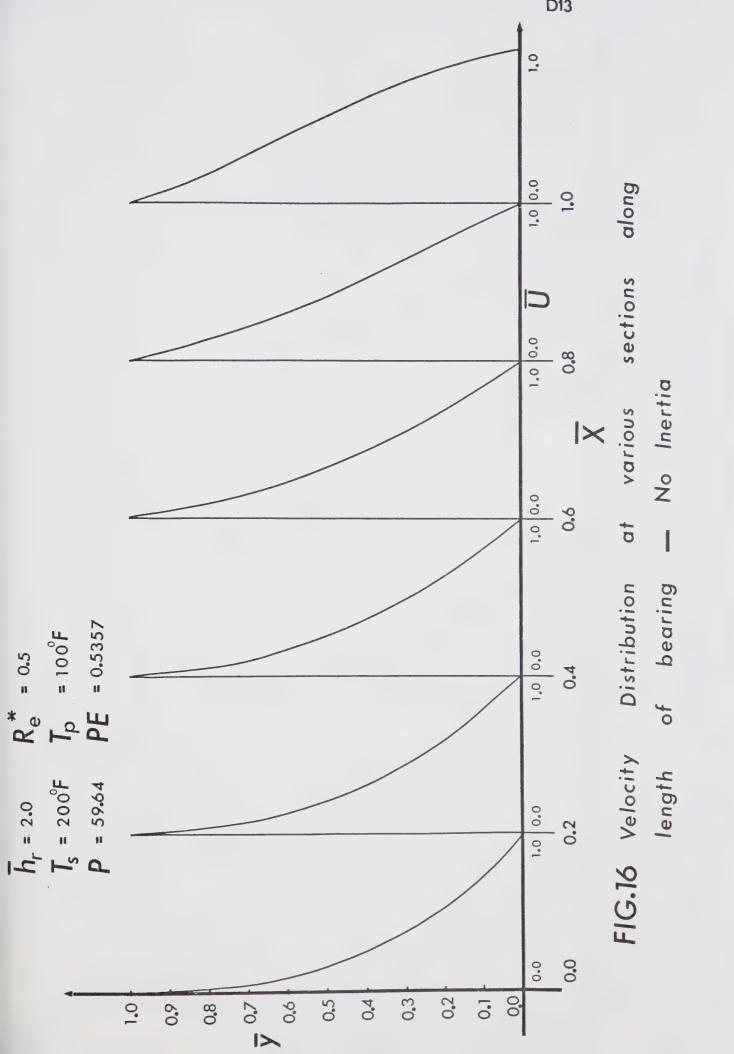


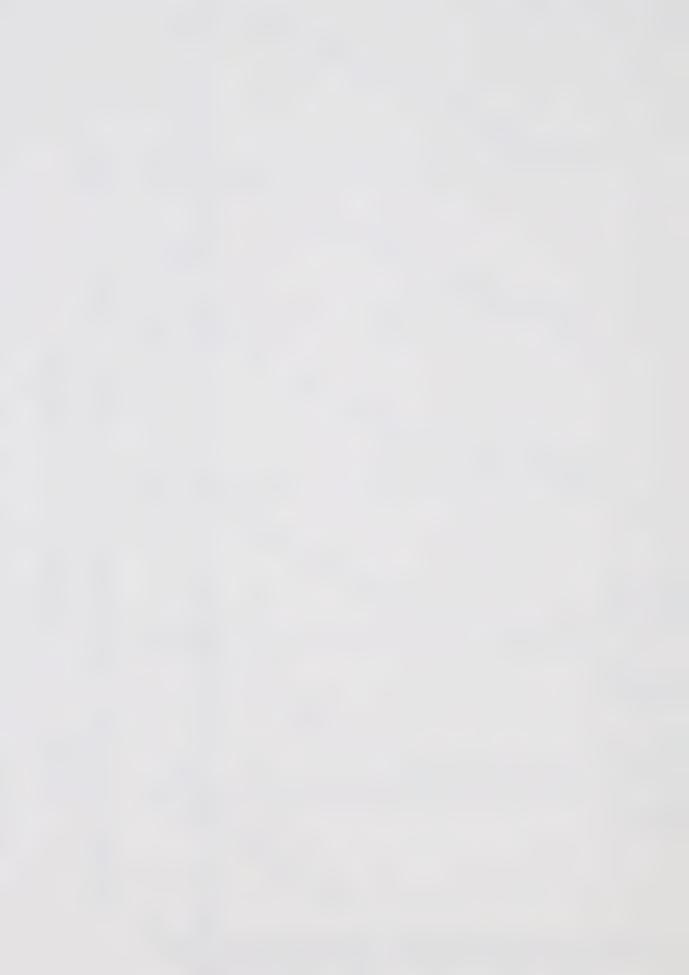


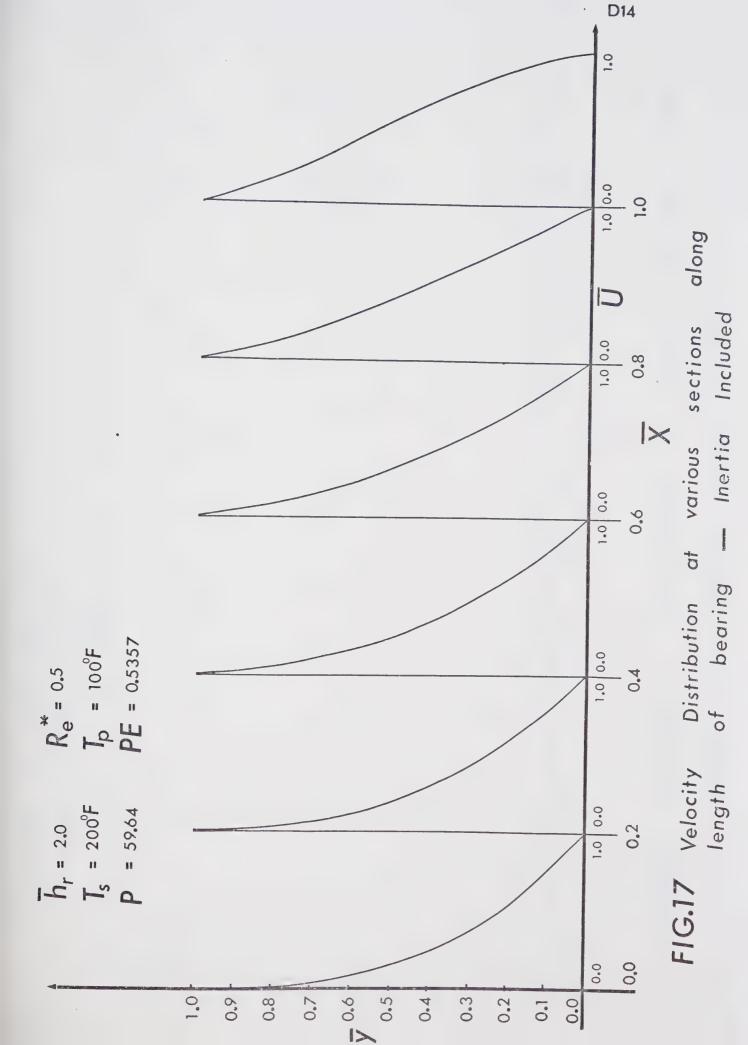


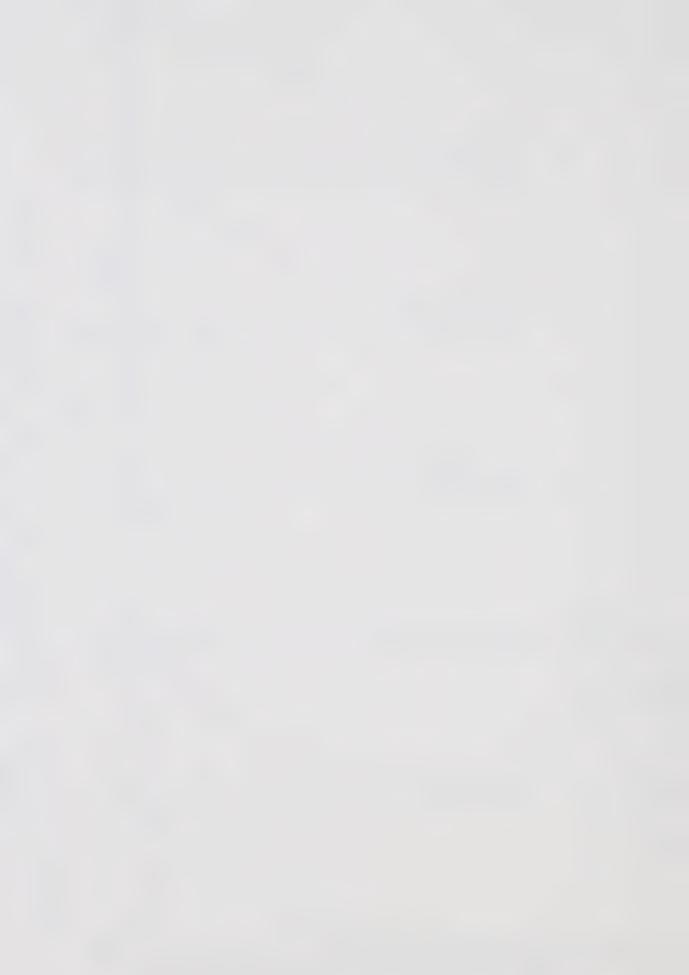


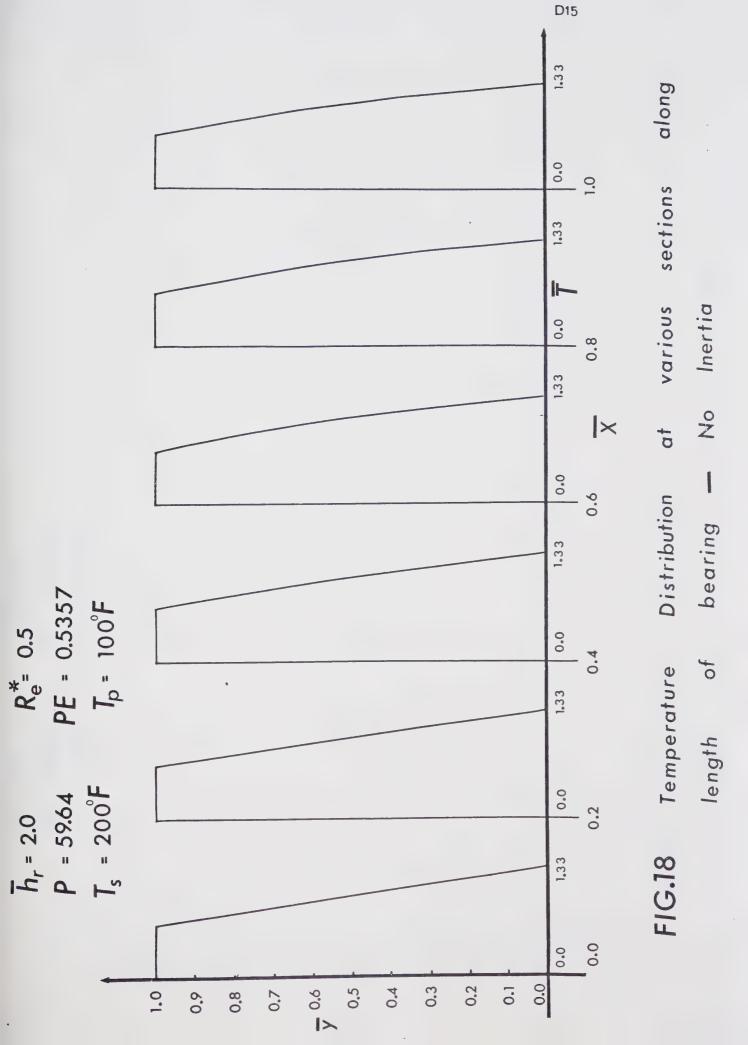


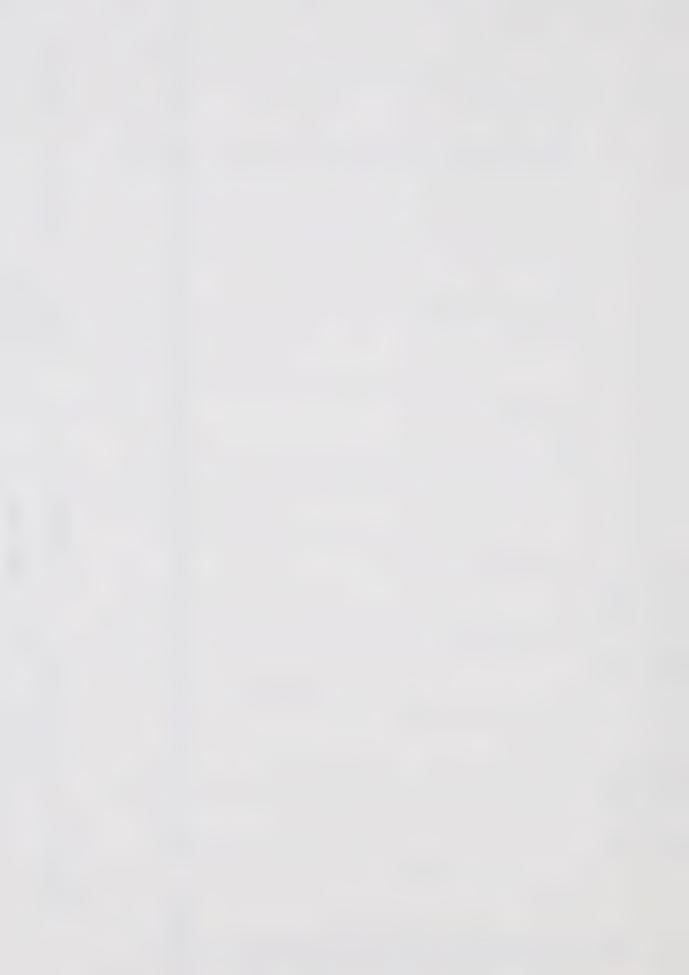


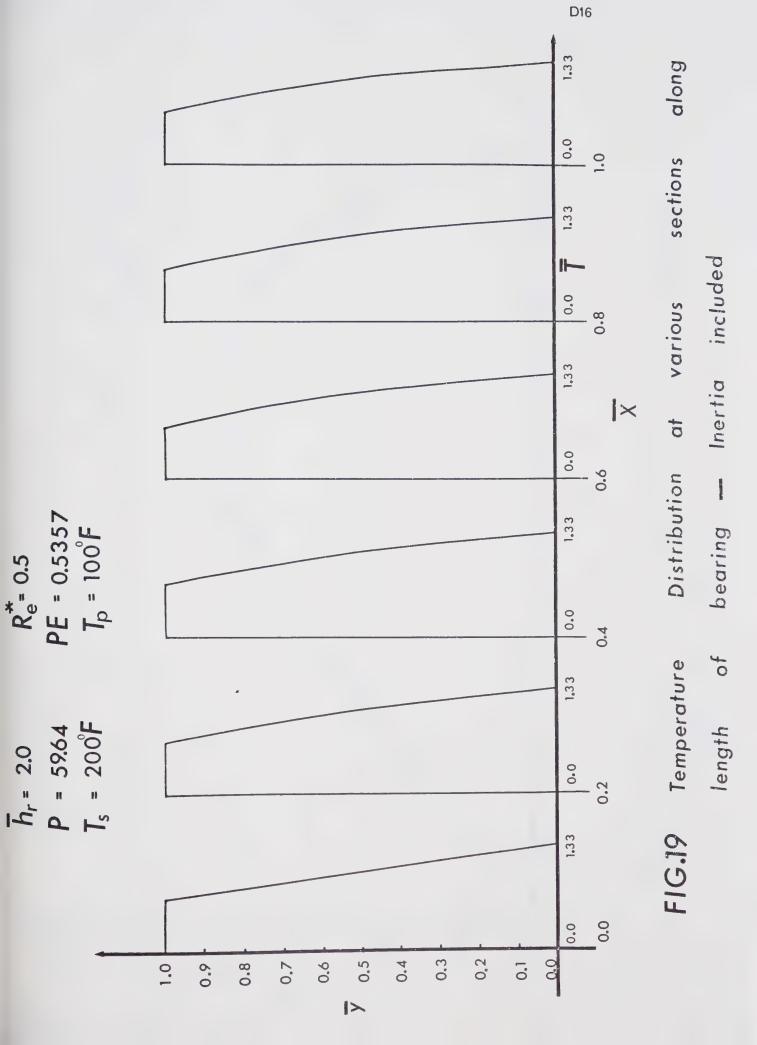




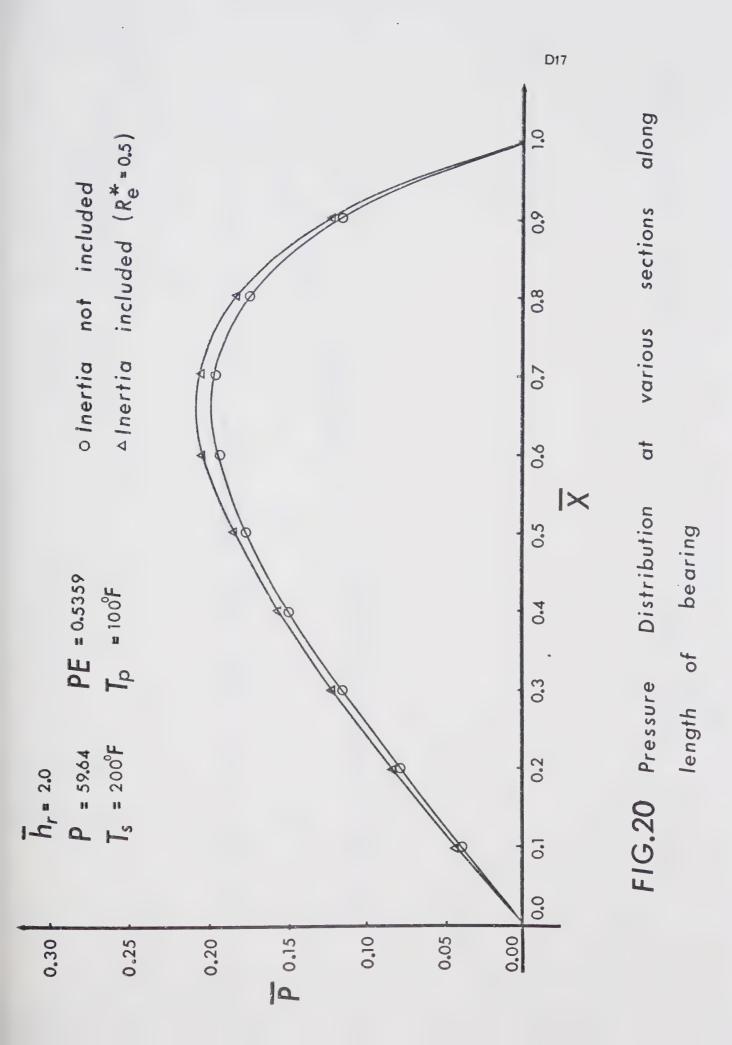




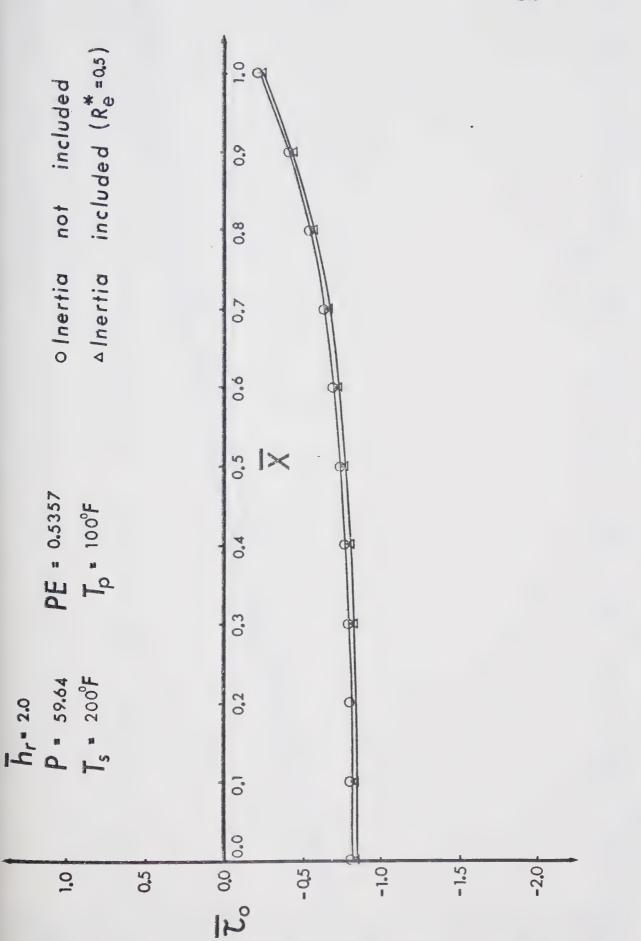




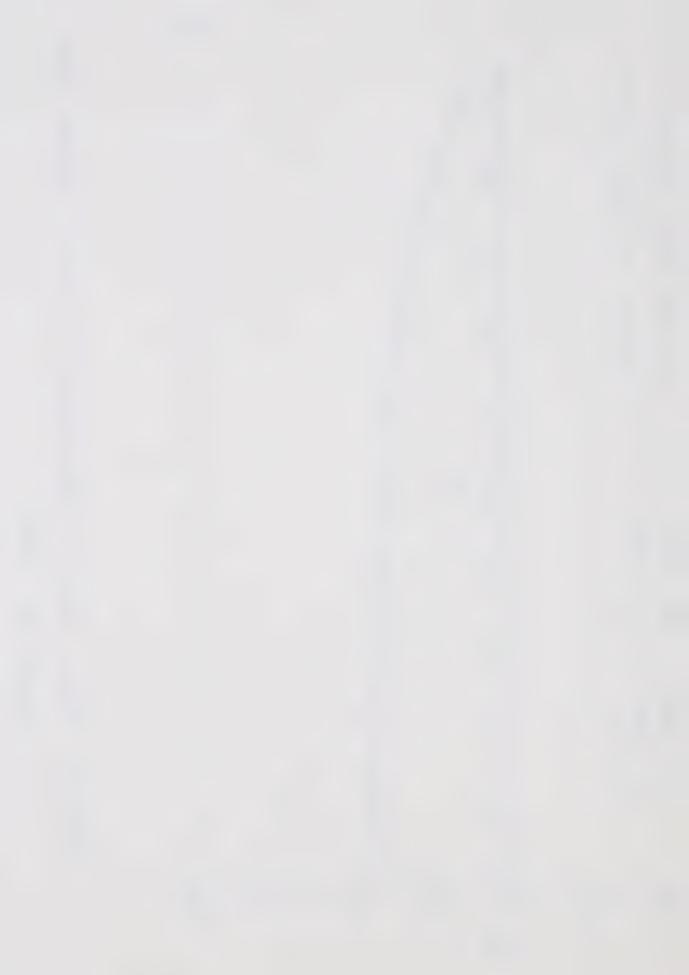


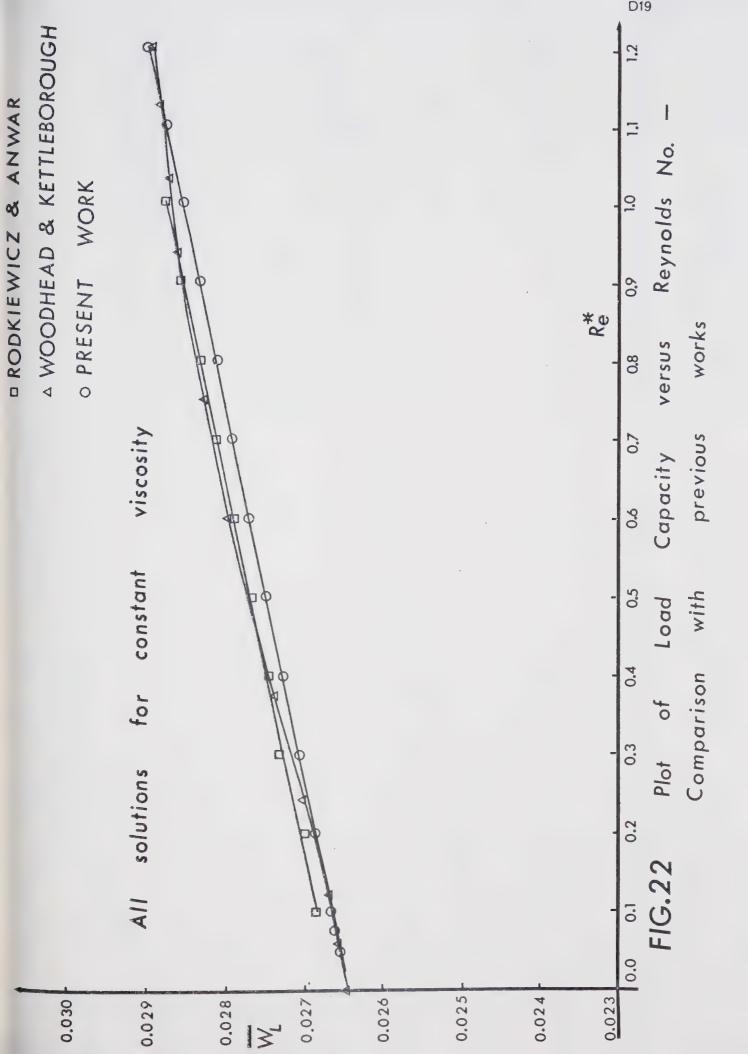




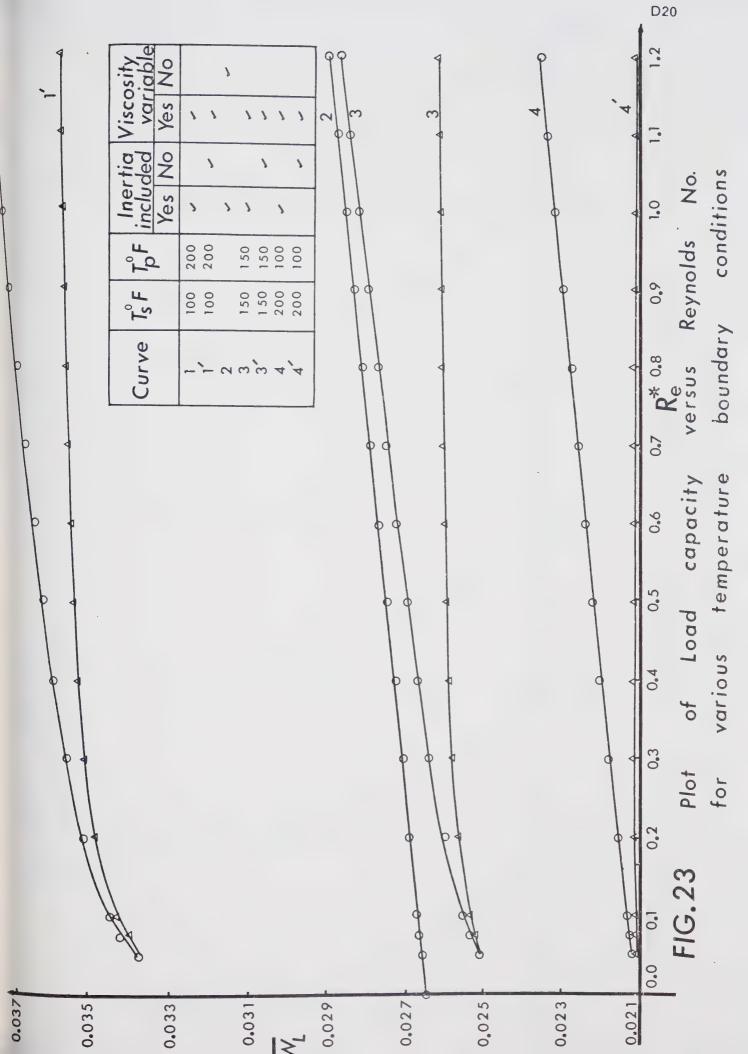


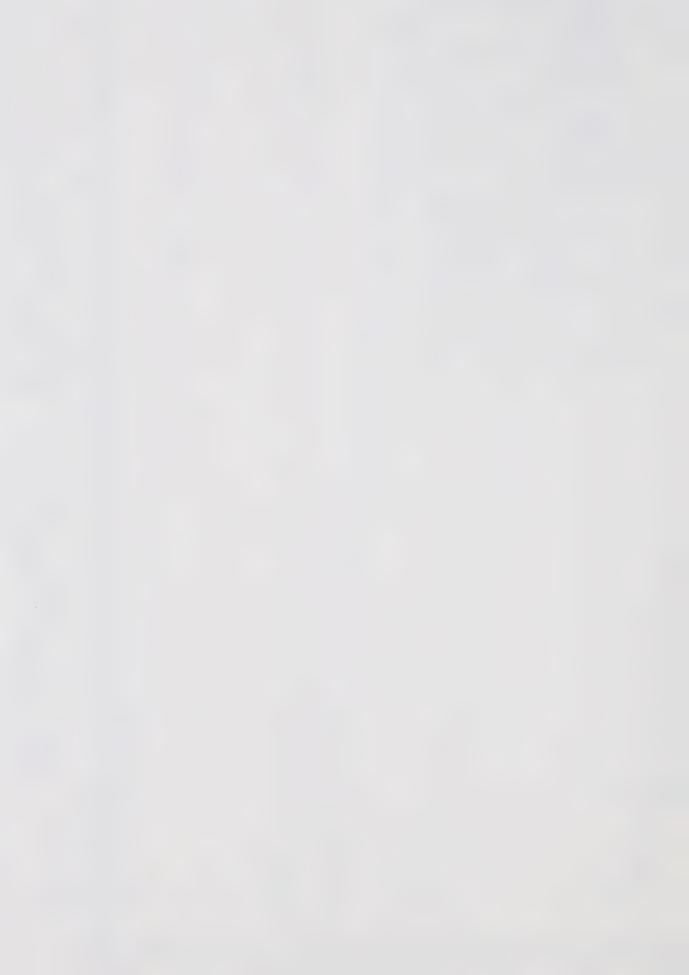
Distribution at various sections along Stress length of Shear FIG.21

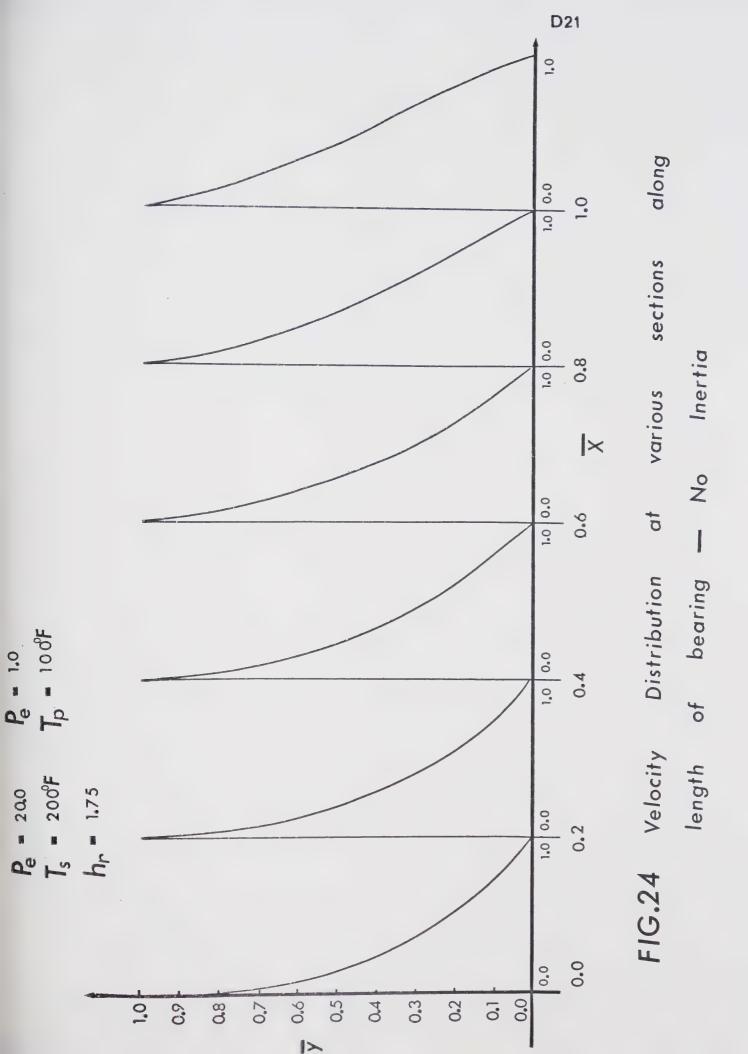




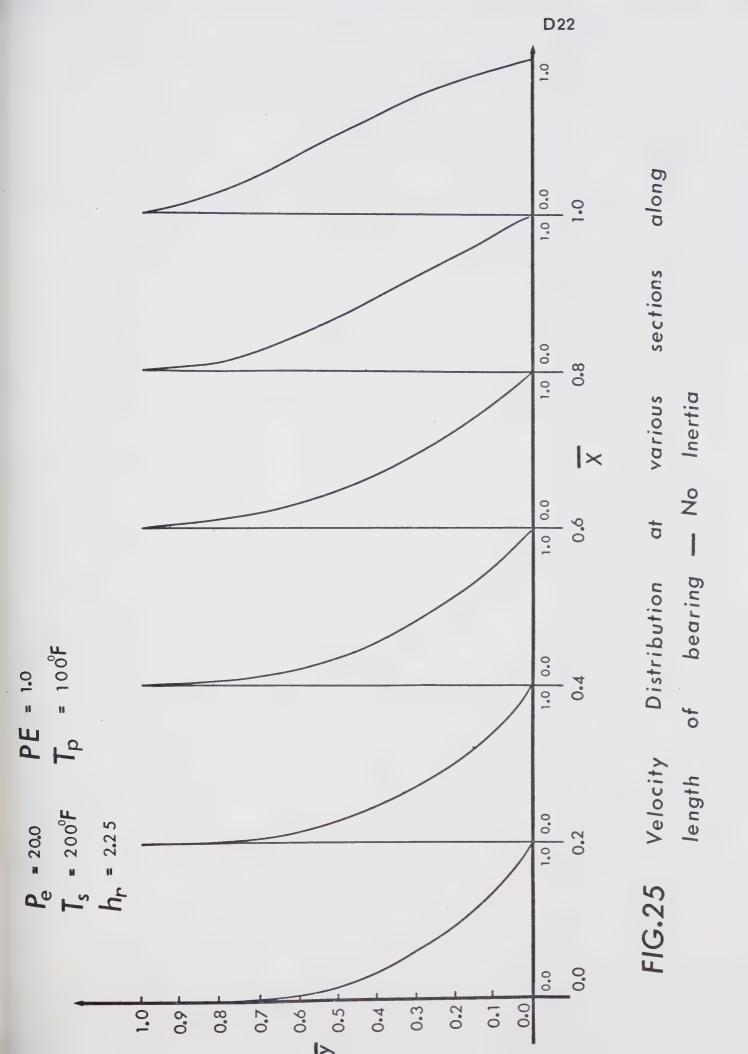


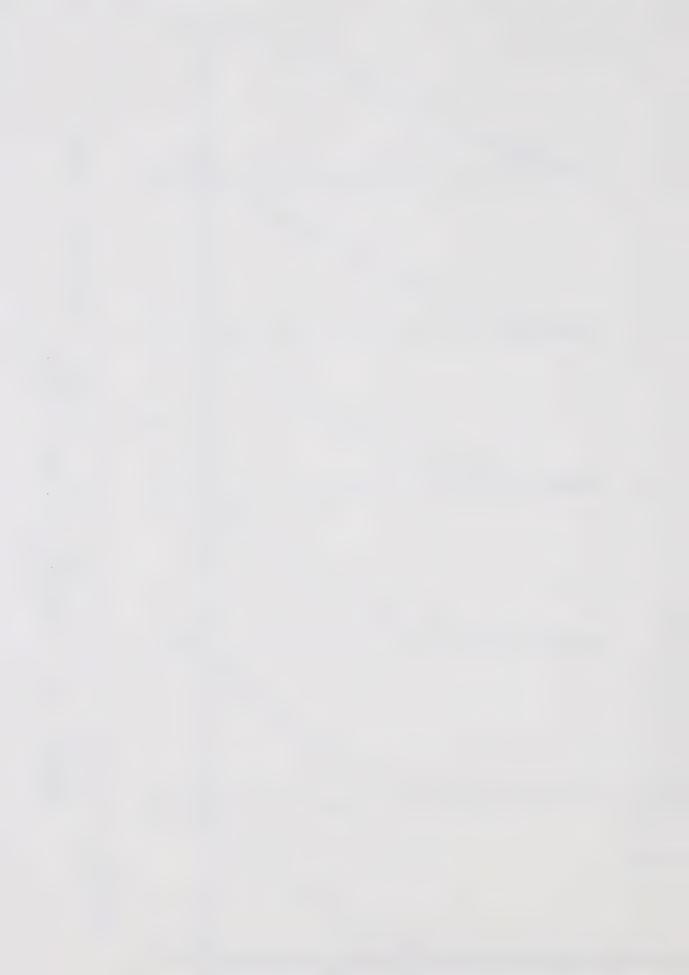


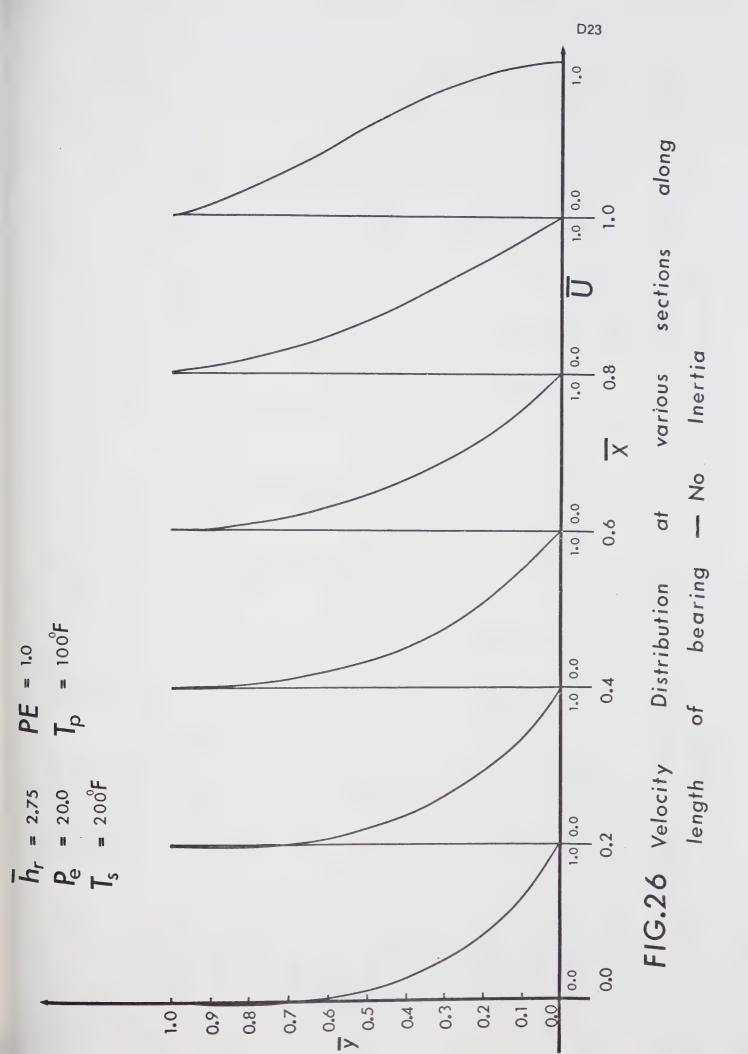


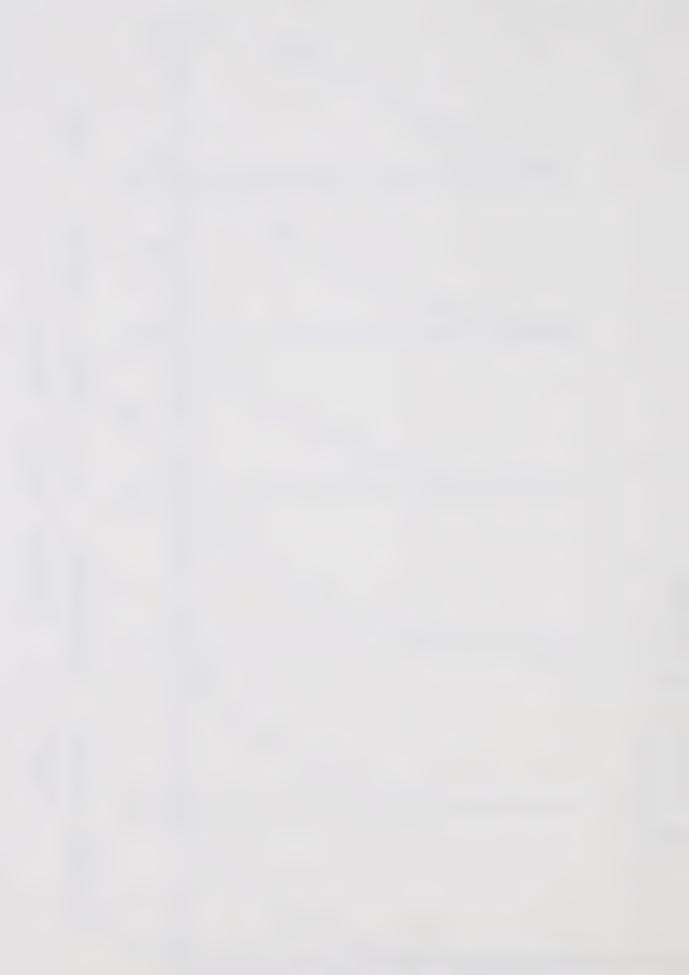


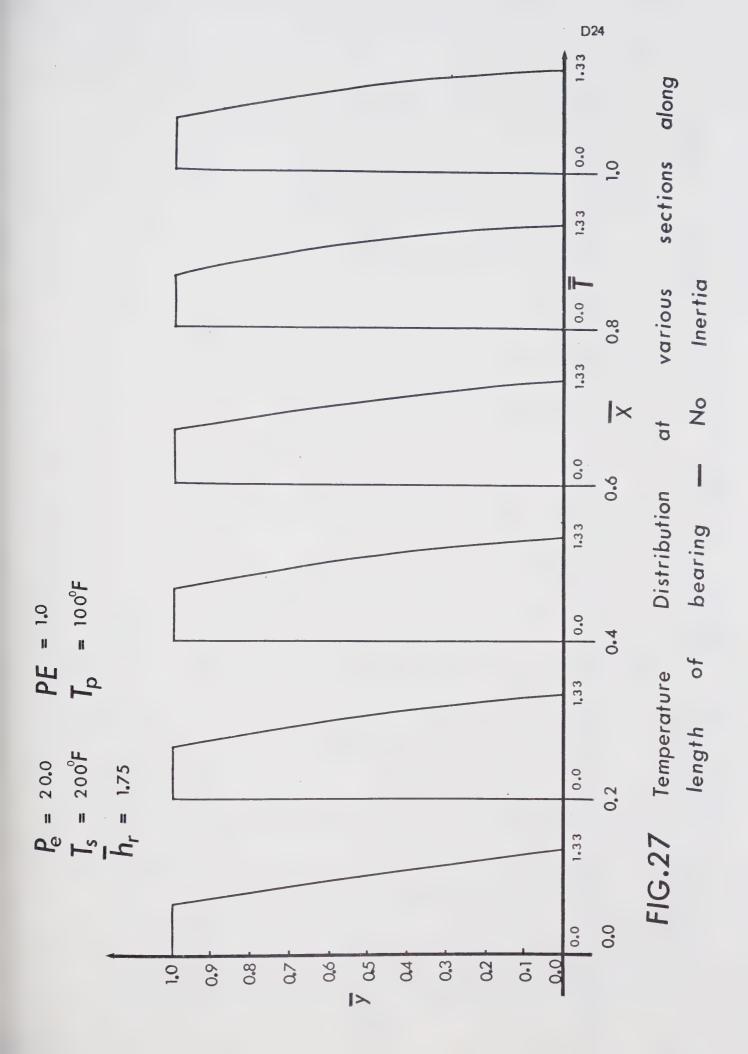


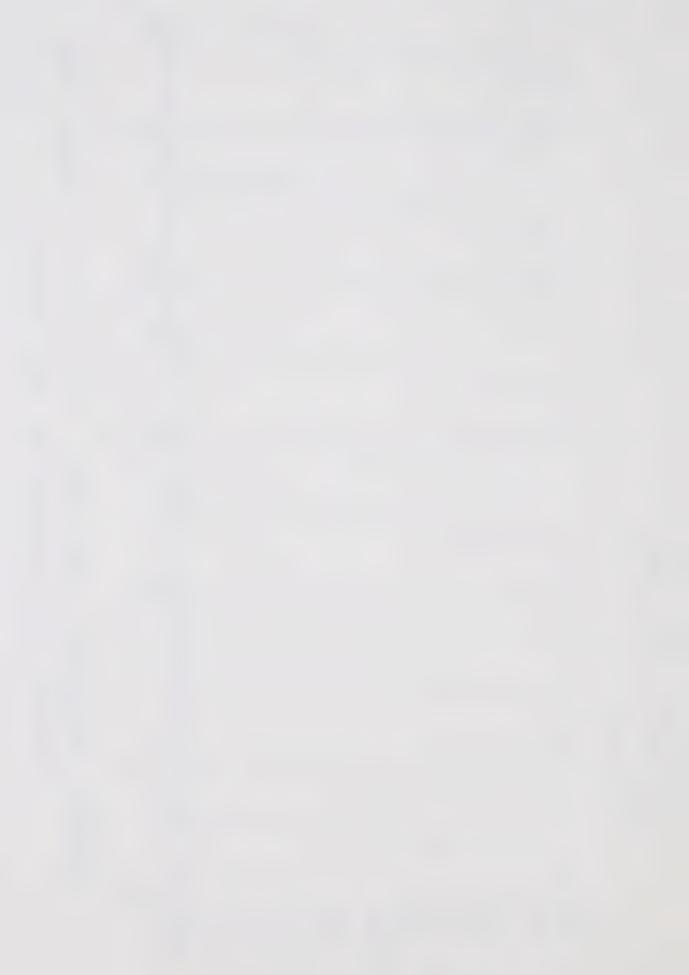


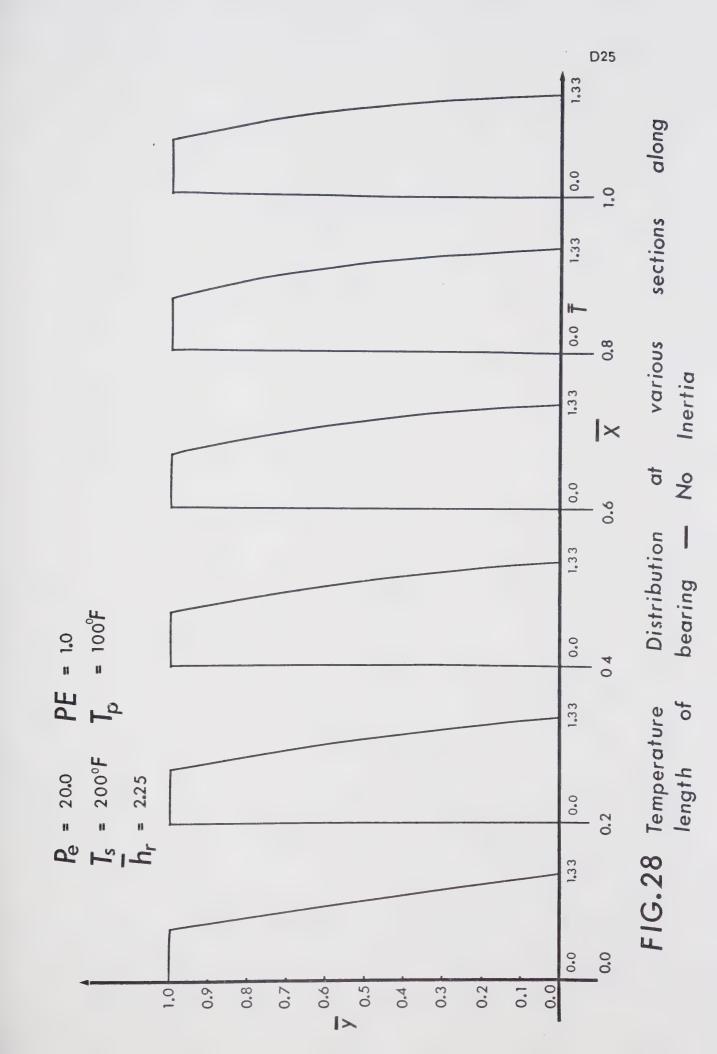


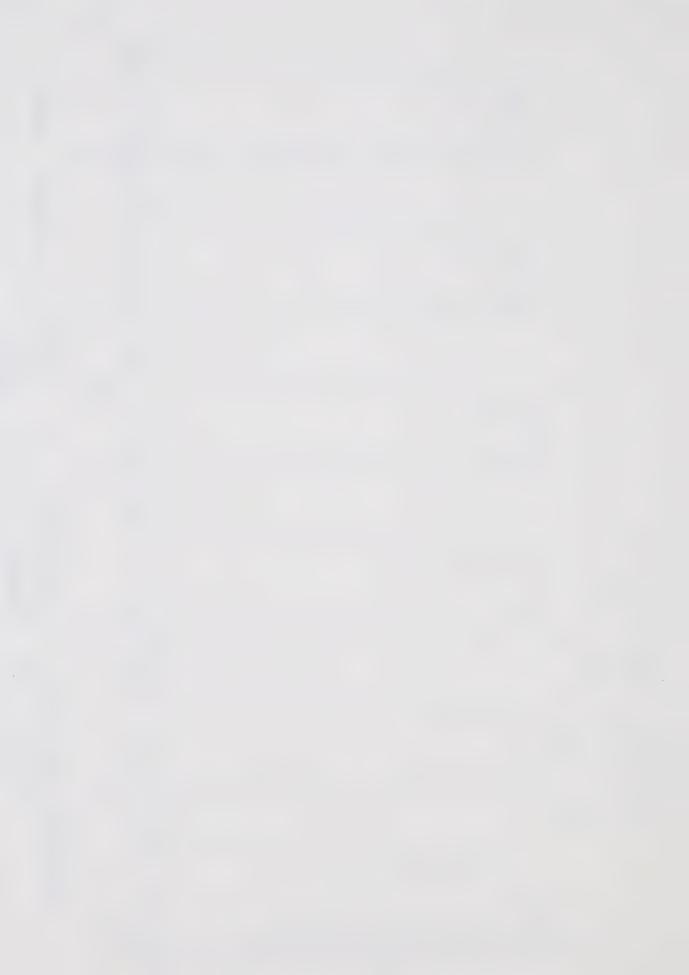


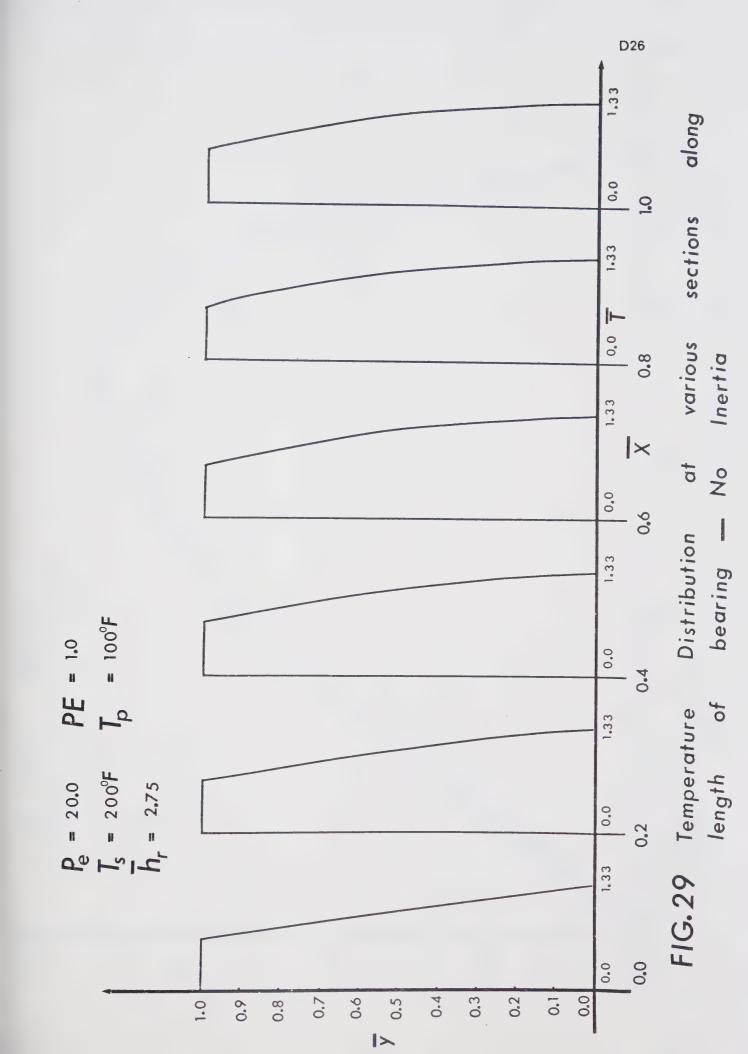


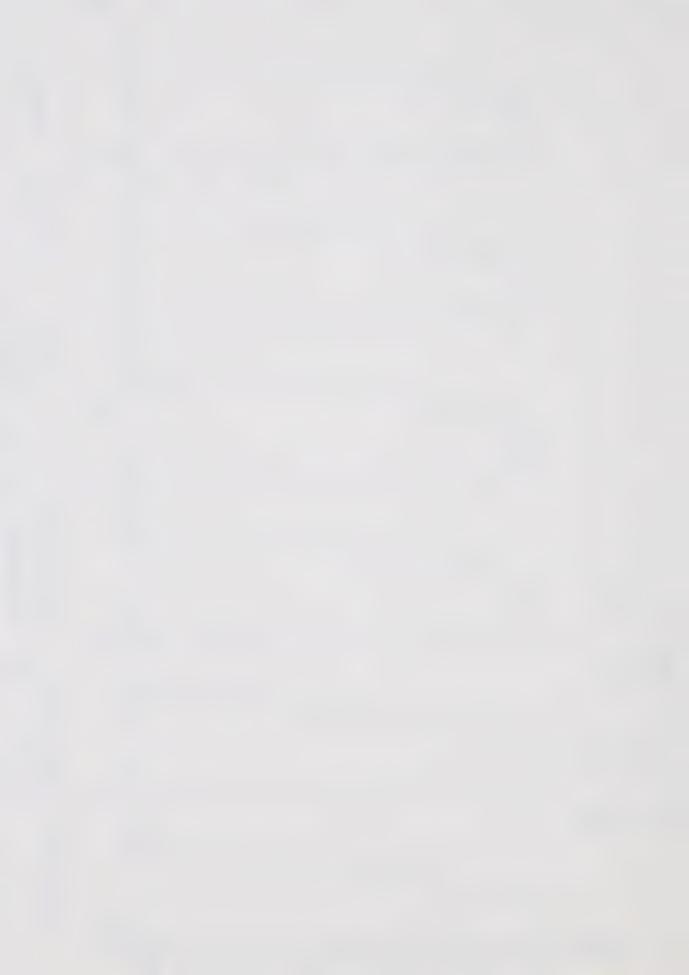


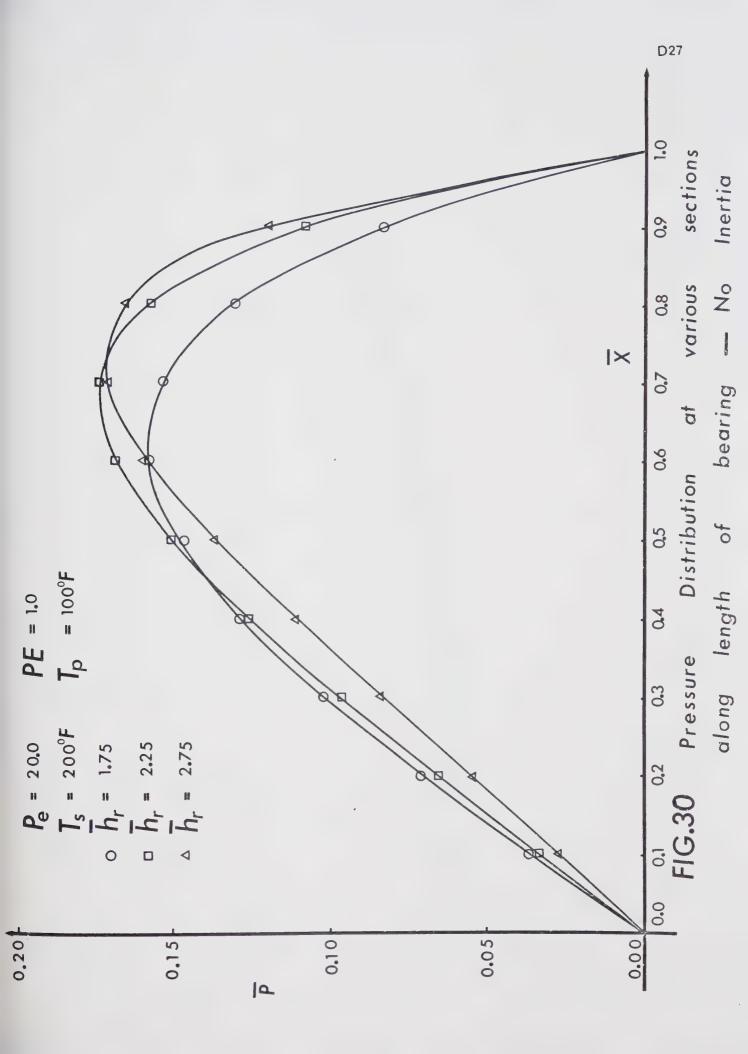


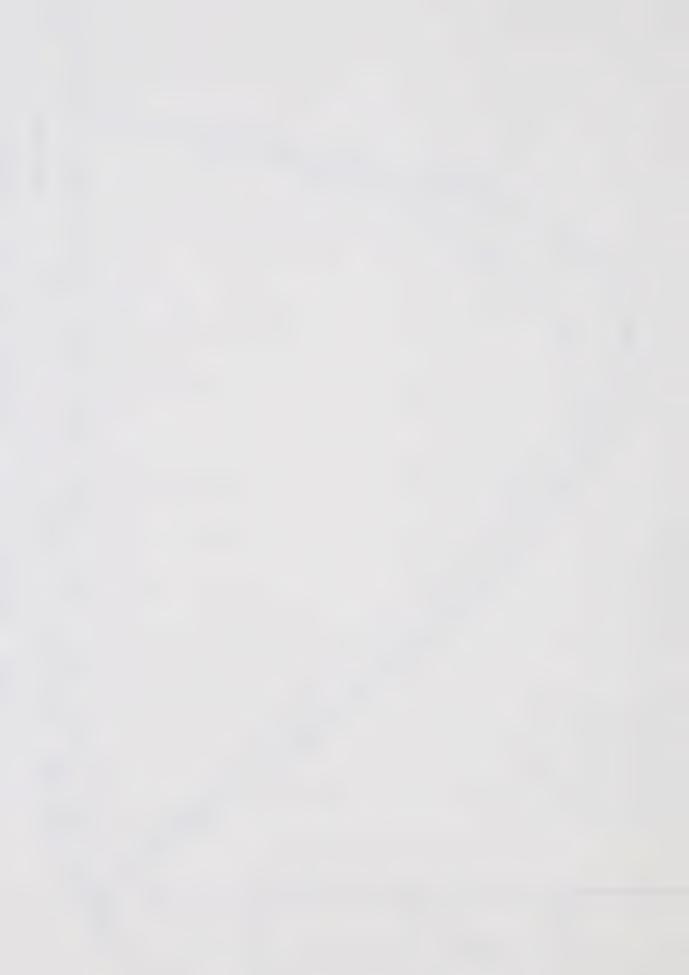


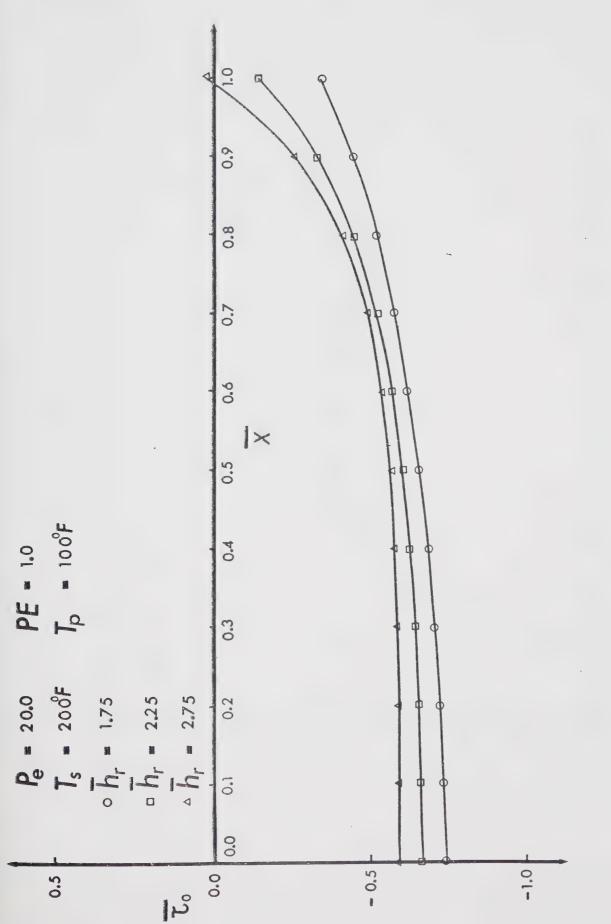




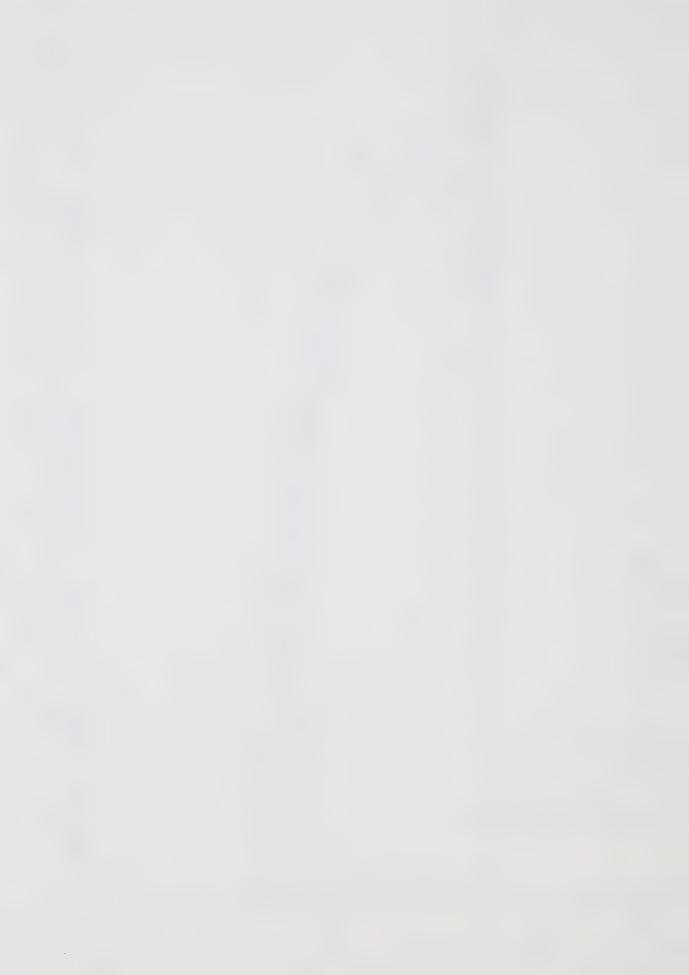


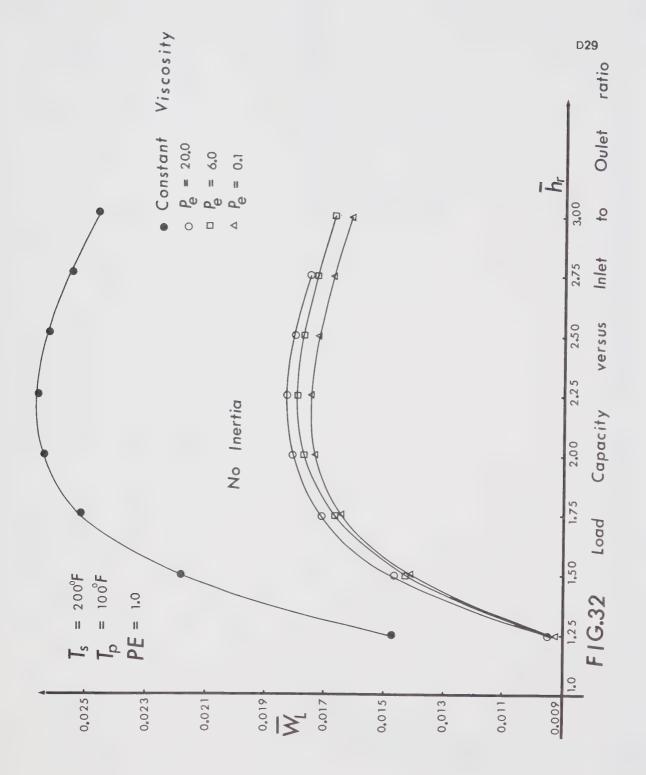


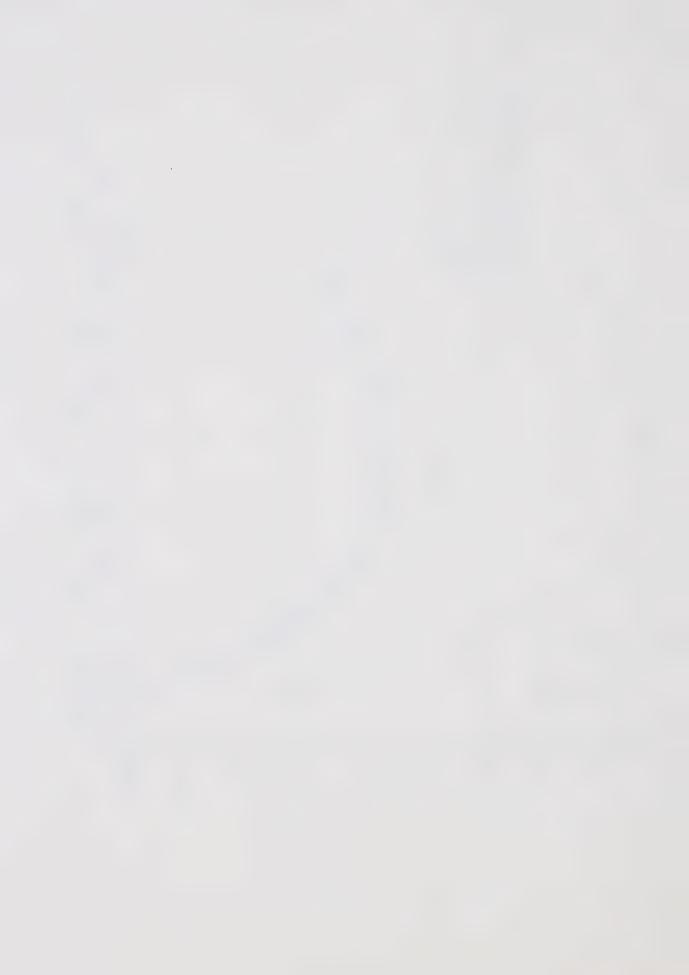


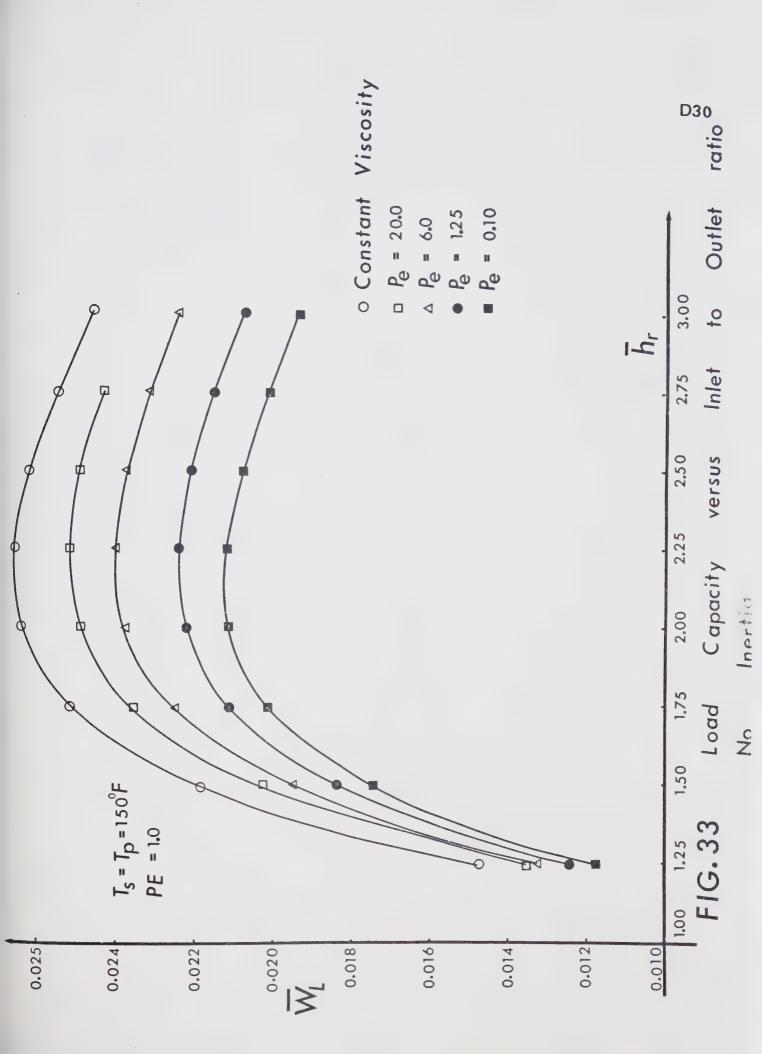


sections No Inertia various at Distribution of slider Stress length Shear along FIG.31

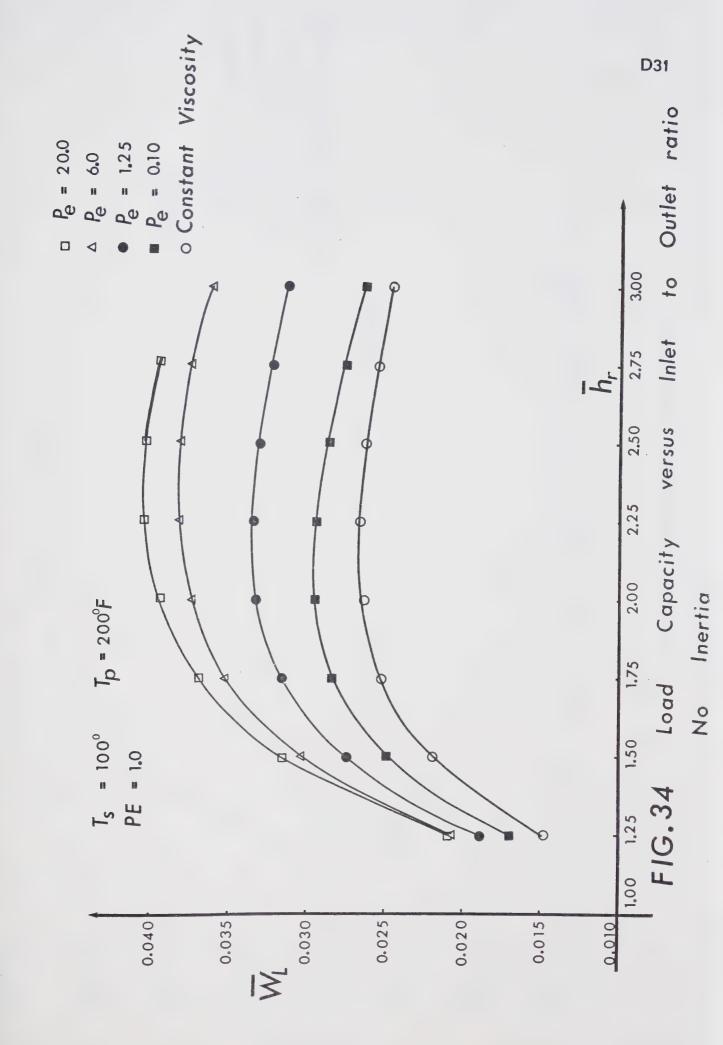


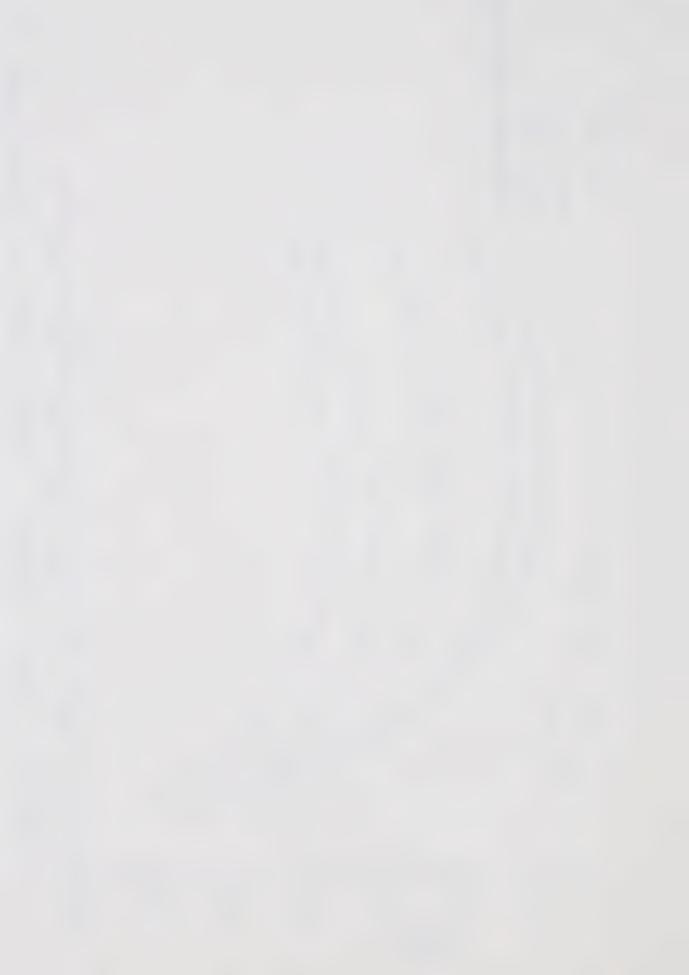












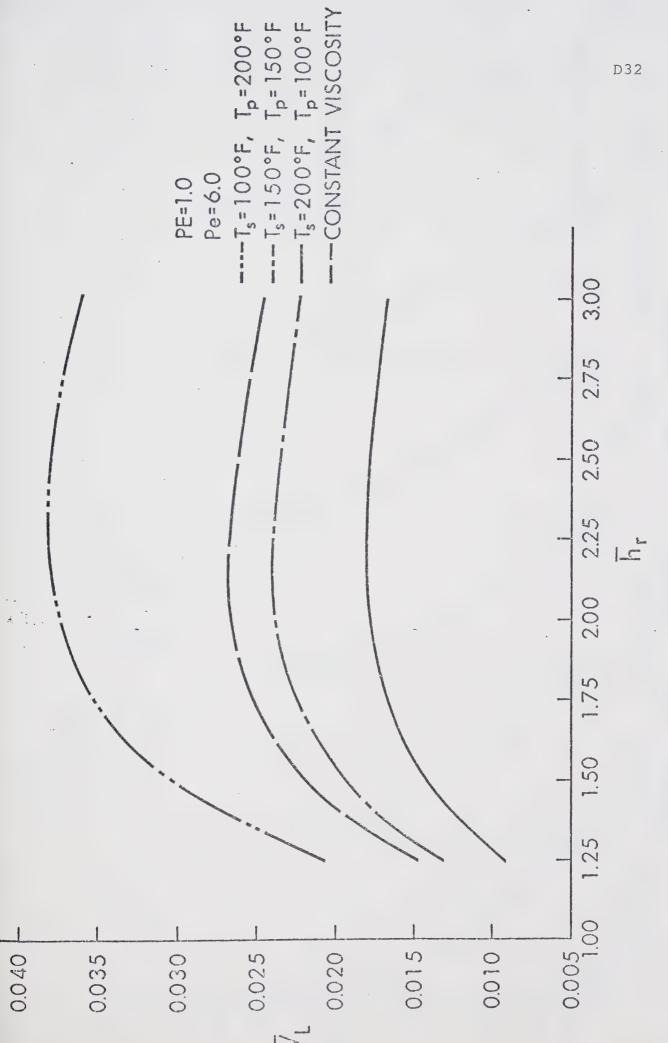
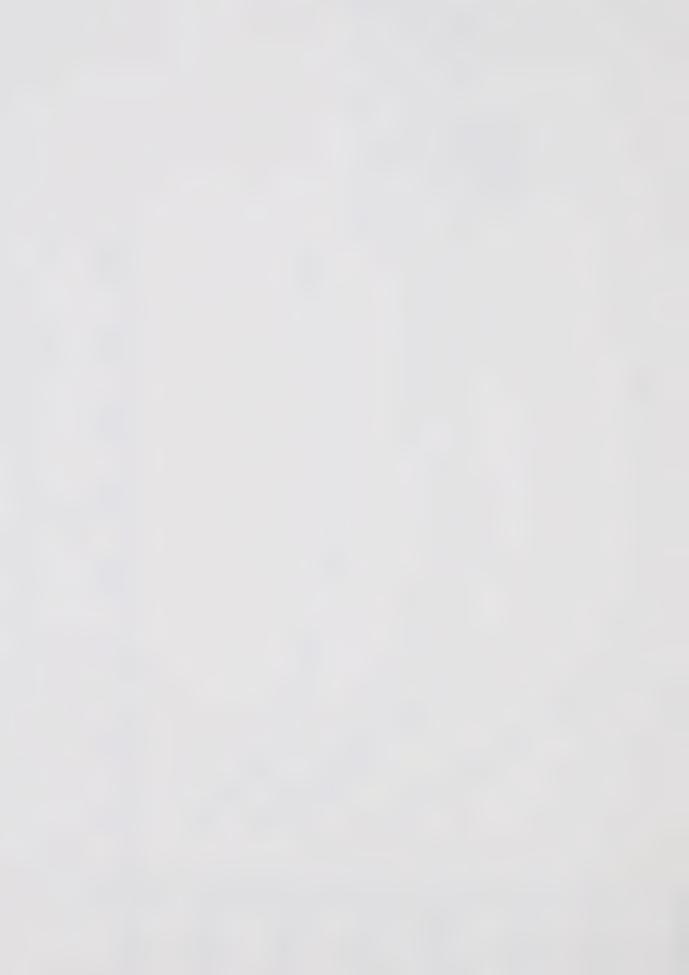
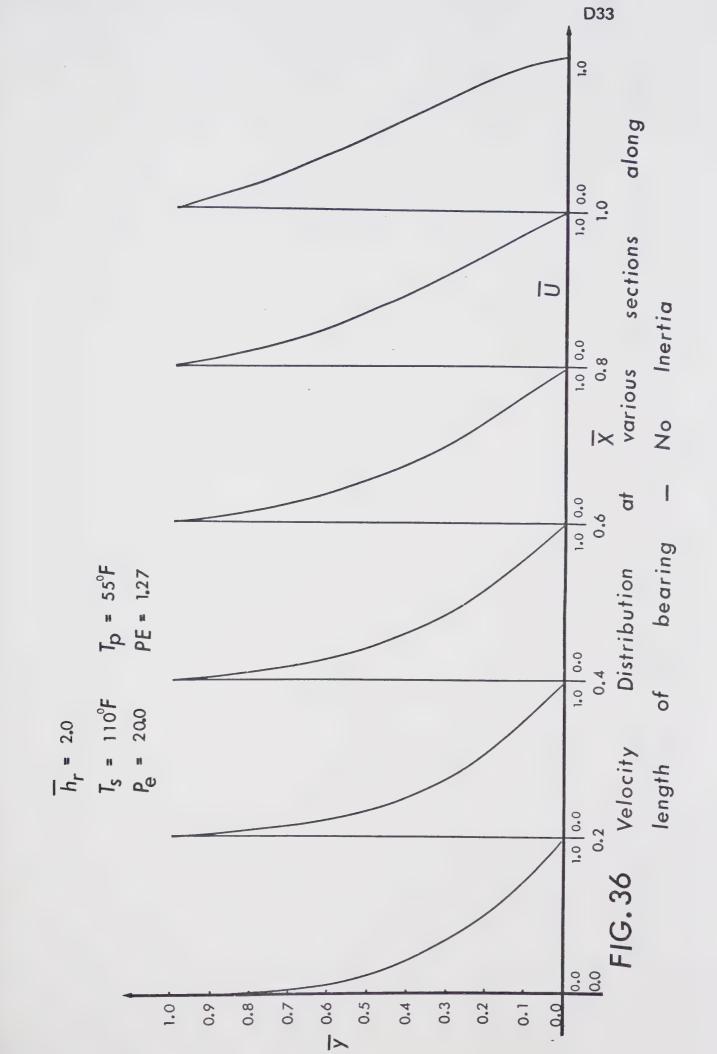
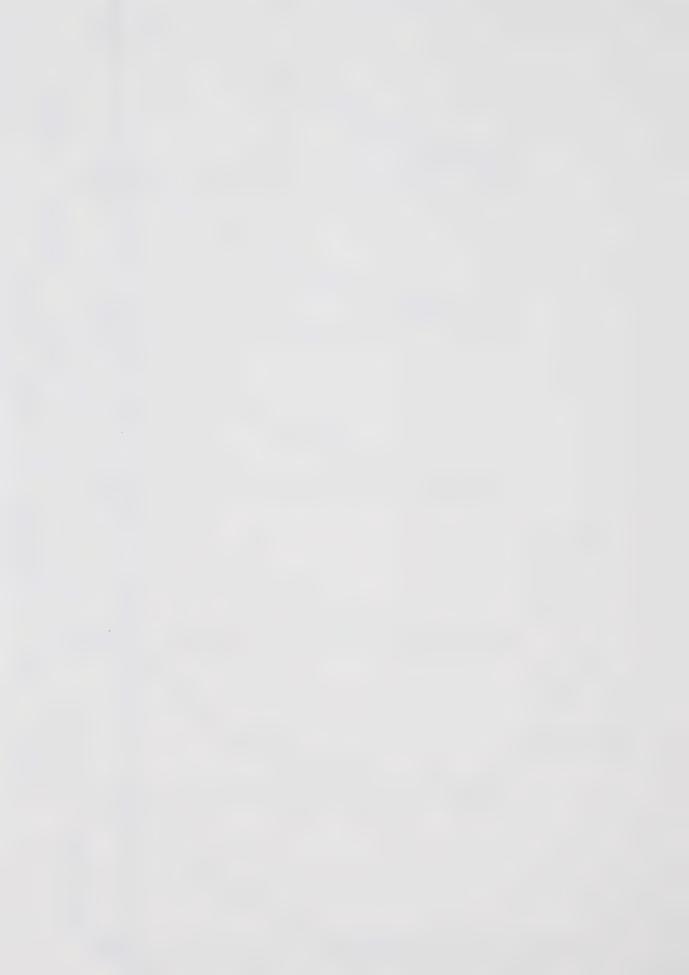
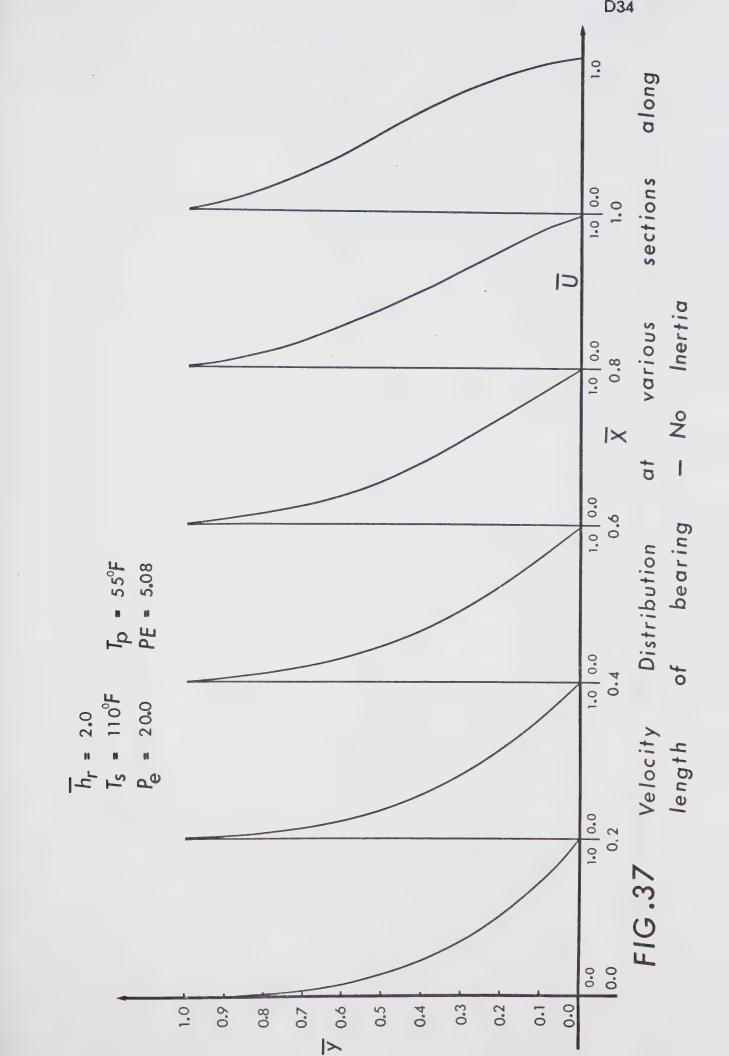


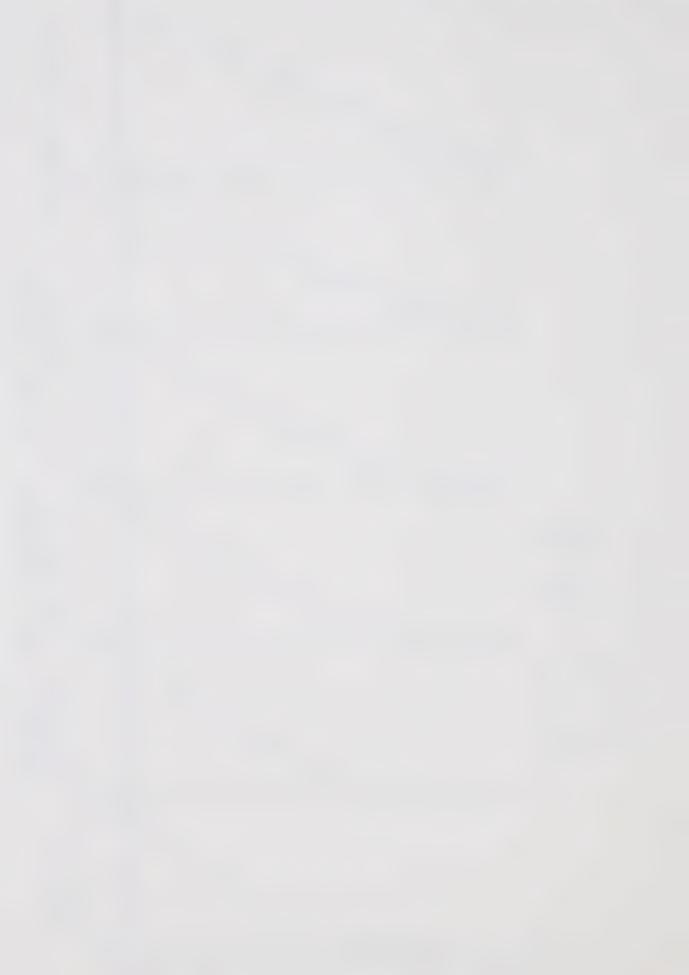
Fig. 35 Load Capacity Versus Inlet to Outlet Ratio

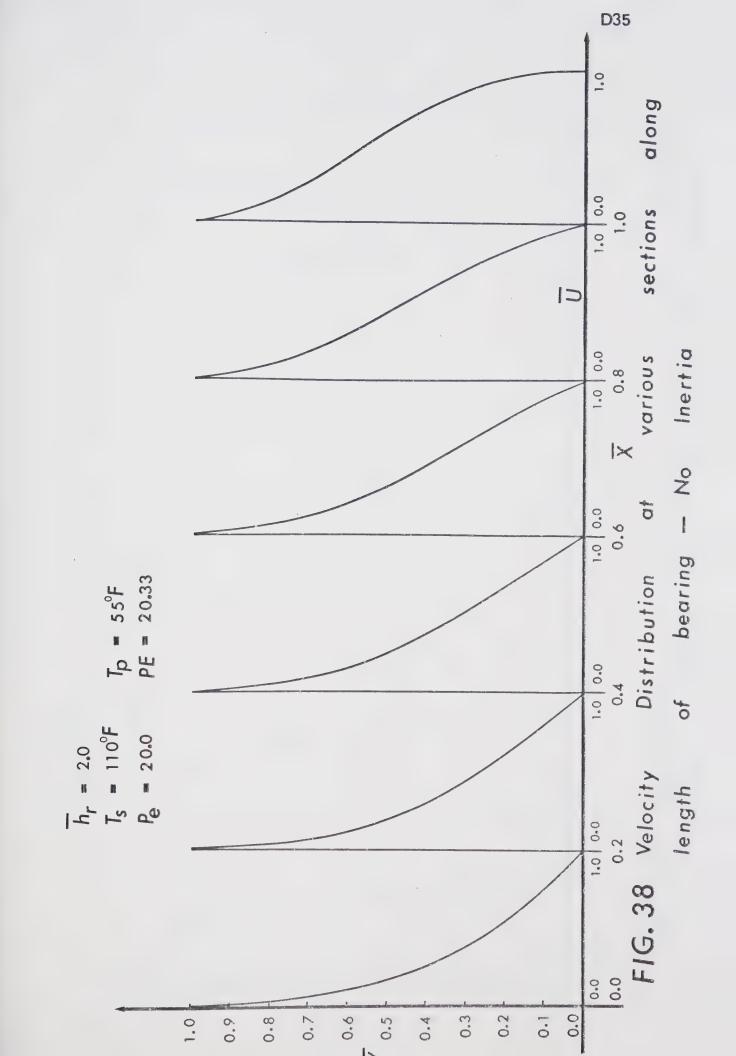


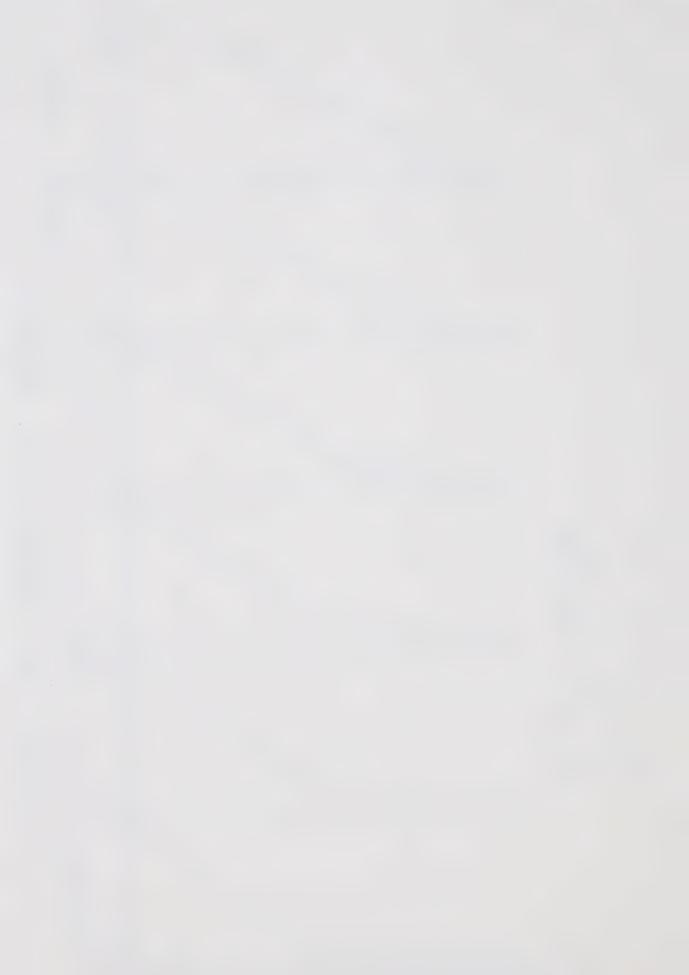


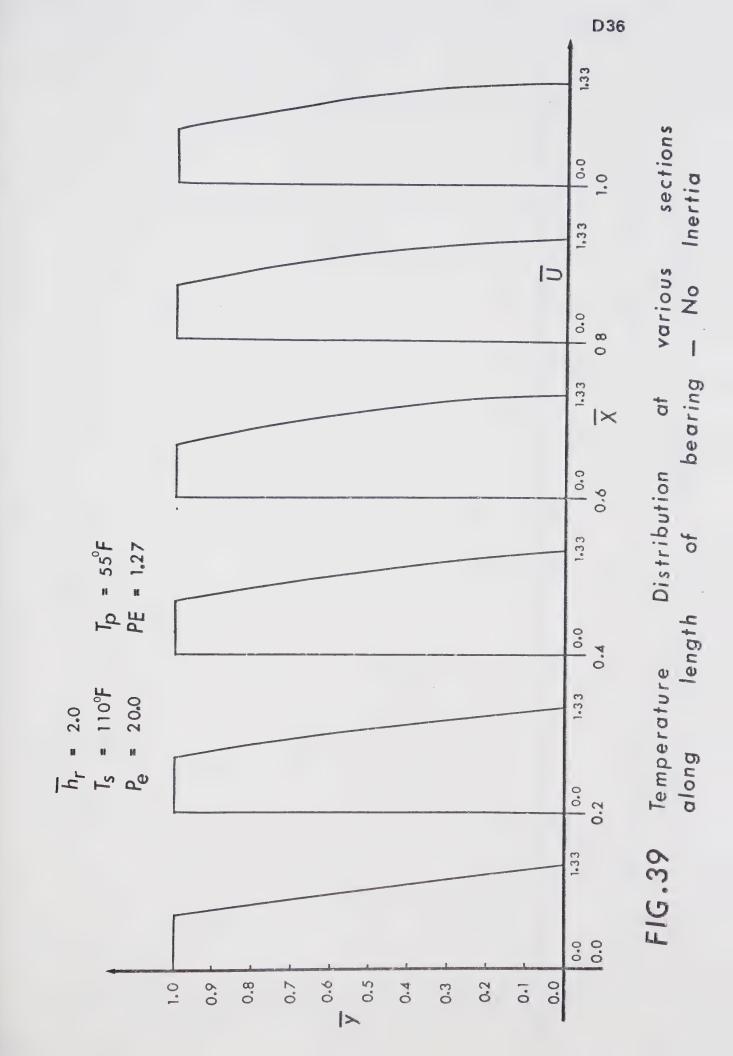


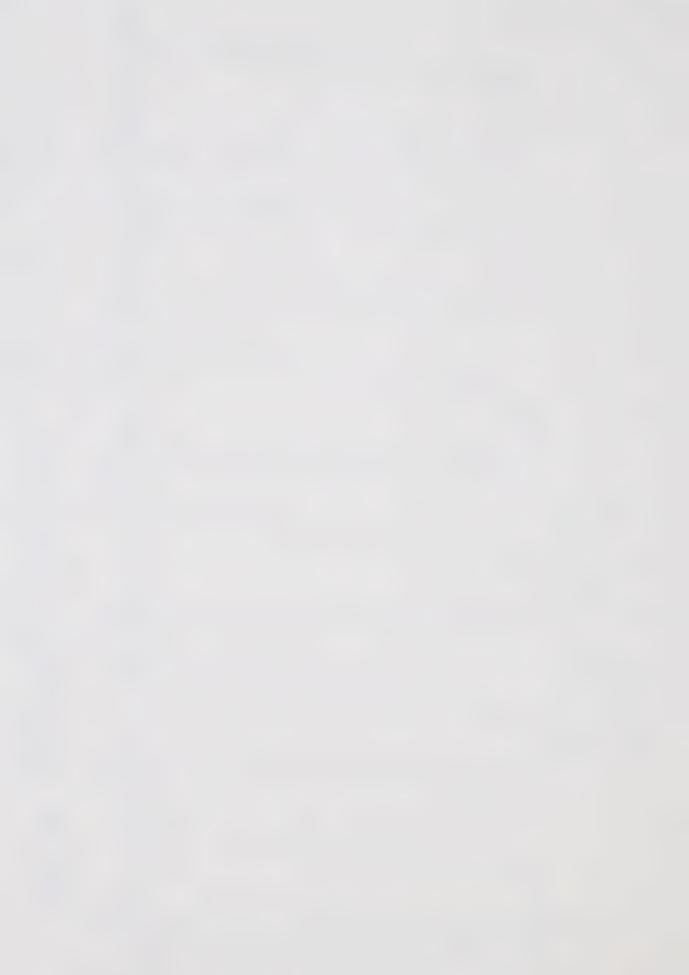


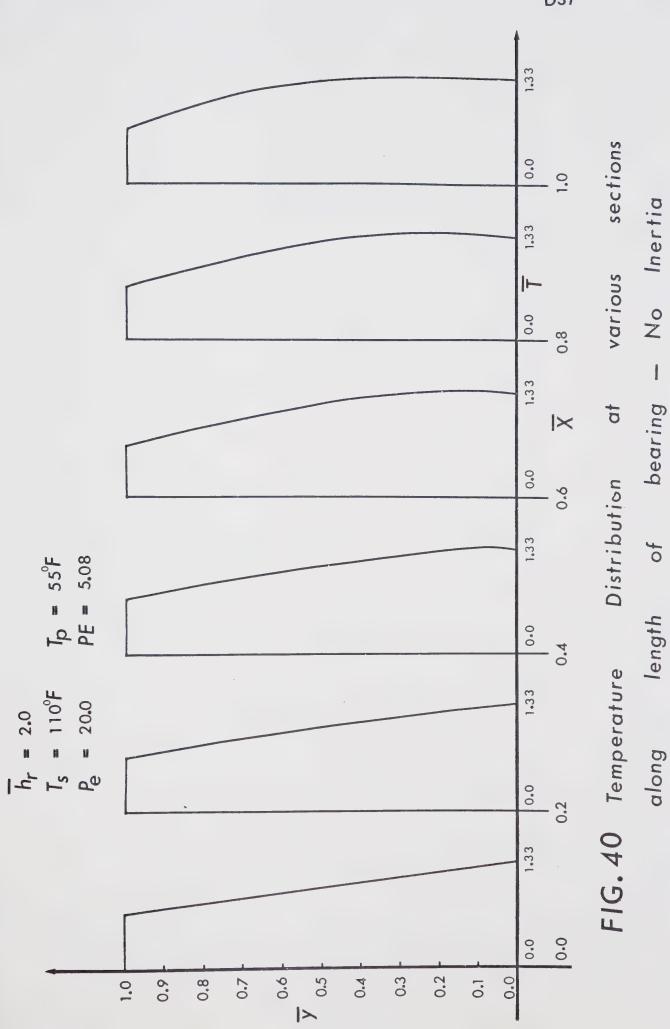


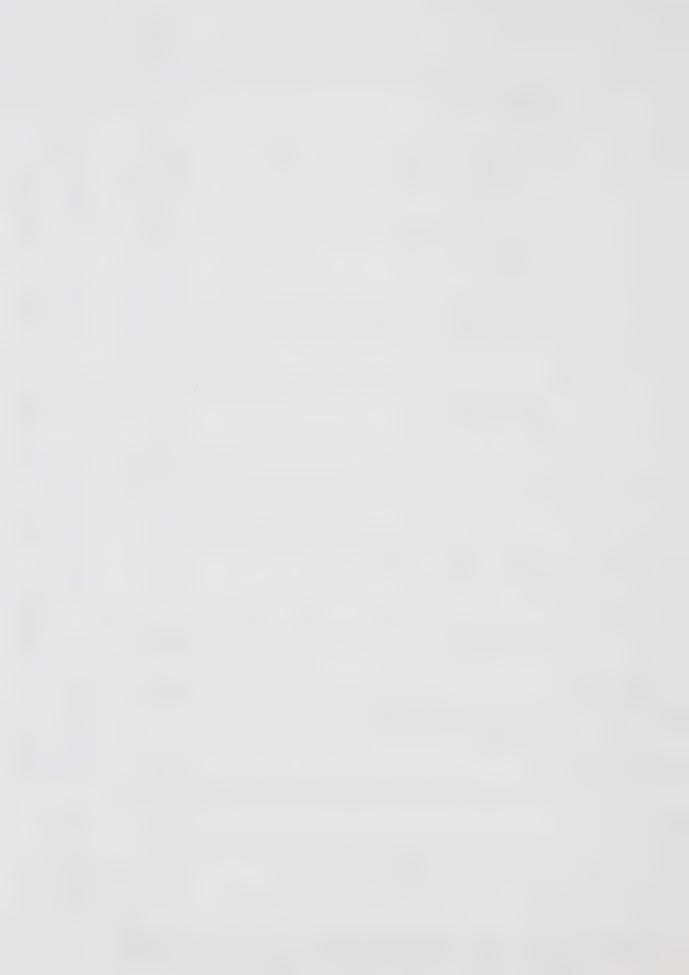


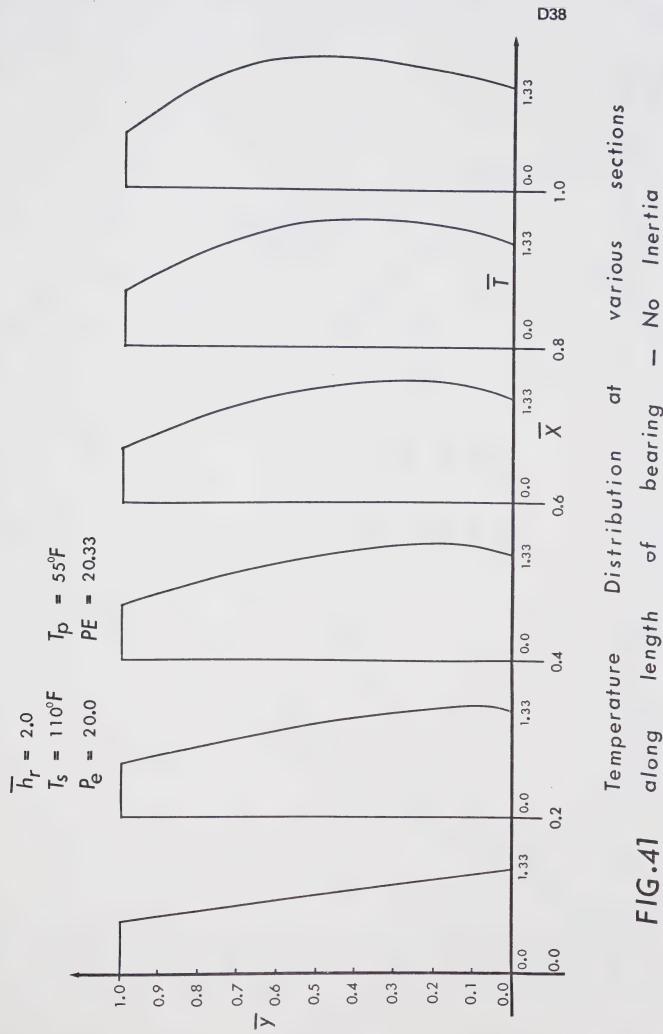








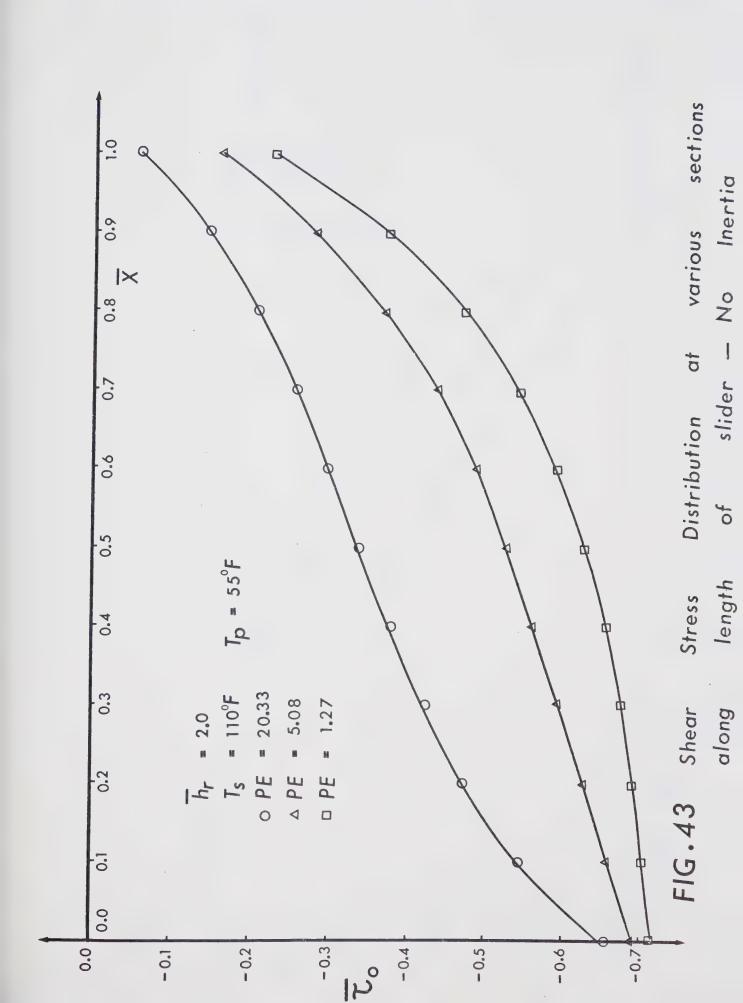


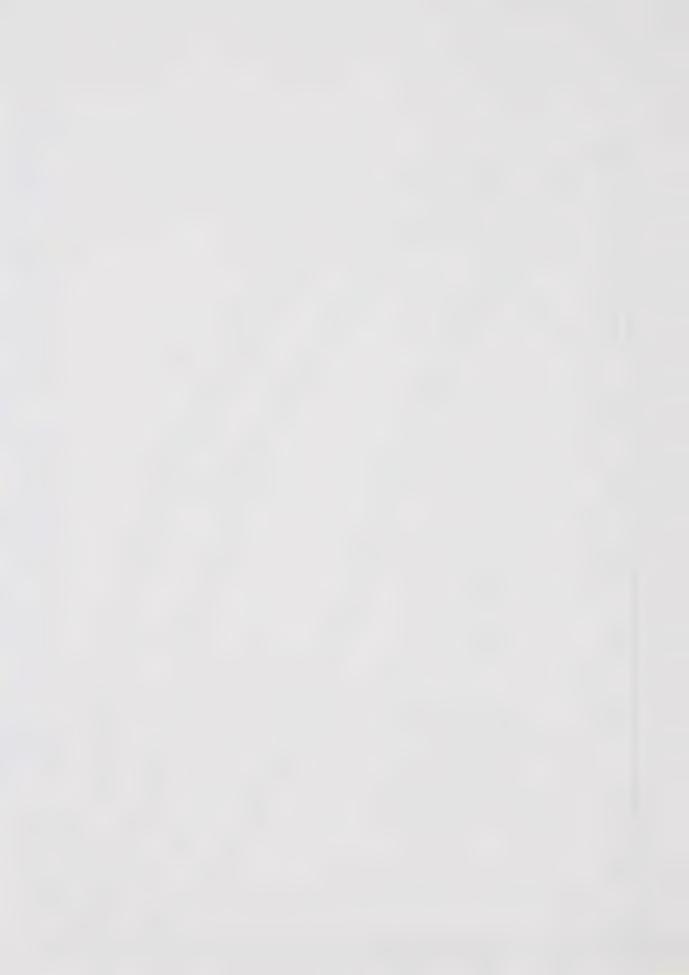


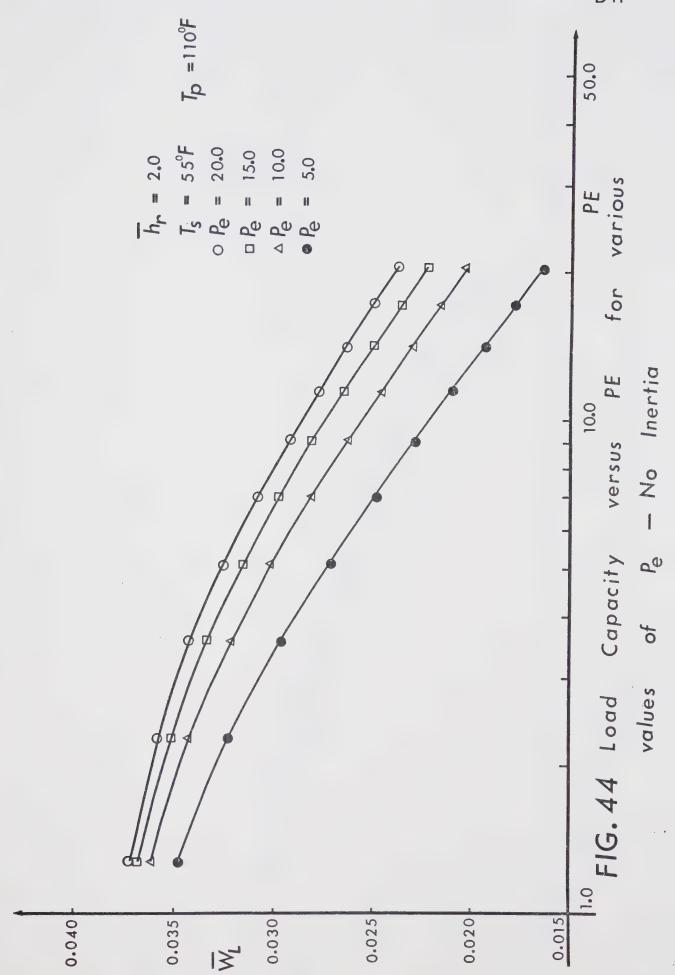
of bearing along length FIG.41

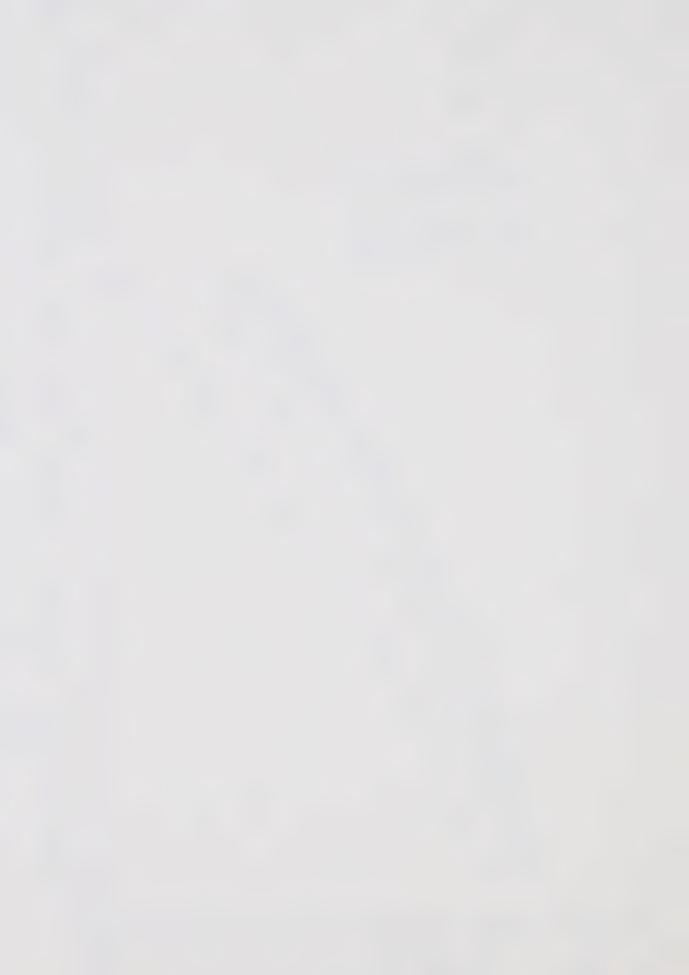


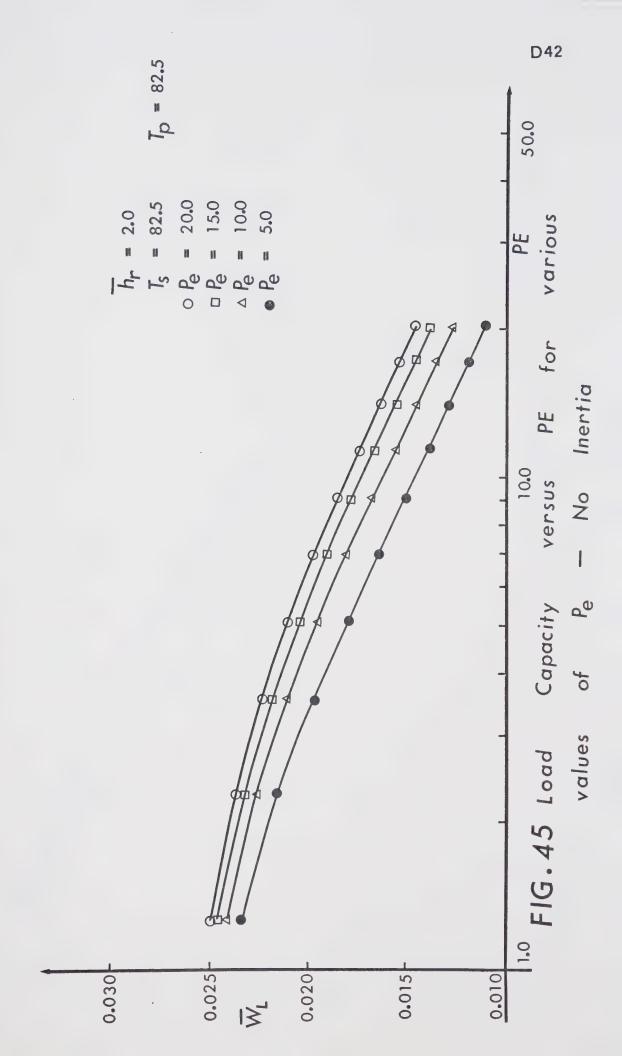


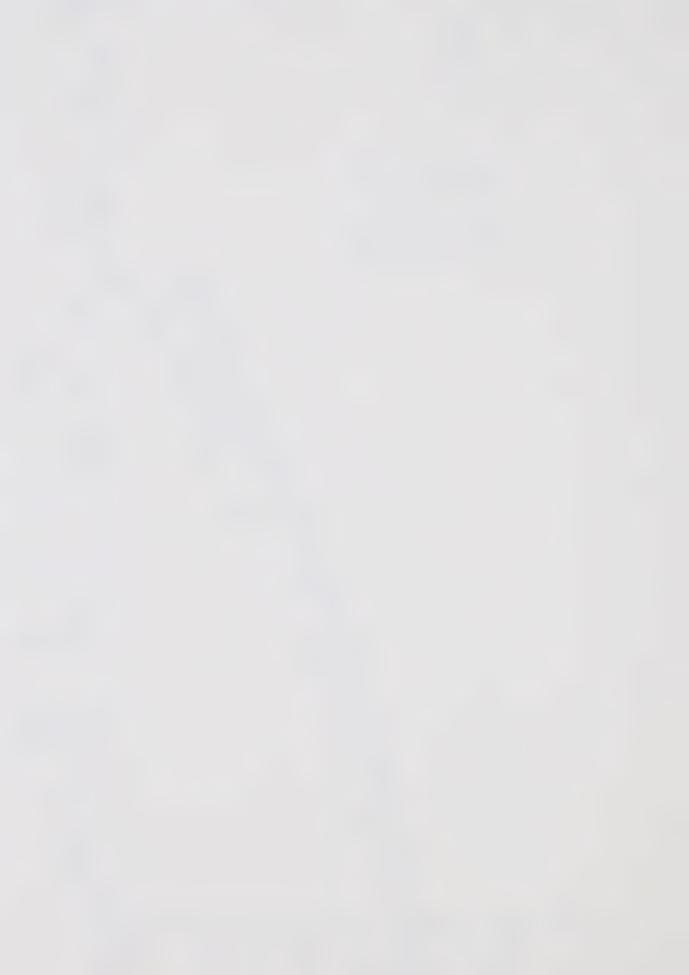


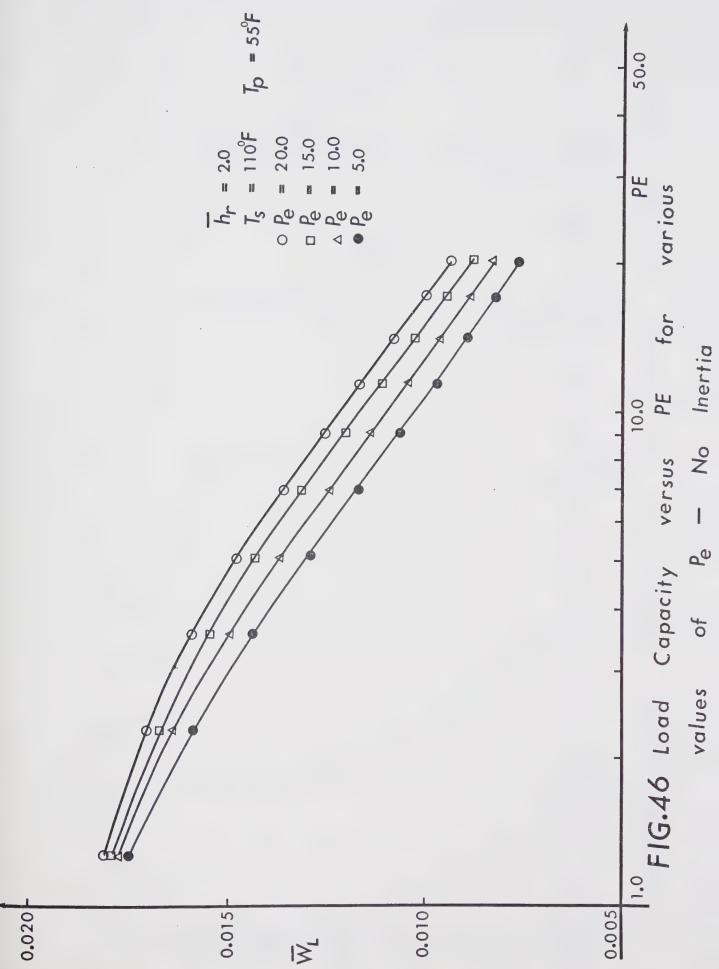


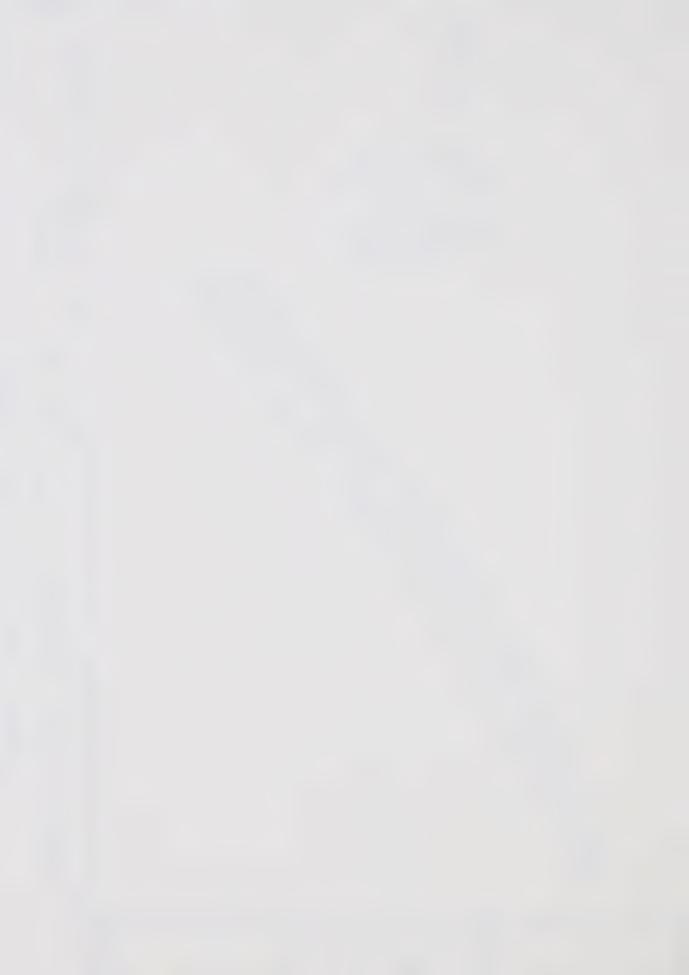


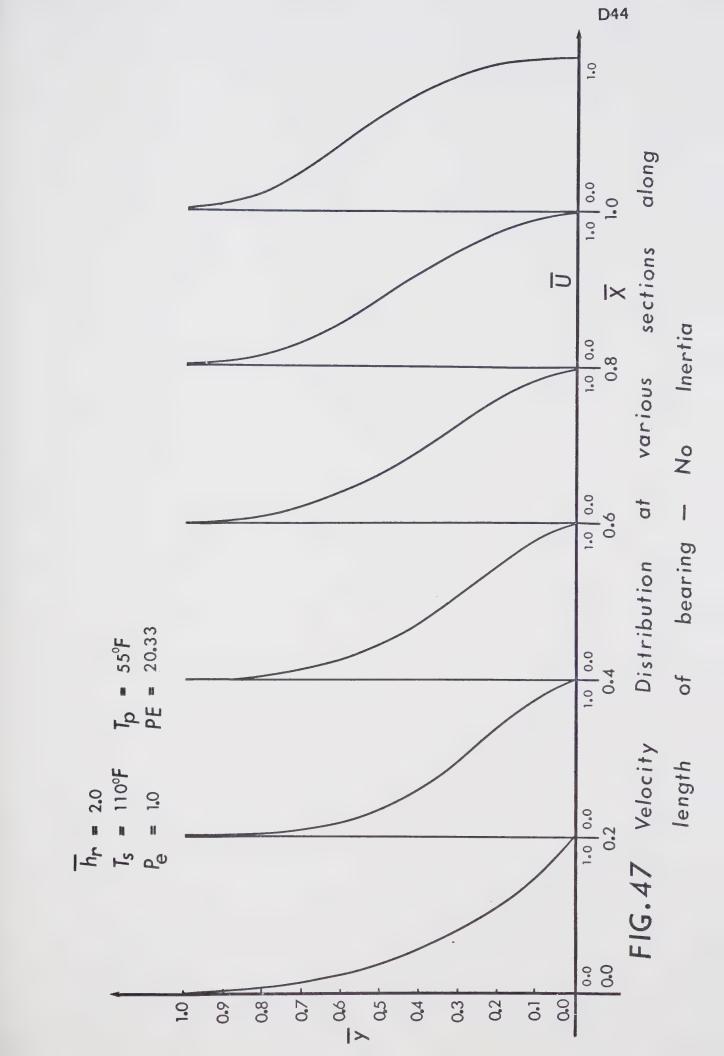


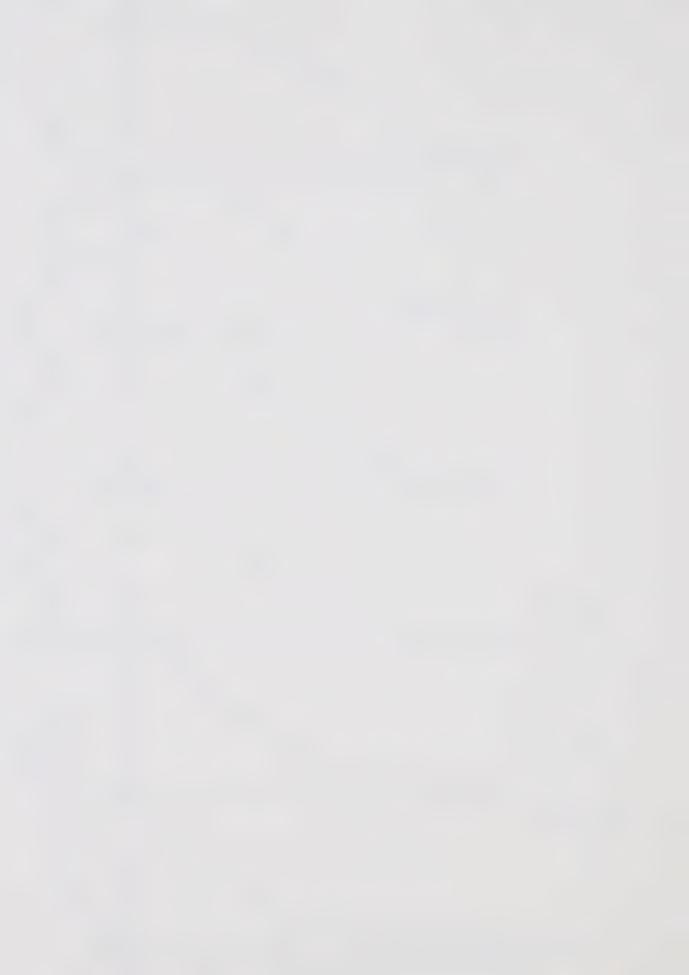


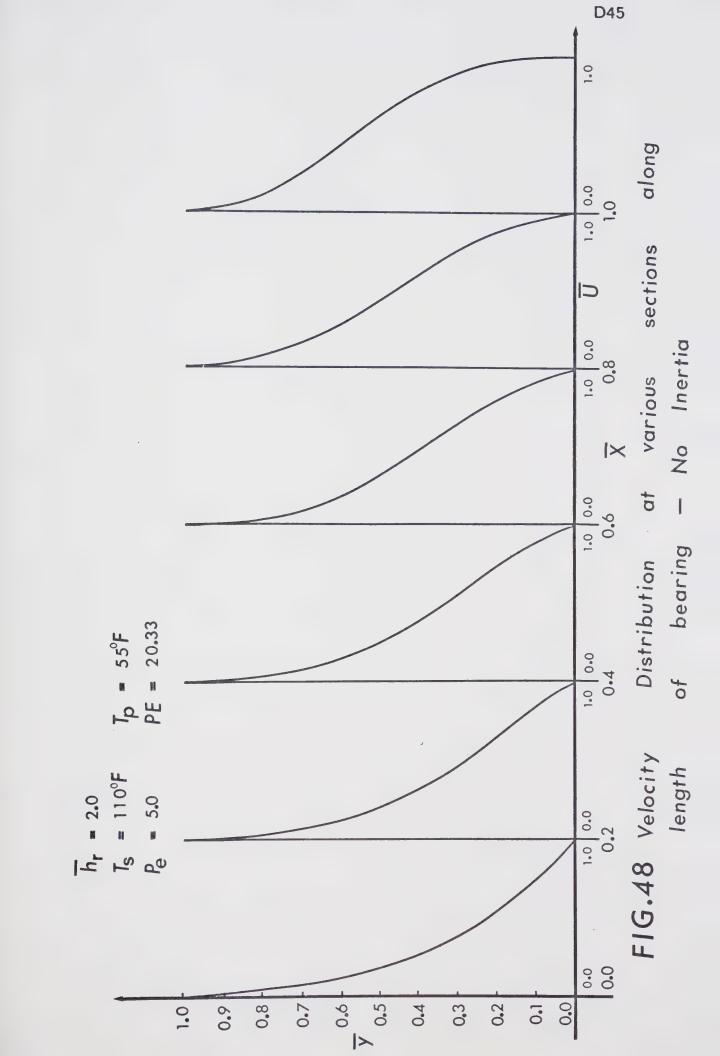


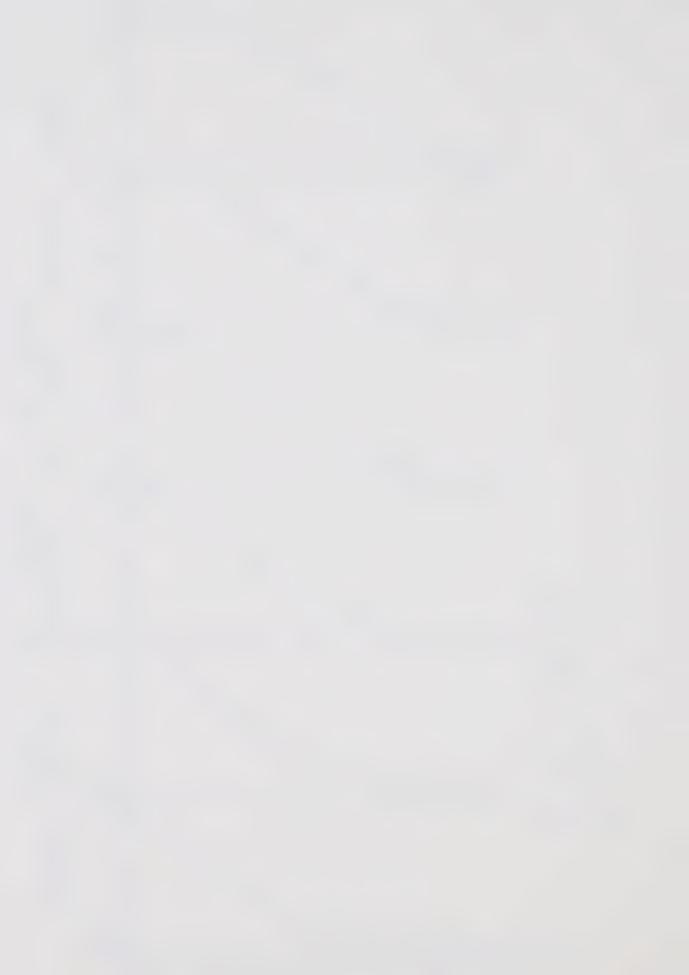


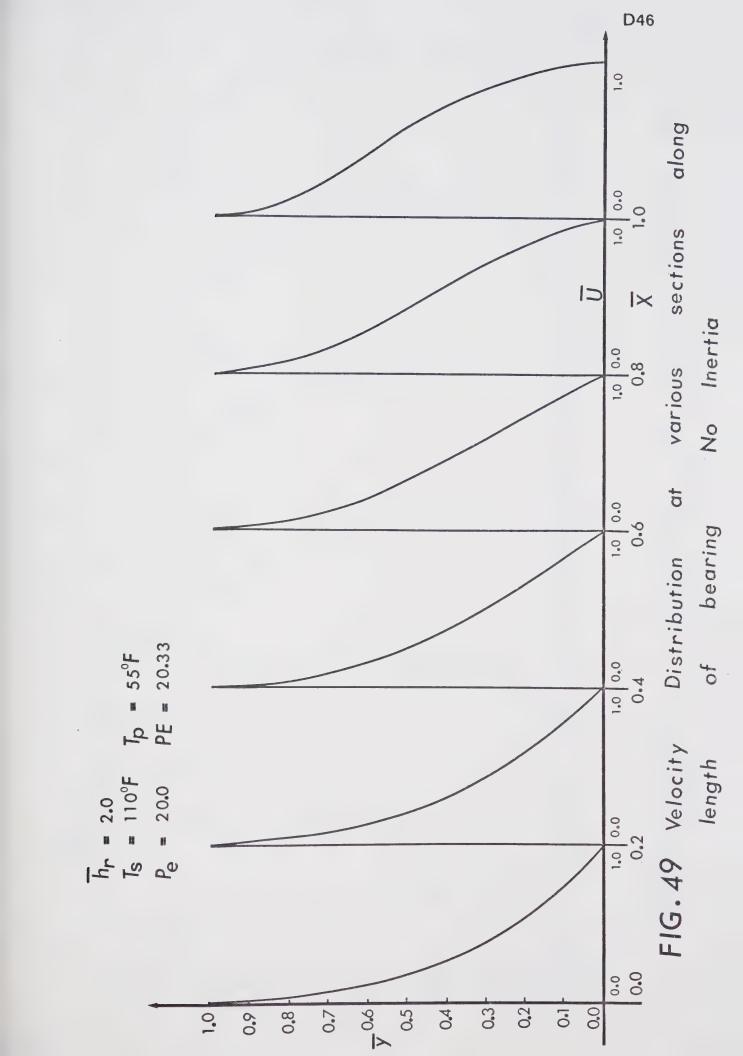


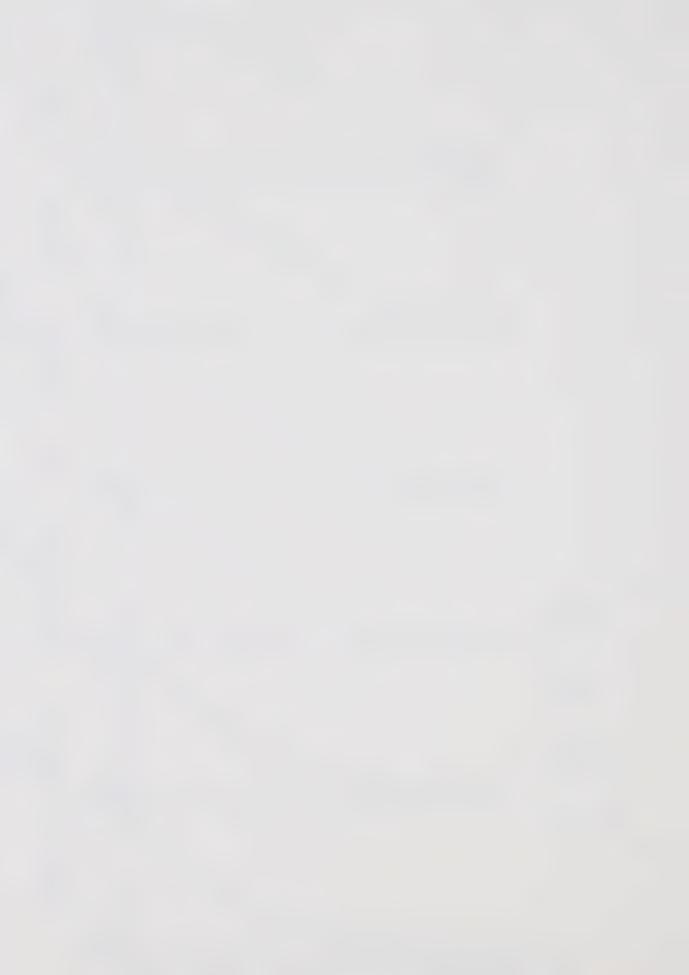


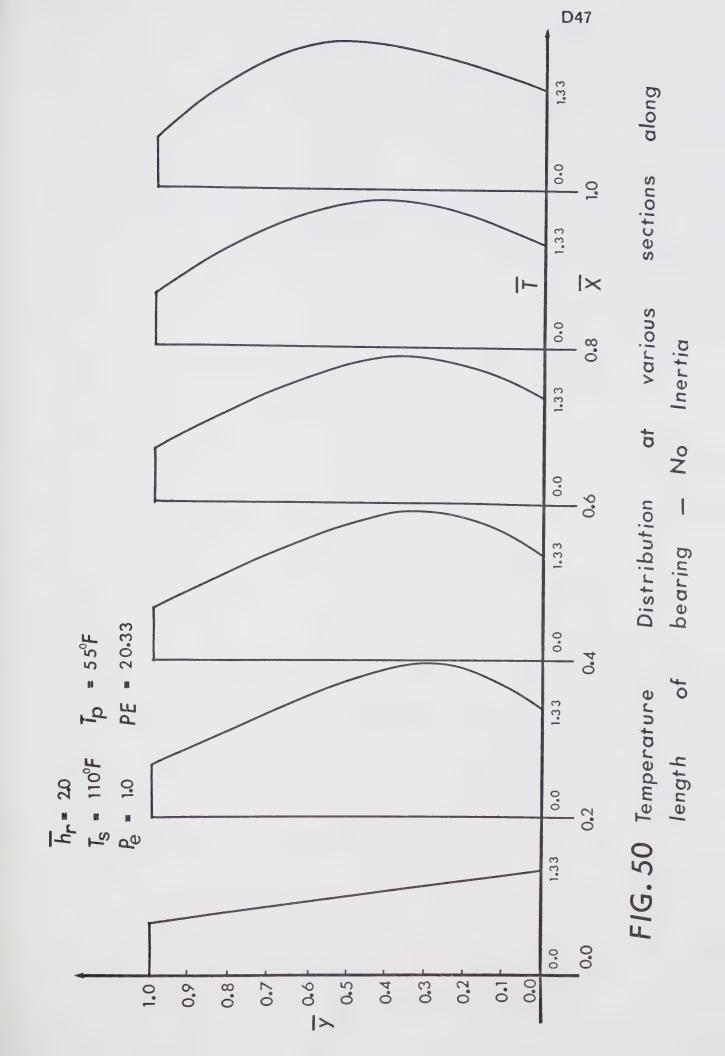


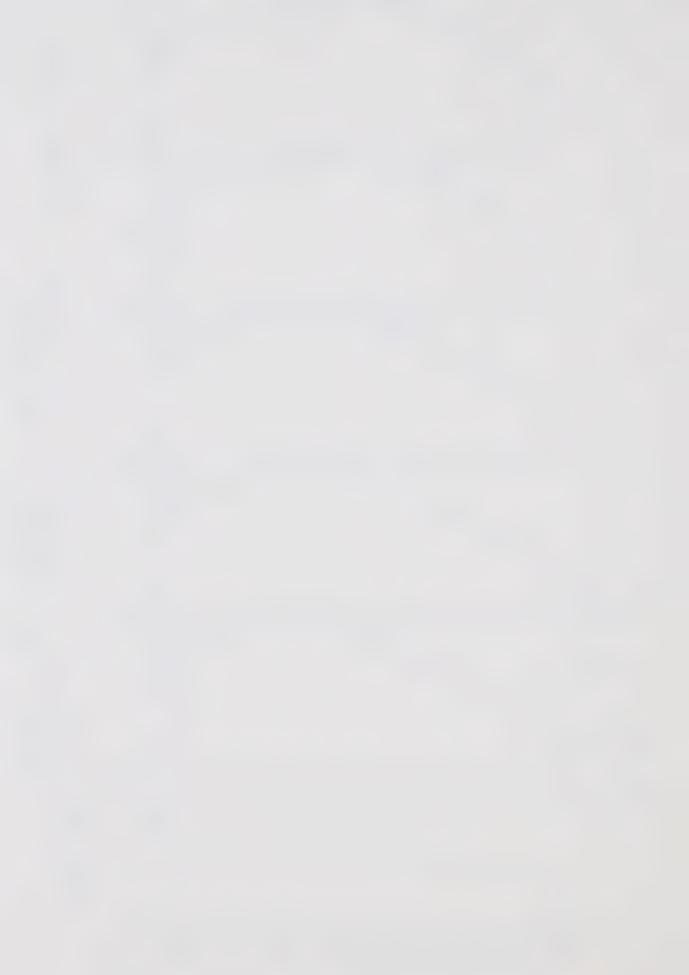


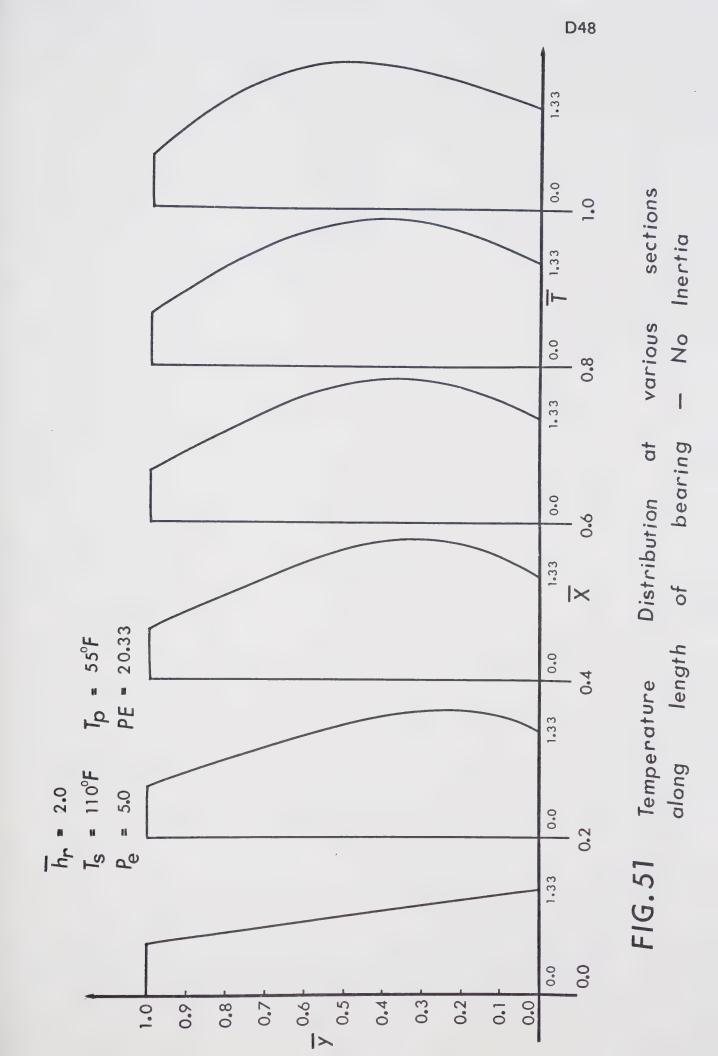


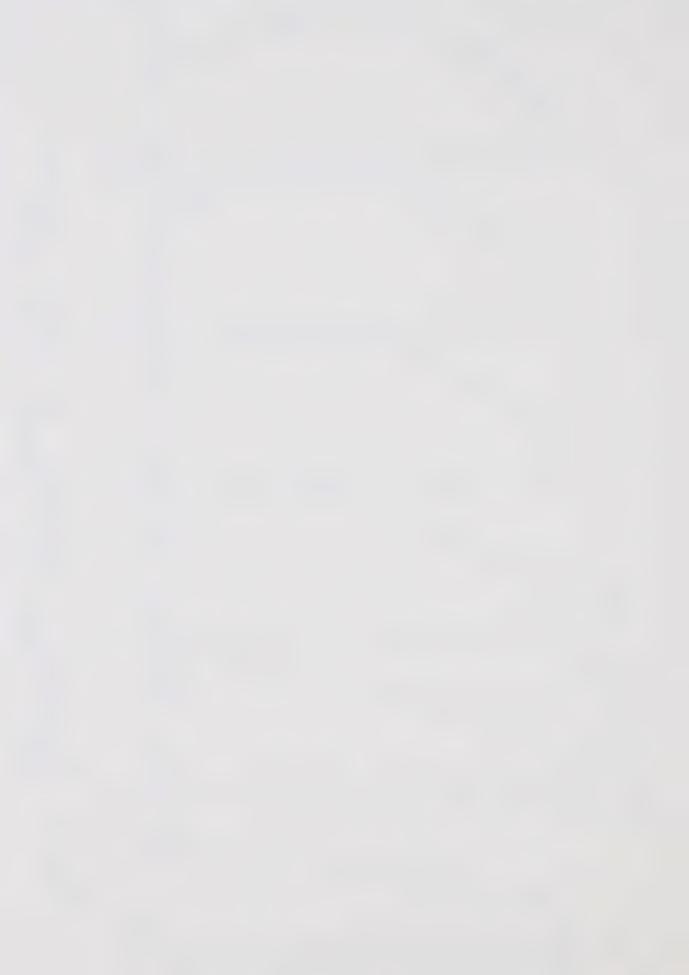


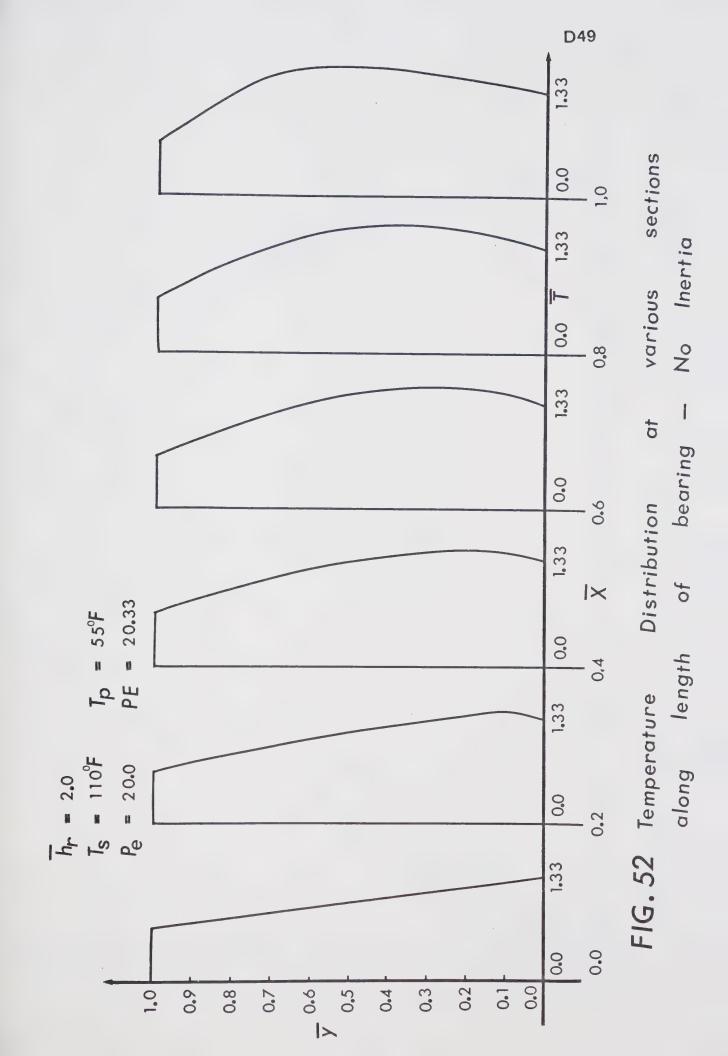


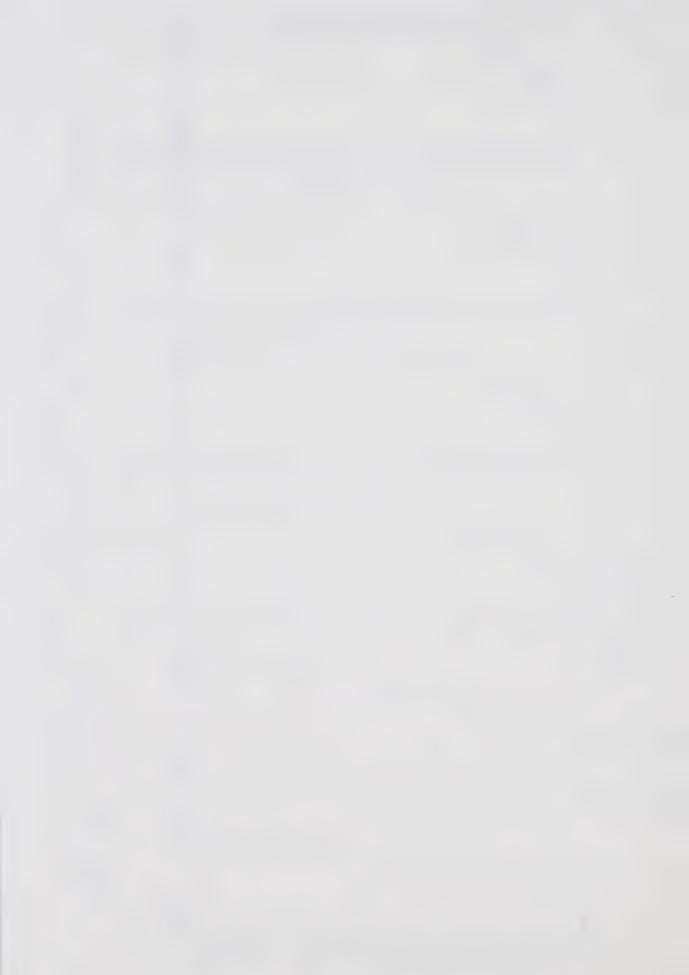


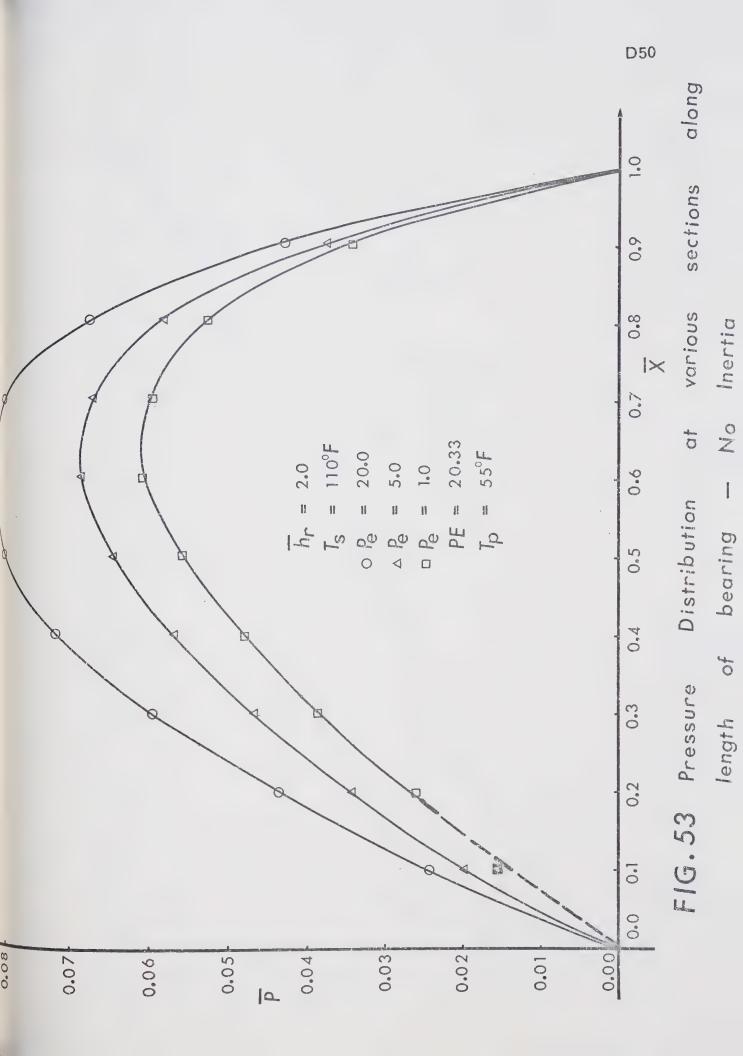


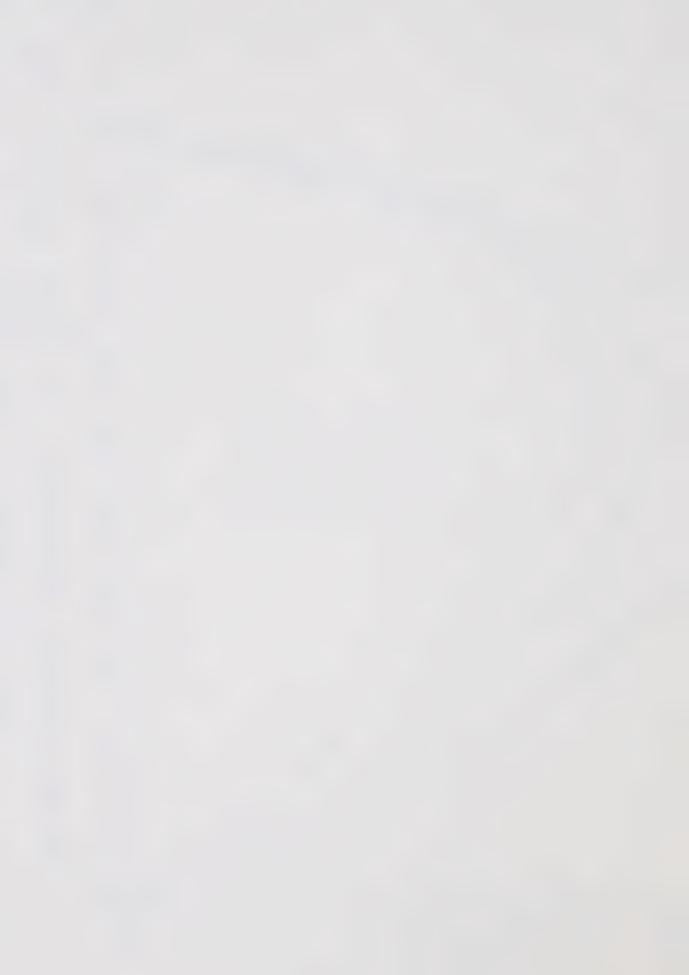


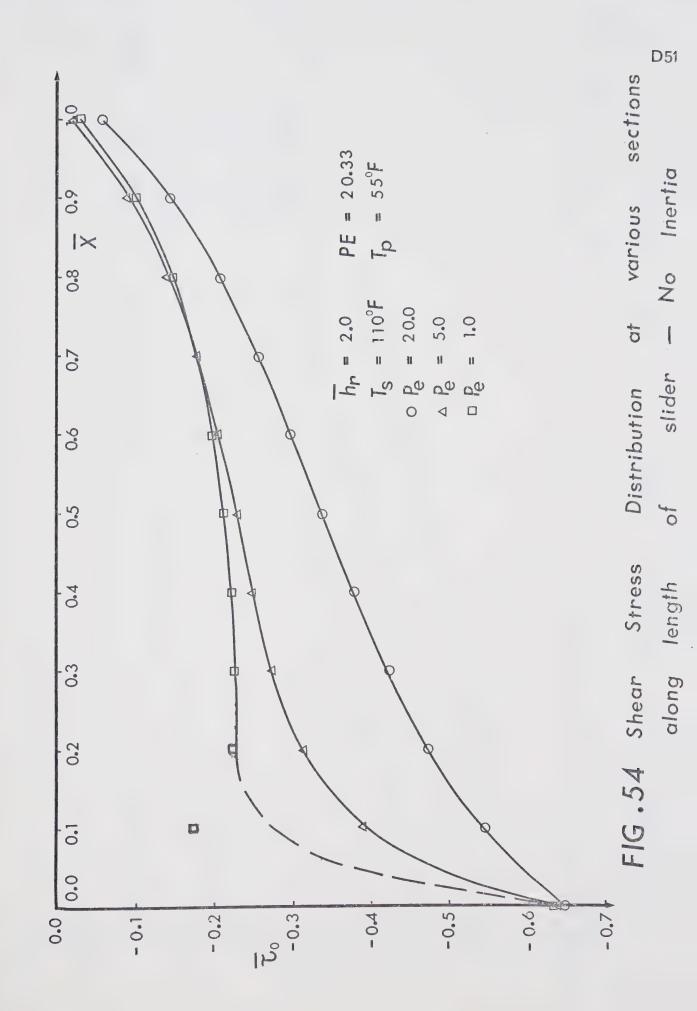


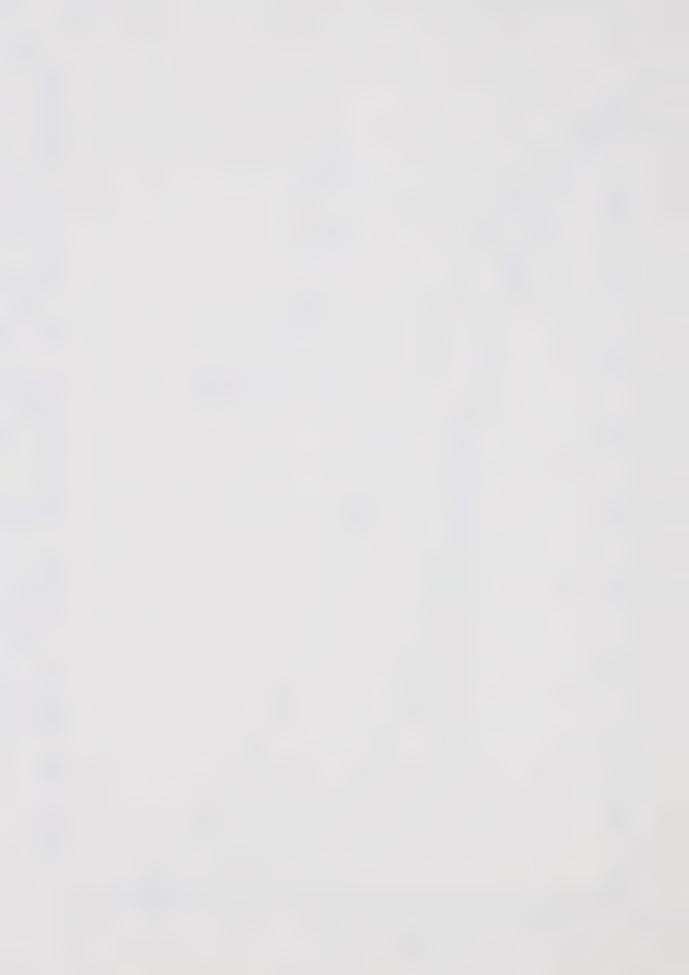


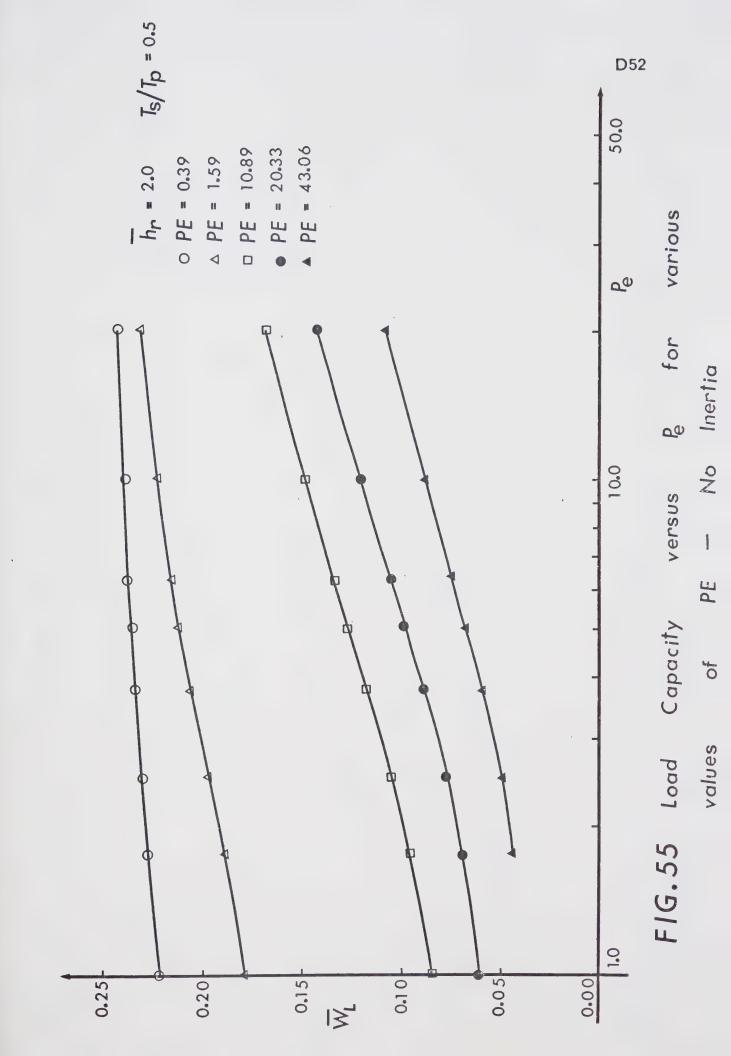


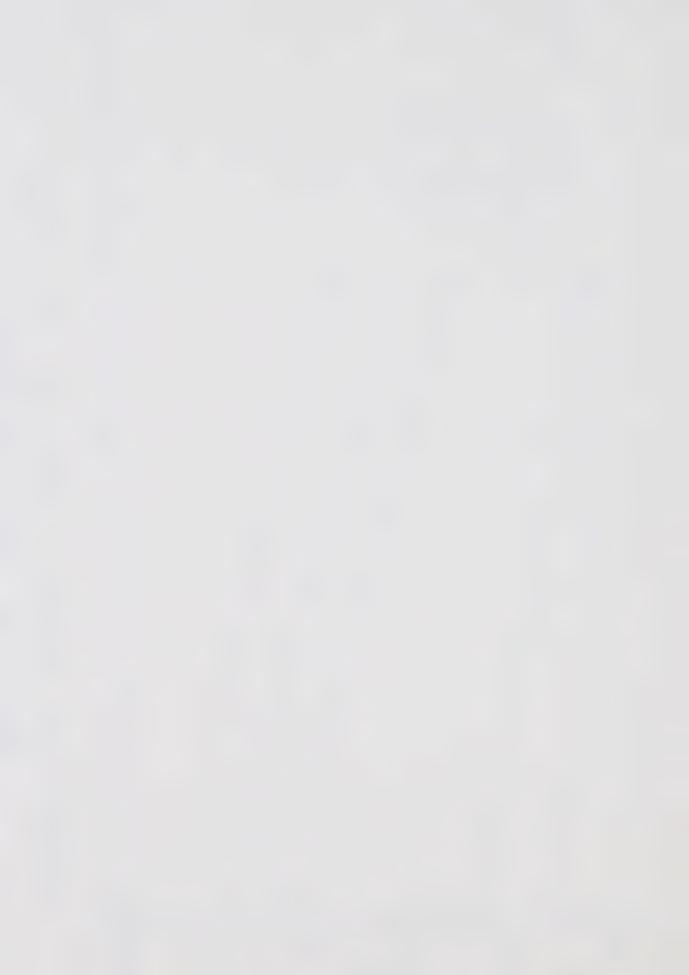


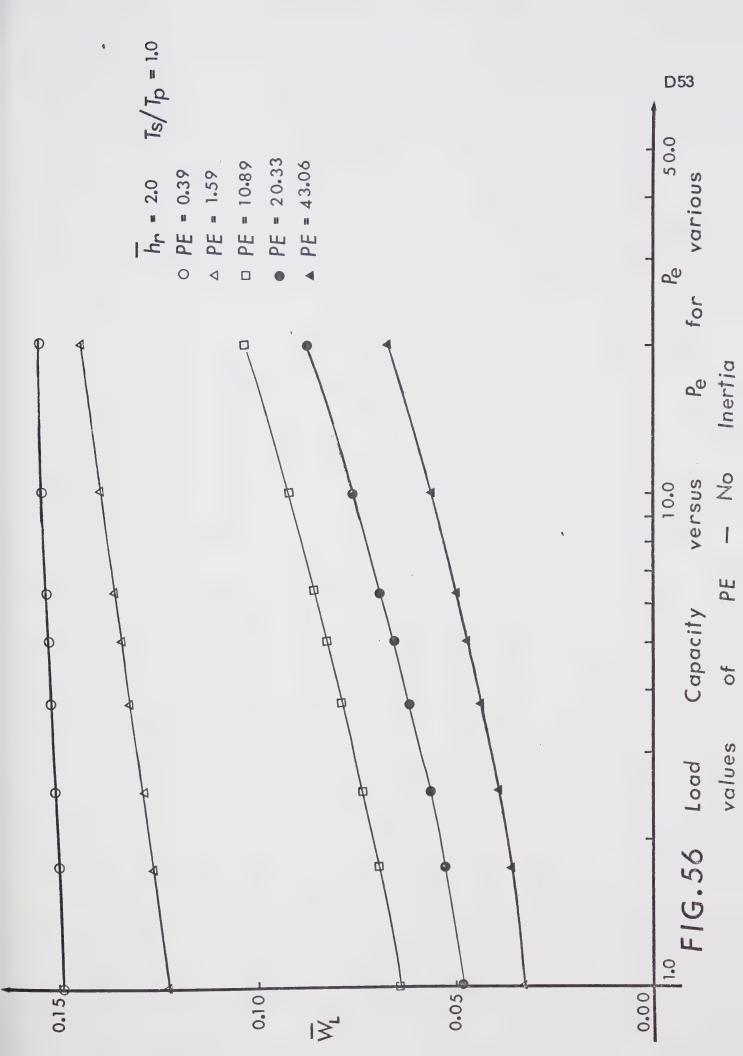


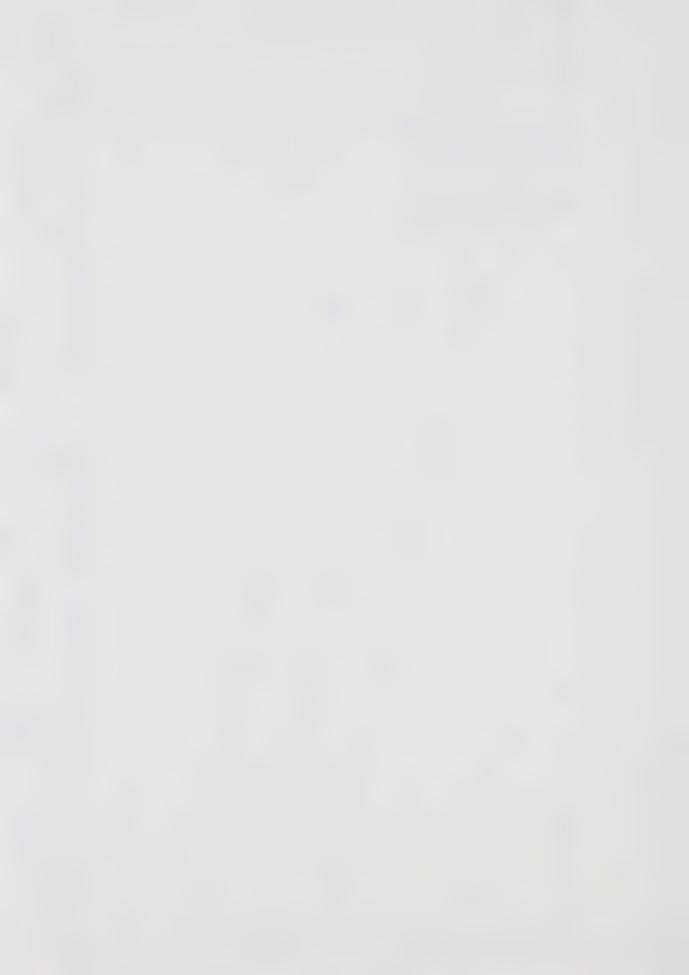


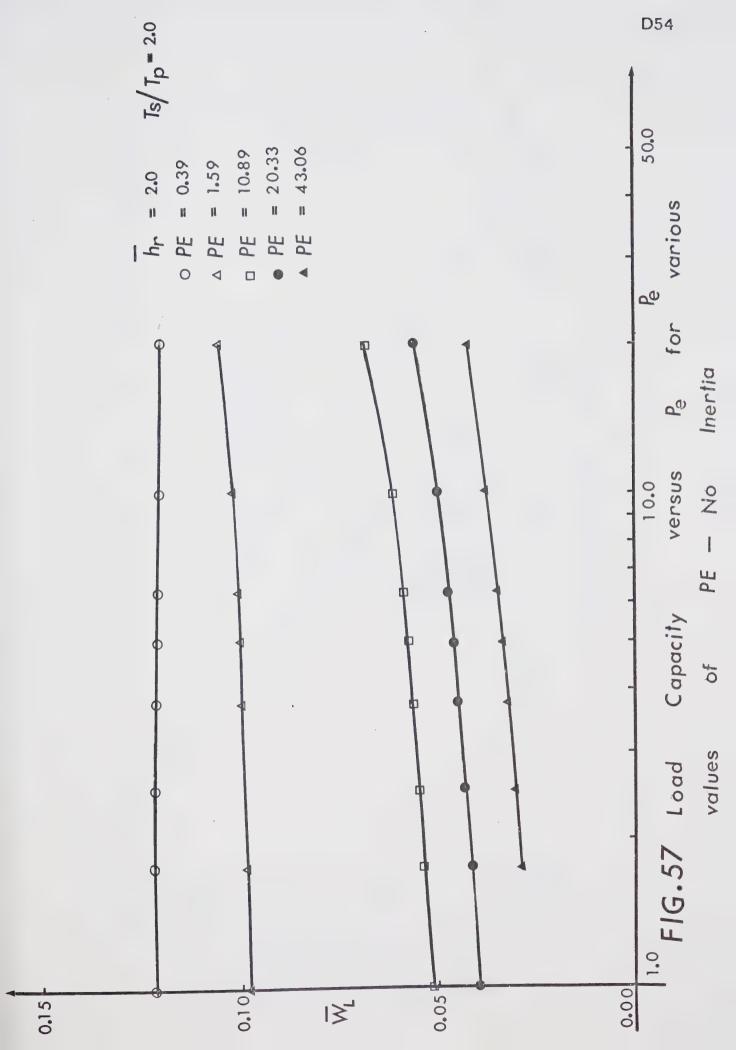




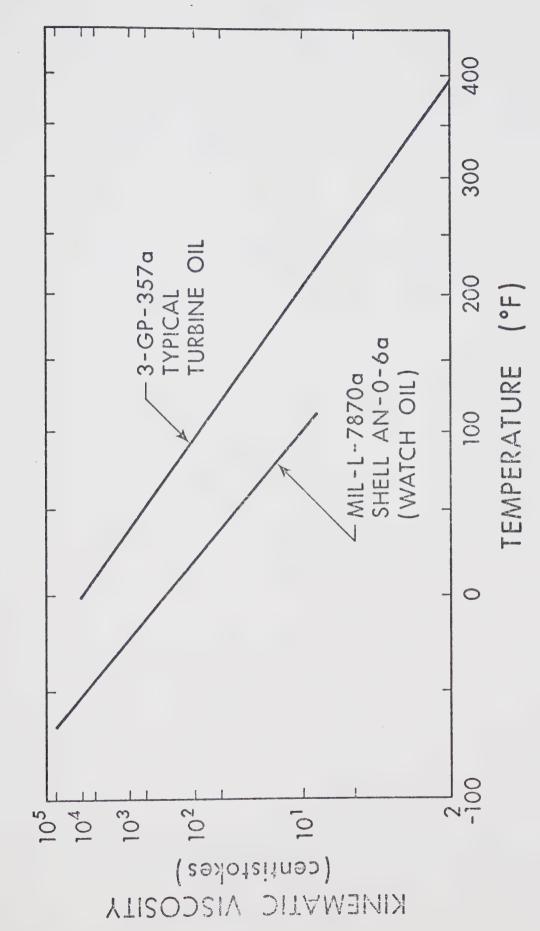




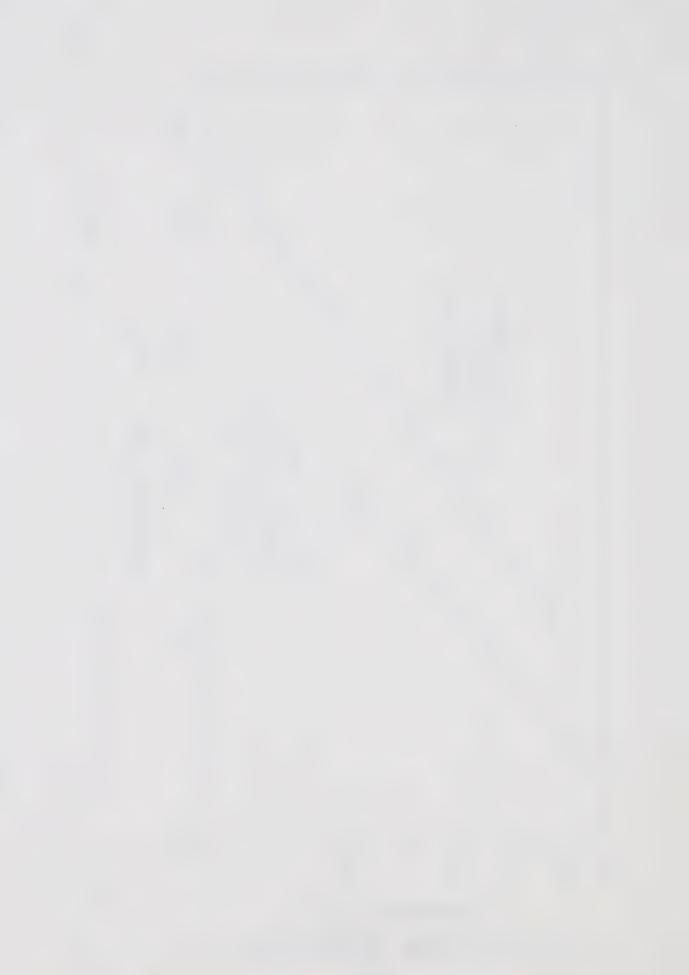








Viscosity Temperature relationships for medium and for light oil Fig. 58.



APPENDIX E
TABLES FOR CHAPTER IV



TABLE la EFFECT OF COOLING SLIDER - NO INERTIA

	T _b (°F)	09.60	84.2	0)	33.8	08.6	83.7	59.1	35.1	12.0	04.4	39.7	.07	1.7	47.89		09.2	83.7	58.4	3.1	07.8	82.7	58.0	33.8	10.6	02.9	88.2	7.0	53.18	6.3
P _e = 5.0	ΙĐ	.4130	.4183	274	.4399	.4567	.4823	.5189	.5699	.6439	.6717	.7387	.8560	.9364	.974	$P_{e} = 10.0$.4154	.4204	.4294	.4415	.4578	.4830	.5188	.5698	.6447	.6728	.7399	.8590	0.94035	. 9787
1.0	IQ	0.5280	-0.5223	-0.52603	0.5381	0.5457	0.5624	0.5828	0.6137	0.6679	0.6685	.6987	0.7329	.7376	0.7435	1.0	0.5262	0.5216	0.5263	.5401	0.5499	0.5698	0.5943	0.6315	0.6958	.6953	.7332	.7750	-0.78445	.7917
= 원전	IΜ	.1068	.1043	0.10365	.1044	.1041	.1061	.1099	.1180	.1373	.1411	.1607	.2083	.2546	.2863	PE =	.1054	.1034	.1030	.1040	.1043	.1072	.1116	.1207	.1415	.1450	.1658	.2147	0.26380	.2974
	dL/sL		. 2	0.	9.	°	0		4	-	0	∞	ů.	\sim	-2		.5	. 2	0.	9 .	<u>.</u>	0	. 7	₽.	۲.	0	∞	.5	0.30	. 2
100°F																= 100°F														
		350	\sim	0	9	m	0 1	7	4		0					·		\sim	9	9	7)	0 1	-	4	\dashv	0			30	

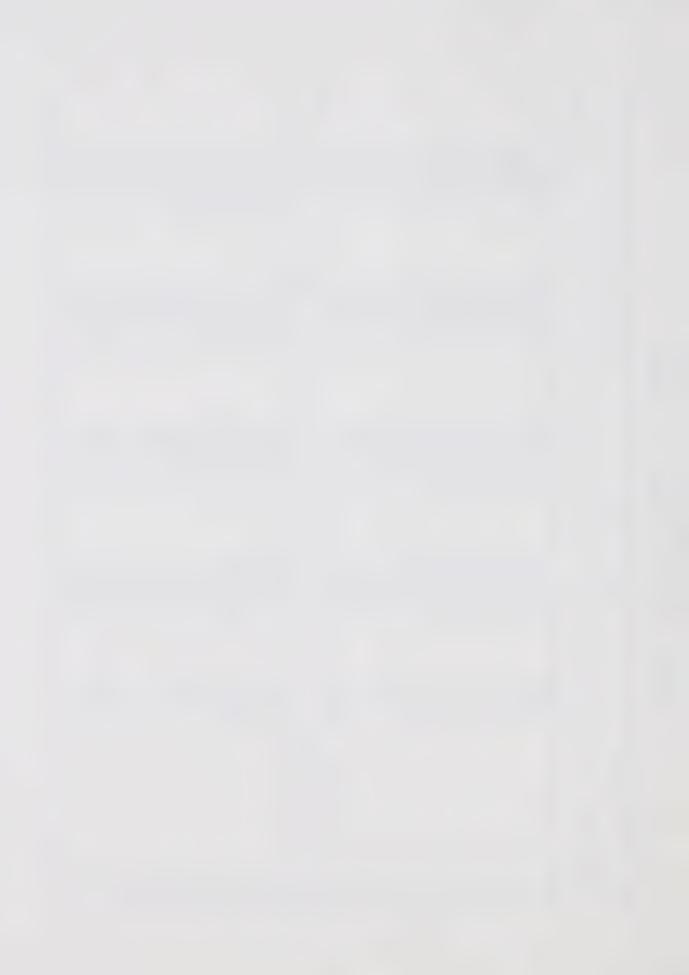
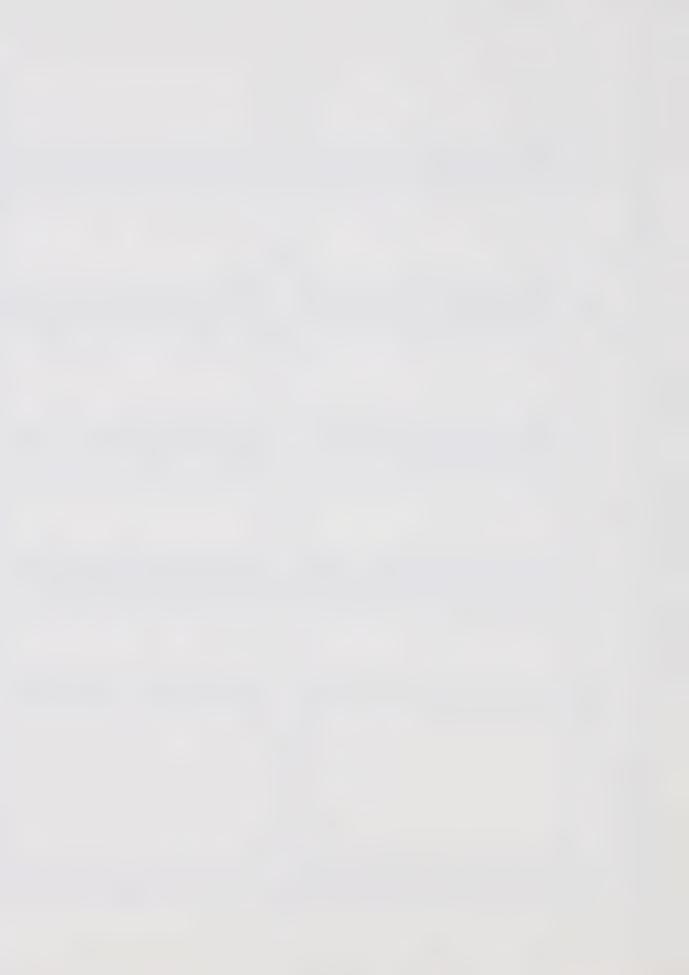


TABLE 1b EFFECT OF HEATING PAD - NO INERTIA

(i) $T_{S} = 100^{\circ}F$		PE = 1.	0	P _e = 5.0	
T _D (°F)	Ts/Tp	IΆ	10	υ i⇒	T _b (°F)
0	0.	.0922	0.4649	3855	9
2	5	.0927	0.4718	3928	
	0.	.0936	0.4826	4031	
0	\sim	.0960	0.5005	4211	
36.4	2.75	0.10037	-0.52948	0.44428	
0	0	.1075	0.5723	4954	9
∞	.2	.1267	0.6415	.6066	8 . 7
10.	0	.1505	0.6923	.7005	07.5
0	. 7	.1727	0.7036	.7775	17.0
70.		.1970	0.7216	.8311	27.1
00		.2218	0.7406	.8726	37.2
30.	. 4	.2447	0.7556	.9014	47.3
0.09	\sim	.2662	0.7744	.9205	57.5
9	~	.2820	0.7818	.9351	67.4
20.	ς,	.2989	0.7967	.9458	77.5
50.	2.	.3164	0.8184	.9524	7.5
(ii) $T_S = 100$ °F		PE = 1.	0		
0	0	.0907	0.4600	.3887	6.7
	.5	.0910	0.4670	.3963	6.9
υ.	0.	.0929	0.4792	.4057	7.3
0	~	.0955	.4990	.4233	7.9
9	. 7	.1004	0.5307	.4460	φ
	0	.1086	0.5798	.4961	1.1
0 0	. 2	.1298	0.6630	.6068	7.6
10 1	0	.1553	0.7245	.7006	05.9
40.	. 7	.1782	0.7417	.7797	14.9
70.		.2039	0.7643	.8349	24.5
00	.5	.2303	0.7878	.8772	34.0
30.	φ.	.2545	0.8057	.9067	43.7
90.	ς,	.2782	0.8275	.9268	53.3
90	ς,	. 2955	.8375	.9413	62.7
320.0	0.31	0.31366	-0.85465	0.95222	172.24
20.	7	.3336	8807	.9593	81.6



EFFECT OF COOLING SLIDER AND HEATING PAD - NO INERTIA TABLE 1c

	T, (°F)	200) [] (-) [) \ - () \ - ())) ! !	ייני ייני		0 0 0	82.8	72.3	53.0	9.8	15.0	135.46		62 4	1 C	43.0	33.7	24.6	07.7	92.8	80.2	69.2	59.4	50.05	40.5	130.39
P = 5.0	U I∌-	3540	3748	3937	4175	4448	5086	00	.6718	.7608	.8440	.9151	.9710	127	P _e = 10.0	3581	3782	0.39662	.4198	.4462	.5089	.5848	.6723	.7629	.8482	.9210	.9776	.0188
0	IQ	0.4437	0.4682	0.4880	0.5114	0.5350	0.5815	-0.62684	0.6702	0.7042	0.7329	0.7613	0.7882	0.8189	0	0.4374	0.4634	-0.48510	0.5108	0.5373	.5916	0.6465	0.6973	.7405	.7769	.8136	.8503	.8933
PE = 1.	ΙZ	.0982	.09922	.0998	.1014	.1034	.1097	0.12183	.1411	.1682	.2062	.2572	.3187	.3911	PE = 1.	.0953	.0969	0.09823	.1005	.1033	.1112	.1248	.1452	.1732	.2134	.2682	.3371	.4211
	TS/Tp	0	.5	9.	0.	.5	∞	1.33	0	. 7	. 21	. 4		긔	50°F	0	.5	3.67	0.	.5	00	.	0		. 2	4	2	
(F)	о О	0	3.6	5.0	7.5	000	25.	150.0	75.	00	25.	LO I	/5	00	+ H + H	0.0	3.6	75.00	87.5	00	٠ س	50	75.	000	25.	50.	75.	0
j. j	F4 0	0	86.	1	9	2	25.	200.0	ر ر ر ر	U C II	25.	00.0	٠ ر		(ii) T _S	0	86	275.0	62.	500	22.0	1 C	75.	500	25.	0 0	ر. د	0

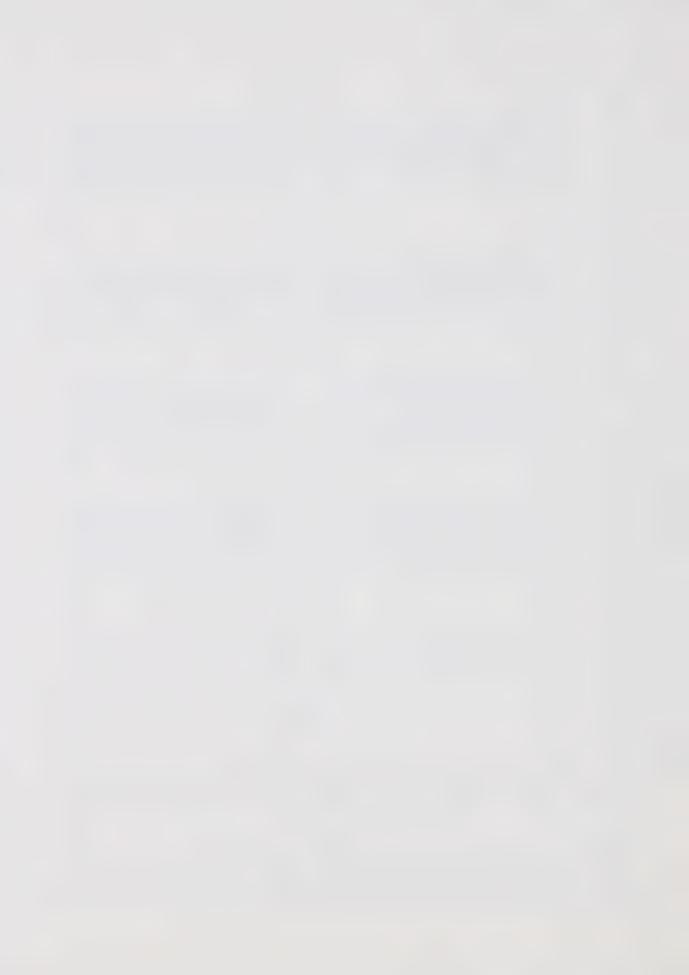


TABLE 1d

EFFECT OF LUBRICANT TEMP ON LOAD CAPACITY

T _D (°F)	321.09 275.46 229.59 213.77 183.74 137.70 91.63 68.59	262.50 225.00 171.39 159.62 137.20 102.88 51.41 34.17
υ Hel	0.50617 0.49709 0.49040 0.48231 0.49547 0.51310	0.84798 0.85768 0.86622 0.87073 0.87267 0.87267 0.83610
IΜ	0.11465 0.11231 0.10817 0.10797 0.10618 0.10445 0.11285	0.22010 0.22318 0.22167 0.22457 0.22185 0.2185 0.20830 0.20279 0.18825
T _S + T _D (°F)	525 345 375 300 1150 75.5	525 450 375 300 1120 75
T _p (°F)	175 150 125 116.67 100 75 50 37.5	350 300 250 233.34 200 150 150 50
T _S (°F)	350 300 250 233.34 150 100 50	175 150 125 116.67 100 75 50 37.5

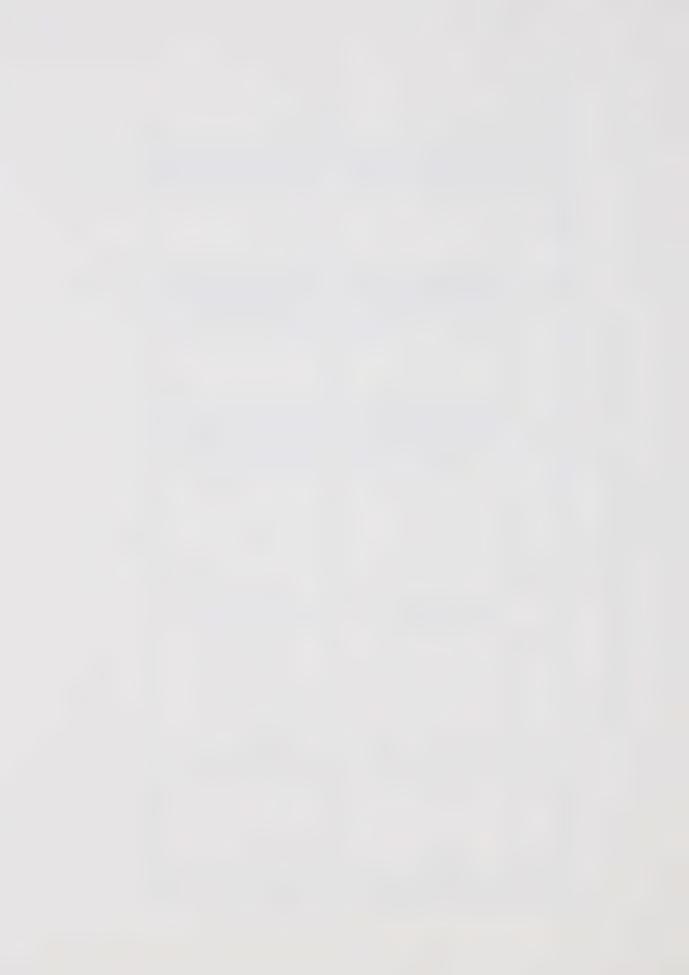


TABLE 2a INFLUENCE OF INERTIA TERMS

(i) Viscosi	ty Constant				
Re ★	M	IQ	[I		
	.1588	.7726	9999		
. 05	.1594	.7769	6651		
0.075	0.15978	-0.77911	0.66446		
	.1600	.7812	.6637		
. 2	.1613	.7893	.6610		
e.	.1625	.7972	6583		
. 4	.1638	.8048	.6558		
	.1650	121	.6533		
9	.1663	.8192	.6509		
. 7	.1676	.8261	.6486		
00	.1689	326	.6464		
0	.1701	.8390	.6443		
0	.1714	451	.6422		
-	.1727	509	.6402		
. 2	.1740	0.8566	.638		
(ii) T _S =	200°F Tp =	100°F	P = 59.64	DE = 0	.5357
₩ *	OM	* <u>*</u>	*10	* (# ¹
0	.1267	.1267	.6641	5343	7 9 6 1
0.05	0.12671	0.12734	-0.66663	0.53292	79.67
0	.1266	.1276	.6670	.5329	79.6
7	.1267	.1280	.6681	.5326	79.6
. 2	.1269	.1295	.6734	.5312	0

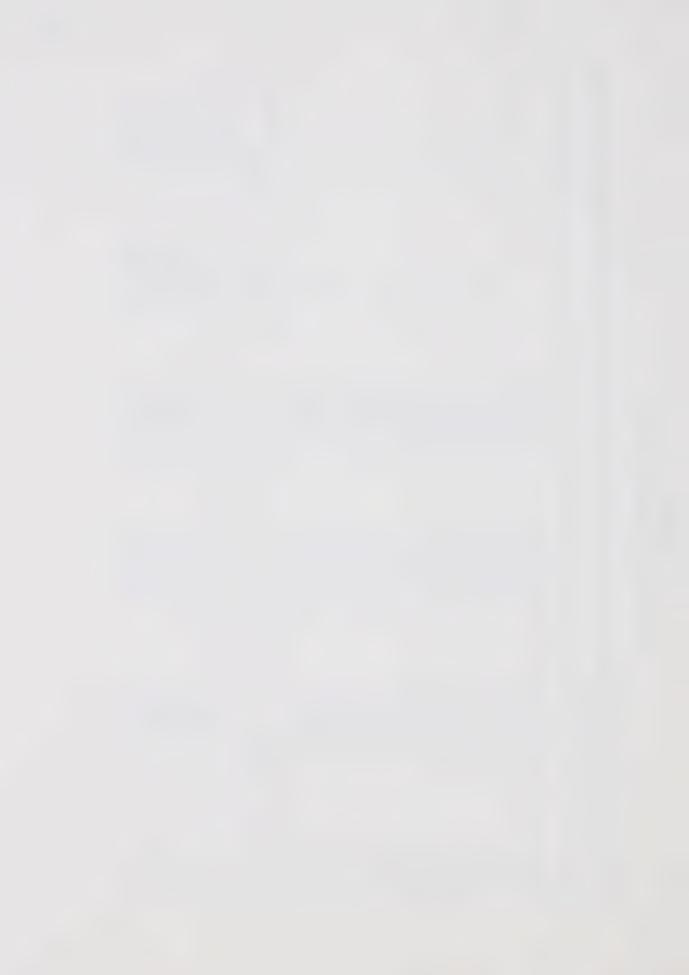
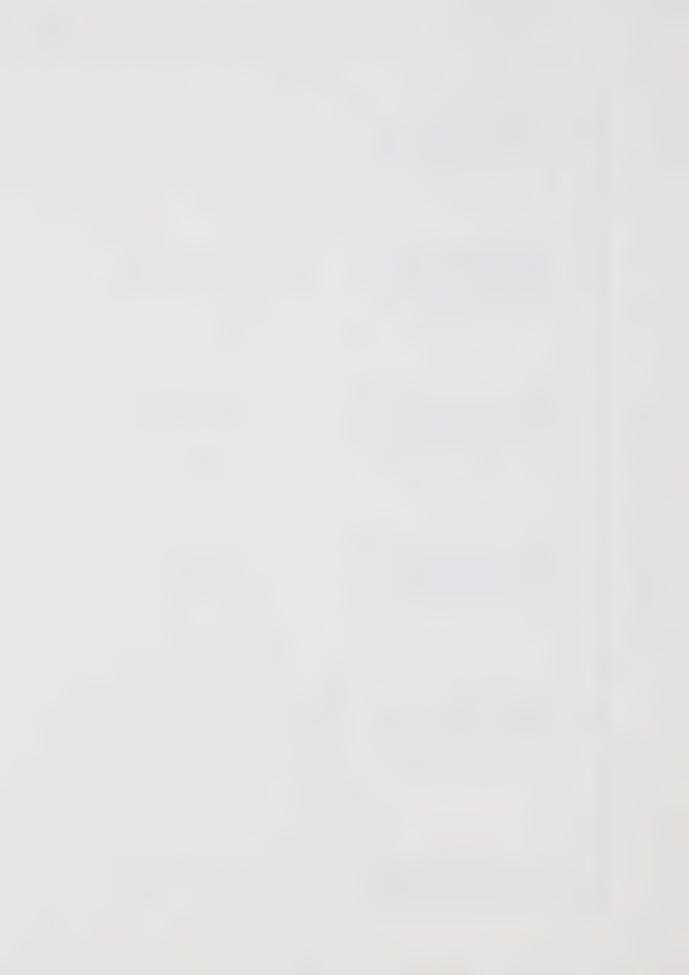


TABLE 2a (Continued)

Re *	M.O.	: IM	: IQ	ĺ≯	k L
0.30	.1269	308	.6785	5295	79.3
	.1269	21	6832	5278	79.3
0.50	0.12686		-0.68762	0.52606	79.3
	.1267	.1344	0.6918	5243	79.3
	.1266	.1356	.6958	.5225	79.4
	.1265	.1367	.6997	.5208	79.4
	.1264	.1379	0.7035	5191	79,5
	.1263	.1390	.7071	.5174	79.5
	.1262	.1401	.7107	.5157	79.6
	.1261	1412	.7142	.5141	179.68

o - Inertia not included * - Inertia included



INFLUENCE OF INERTIA TERMS

TABLE 2b

*					
Re	ΔM	* M	* 10	* !	T, (°F)
0.0	.1504	.1504	0.7224	.6684	54
.05	.1504	.15231	0.7350	.6665	54.
0	.1514	.1509	0.7265	.6669	54.7
_	.1522	.1533	0.7421	6659	77 (
	.1540	.1563	0.7626	.6631	52.2
	.1549	.1585	0.7767	.6602	51.6
	.1555	.1603	0.7882	.6574	2 2
	.1559	.1620	0.7981	.6548	51.
	.1562	.1636	0.8071	.6522	50.9
_	.1565	.1651	0.8154	.6497	0.0
00	.1567	.1665	0.8232	.6474	50.7
9	.1568	.1680	0.8307	6451	9 0 0 0
0	.1570	.1694	0.8377	6428	9.05
1.10	0.15711	0.17085	-0.84453	.6407	50.5
7	.1572	.1722	0.8510	0.63865	150.53
(ii) T _S =	100°F Tp	= 200°F	P = 59.64	다 단 대	= 0.5357
0	.2025	.2025	0.7776	8080	35.7
. 05	.2025	.2030	0.7832	8069	35.6
0	.2049	.2056	0.8013	8082	34.1
-	.2063	.2072	0.8152	.8086	33.1
. 2	.2092	.2111	0.8520	.8076	30.9
<u>.</u> ص	.2107	.2136	0.8766	.8054	29.9
	0.21176	.2156	.8963	.8029	29.3
٠. د	.2125	.2175	0.9134	.8005	28.9
9	.2131	.2191	0.9289	.7982	28.5
	.2135	.2207	0.9432	.7959	28.3
00	.2139	.2223	0.9567	.7936	28.1
9	.2143	.2238	9696.	.7914	27.9
0	.2146	.2254	0.9820	.7893	27.7
1.10	14	0.22692	-0.99383	0.78720	127.59
7	.2151	.2284	1.0052	.7851	27.4



% INCREASE IN LOAD CAPACITY DUE TO PRESENCE OF INERTIA TERMS TABLE 2c

T _S (°F)	T _p (°F)	Re *	MO	* 1'\(\text{\tin}\text{\tex}\text{\texi}\text{\text{\texit{\texi}\tex{\text{\texi}\text{\text{\text{\text{\text{\text{\texit{\text{\tex{\text{\text{\texi{\text{\texi}\text{\texi}\texit{\text{\	0 M - * M	% increase in load capacity
00000	100 100 100 100 100	00001	0.12692 0.12695 0.12674 0.12651 0.12630	0.12951 0.13215 0.13448 0.13676 0.13903	0.00259 0.00520 0.00774 0.01025	
Cons	Constant Viscosity	00001	0.15886 0.15886 0.15886 0.15886 0.15886	0.16134 0.16384 0.16636 0.16891 0.17148	0.00248 0.00498 0.00750 0.01005	1.56 3.14 4.72 6.34
150 150 150	150 150 150 150	0000	0.15401 0.15553 0.15625 0.15670 0.15700	0.15636 0.16038 0.16362 0.16659 0.16945	0.00235 0.00485 0.00737 0.00989	1.53 3.12 4.72 6.30
100 100 100 100 100	200 200 200 200 200	00001	0.20923 0.21176 0.21310 0.21396 0.21464	0.21111 0.21567 0.21917 0.22233 0.22541	0.00188 0.00391 0.00607 0.00837 0.01077	0.00 2.84 3.91 5.02

o - Inertia terms not included

^{* -} Inertia terms included

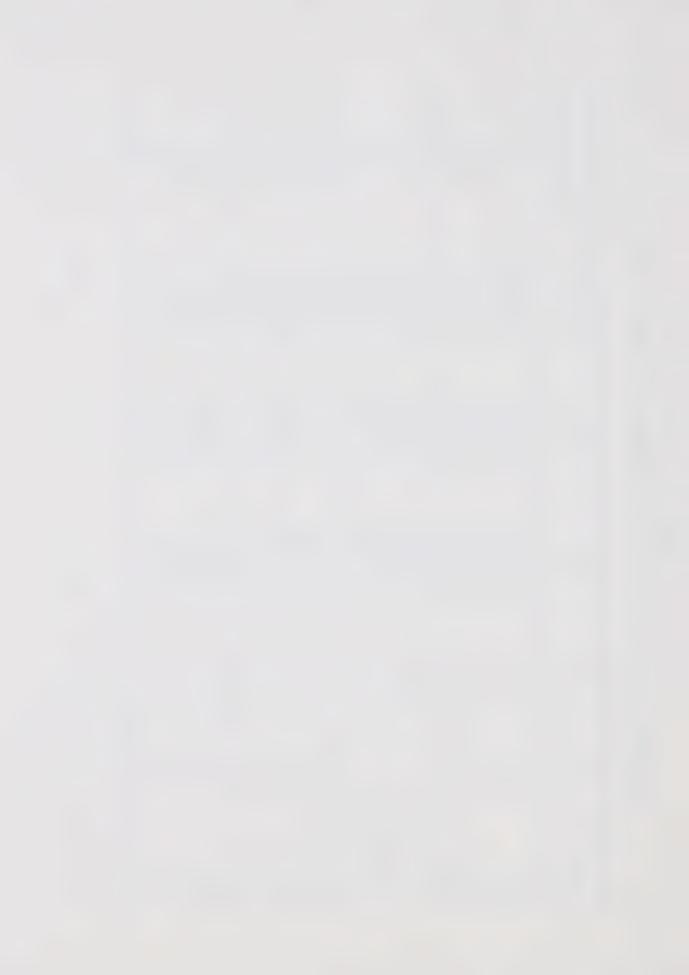


TABLE 3a VARYING INLET TO OUTLET RATIO - NO INERTIA

																				1	1							
11	0.9 =	T _L (°F)	27.7	56.7	56.3	56.1	55.9	55.7	155.59	55.4	1.25	60.0	0.09	60.09	60.1	60.1	60.2	0	60.3	0.10	62.2	62.2	62.3	62.5	62.7	62.9	163,18	63.4
	പ്										P e																	
	0.	l∋₁ C	5584	.6040	.6413	.6725	.6989	.7216	0.74124	.7584	0	.5565	.6012	.6379	.6685	.6944	.7167	0.73593	.7527	0 P	.5553	.5990	.6348	.6647	.6900	.7119	0.73083	.7473
	⊣										-i									= 1.								
	기기										E E									PE =								
		IQ	0.7801	.7332	0.7010	.6770	.6583	0.6429	-0.62973	0.6181		.7399	0.6906	.6561	.6303	.6099	0.5930	-0.57858	0.5659		.7166	.6684	341	.6080	.5871	5695	-0.55429	408
0											150°F									150°F								
	1 01	ΙZ	.0793	.1169	.1349	.1424	.1441	.1425	13916	1347	Ω		.1101	.1267	.1334	.1346	.1327	.1292	.1248		.07040	1050	1208	1267	1273	1250	211	1166
17.00 F			0	0	0	0	0	0	0 (0	150°F	0	0	0	0	0	0	0	0	150°F	0	0	0	0	0	0	0	0
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E-	ι N								J (വ									ر د د							
(:		E						9		•	-H	0.2		9					•		0.0							

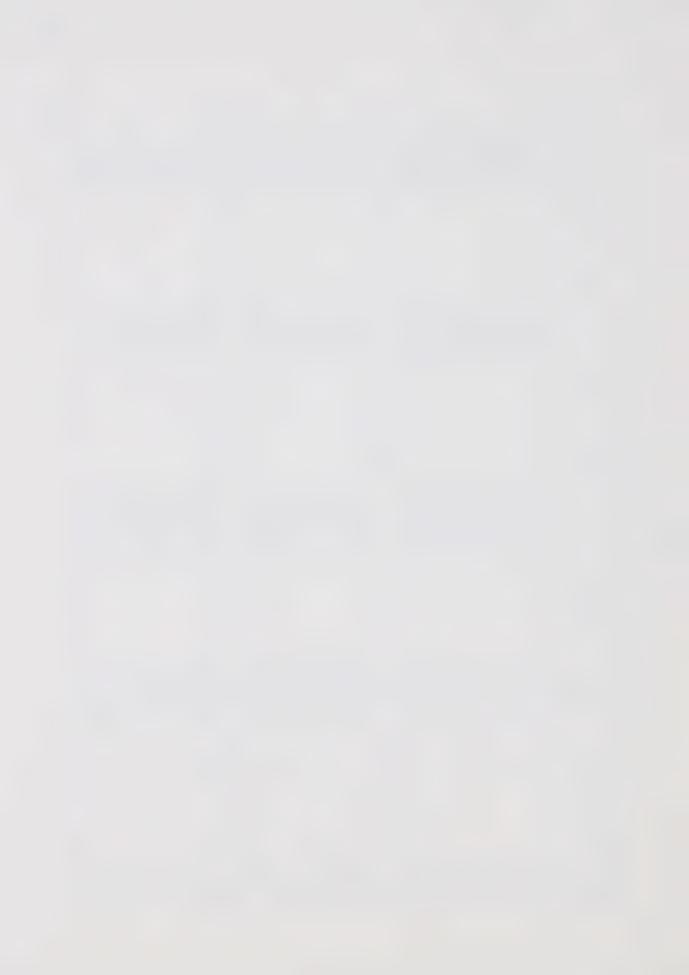


TABLE 3b VARYING INLET TO OUTLET RATIO - NO INERTIA

0.9 =	T _b (°F)	2 2	81.0	82.5	83.5	84.6	85	187.06	88.2	= 1.25	82.6	83.1	83.8	84.6	85.5	86.5	87.6	00	= 0.10	84.5	84.8	85.4	86.0	86.7	87.5	188.42	89.2
1.0 Pe	ا∌۰	.3967	.4302	.4583	.4825	.5035	.5222	0.53912	.5547	1.0 Pe	.3976	.4301	0.45720	.4800	.4996	.5165	.5313	.5443	1.0 Pe	.39840	.4301	.4564	.4786	.4976	.5140	0.52846	.5411
- E E E E	IQ	.7019	0.6439	.5995	.5640	.5344	.5089	-0.48666	.4672	F PE =	0.6838	0.6301	-0.58973	0.5578	.5315	0.5091	.4896	0.4722	0°F PE =	0.6653	.6161	0.5793	0.5502	0.5264	.5062	-0.48878	.4733
0°F T _p = 100'	M	.0553	.08561	.1001.	.1063	.1078	.1067	0.10405	. 1004	$T_{p} = 100$	057	.0859	.0995	.1051	.1063	.1049	.1022	.0986	p = 10	0.05619	.0853	.0987	.1041	.1050	.1034	.1005	.0970
(i) $T_{S} = 20$	m	. 2	٠ ر	. 7	0	2	٠ ا	1.75		$i)$ $T_s = 2$	0.25		. 7	0	7	υ.	. 7		ii) T _s =	0.25	٠ ر		0	7	5	. 7	0

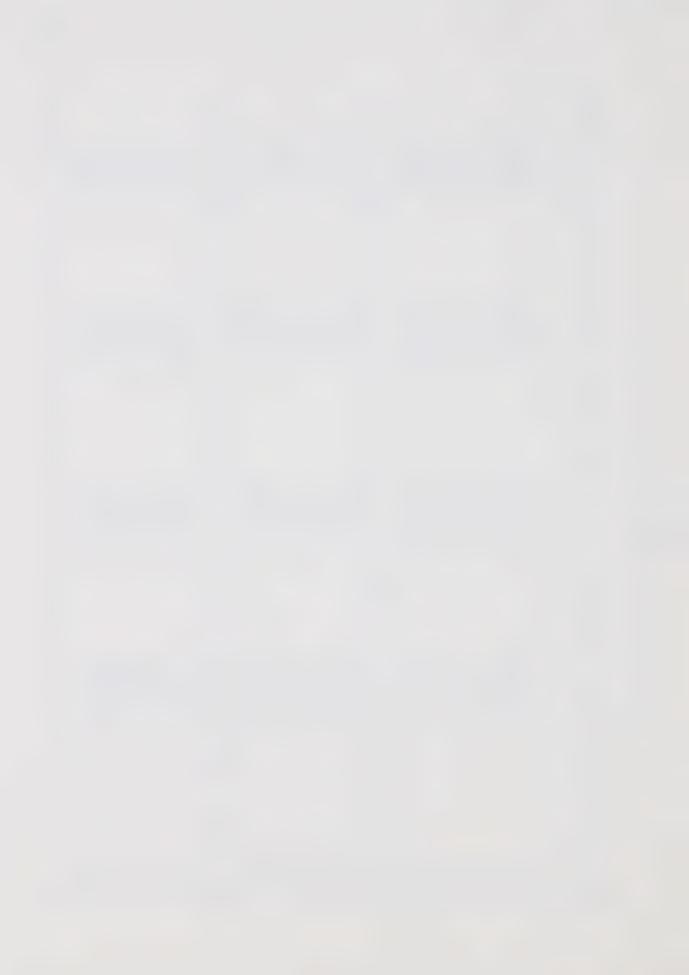


TABLE 3c VARYING INLET TO OUTLET RATIO - NO INERTIA

P _e = 6.0	T _h (°F)	41.9	40.0	38.2	36.3	34.4	32.4	9	28	$P_{\rm P} = 1.25$	145.4	44.7	43.9	43.0	9	40.8	39.6	ω	0.10	147.6	47.4	47.2	146.98	146.6	46.1	45.6	45.0
= 1.0	I∌·	.7235	.7837	.8331	.8742	.9089	.9384	0.96347	.9782	= 1.0	.7160	.7730	.8193	.8578	0.89035	.9182	.9424	.9635	= 1.0 P	.7123	.7668	.8107	0.84684	.8770	.9026	.9247	.9437
PE PE	IQ	0.7524	0.7394	.7425	.7533	.7680	.7846	-0.80276	.8291	PE	0.7048	.6776	.6657	.6615	-0.66092	0.6624	.6650	.6684	田山	0.6781	0.6449	.6256	-0.61277	.6032	0.5954	. 5885	0.5822
00° F $T_{\rm p} = 200^{\circ}$	M	124	.1823	.2111	. 2243	. 2287	.2281	. 2245	.2164	00°F Tp	.1133	.1655	.1899	.1994	0.20110	.1984	.1936	.1876	100°F T _D = 200	0.10184	.1499	.1706	.1770	.1762	.1716	.1652	.1579
$(i) T_{S} = 10$	E	0.25	٠ ر	•	0.0	7 1	٠ ر			(F)	2.1	3	. 7	0.	1.25	٠ ر			근	0.25	ئ ر		0.	7 1	٠ ر		·

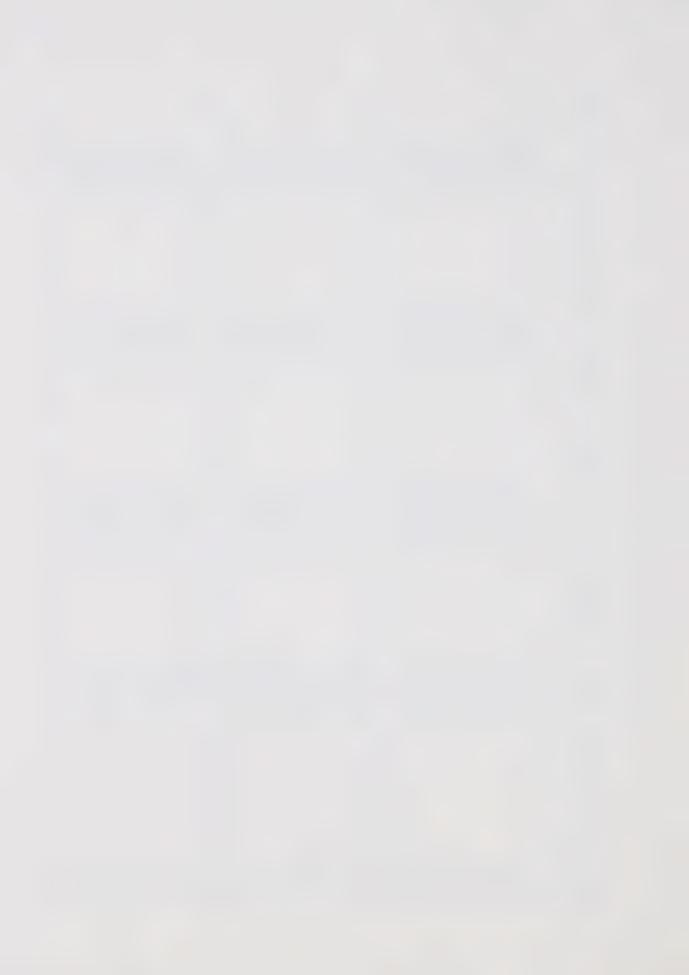


TABLE 4a

DISSIPATION EFFECTS - NO INERTIA

	T _b (°F)	74 04	[0 0 0	6 82.37	7 85.81	89,34	92,89	8 96.47	100.04	0 103,46	3 106.		1 84.70	0 87.17	0 90.17	5 93.54	0 97.06	4 100,70	104.31	108:00	7 111.65	0 114.96	118.380
	D I∌'	.862	ж 200	0.8560		. 848	.844	.840	.836	.832	.829	.825		.6694	.6732	.6766	.6801	.6828	.6852	.6875	.6890	.6905	,6917	0.6922
	IQ	0.7785	0.7177	-0.65143	0.5844	0.5228	0.4679	0.4198	0.3777	0.3412	.3097	0.2819		0.7220	0.6631	-0.59758	0.5343	0.4783	0.4285	0.3843	0.3462	0.3137	0.2862	0.2615
$P_{e} = 5.0$	M	.2216	.2086	0.19409	.1783	.1633	.1494	.1373	.1259	.1158	.1072	0660.	P _e = 5.0	.1502	.1403	0.12931	.1181	.1080	.0988	.0903	.0829	.0769	.0714	.0661
	A	.564	.270	2.2585	.529	.081	.916	9.034	1.434	4.116	.080	0.327		.5646	.2704	2.25850	.5290	.0817	.9168	.0342	1.4340	4.1160	.0800	0.3270
0.5	- 1	\vdash	$\overline{\Box}$	110	$\overline{}$	Н	\dashv		$\overline{\Box}$	\dashv	$\overline{-}$	-1	= 1.0	2	2	82.5	2	N.	N.	2	2	2	2	2
(1) T _S /T _p =				55									_	2	2	82.5	5	2	2	2	ζ.	c'	2	2

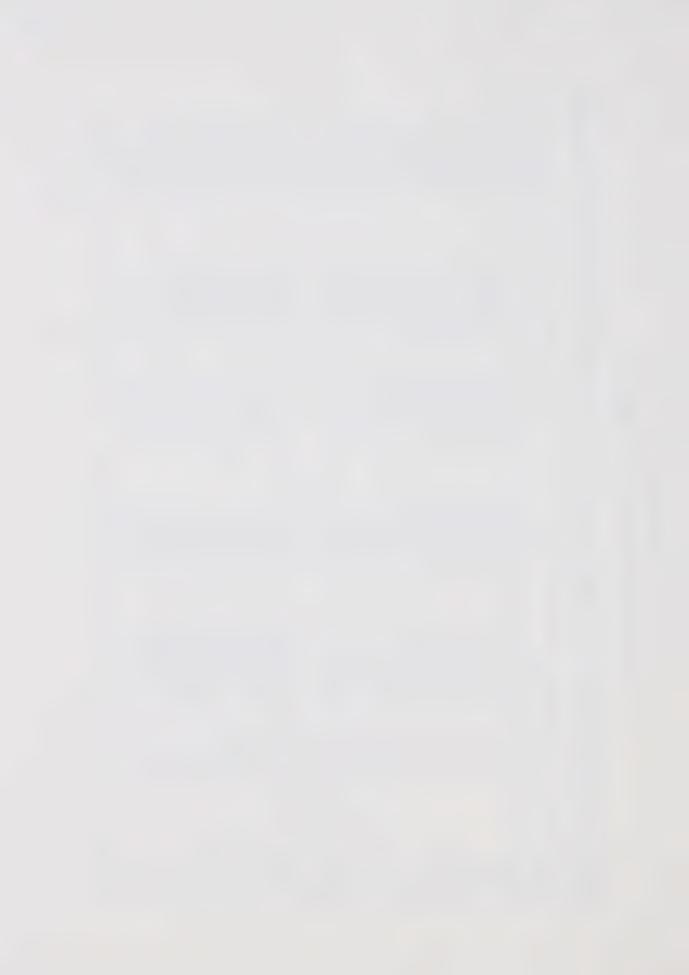


TABLE 4a (Continued)

	T _b (°F)	48631 99.47	.49423	50378	51194	52047	52866 114.38	.53611 117.82	.54341	55047	55577 108 17	
Pe = 5.0	ī	.60125	.55727	.50916	.46042	0.41546	.37451	.33847	0.30716	0.27970	.25642	-0.23636 0
	M	.1132	.1046	.0951	.0861	.0775	0.07030	.0638	.0580	.0533	.0494	.0461
0	더	.564	.270	. 258	.529	.081	6.9168	9.034	.434	4.116	7.080	0.327
$s/T_p = 2.$	Tp (°F)						52					
(iii) T	Ts (°F)	110	\vdash		\vdash	-	\vdash	<u> </u>	\vdash	\vdash	$\overline{}$	$\overline{}$

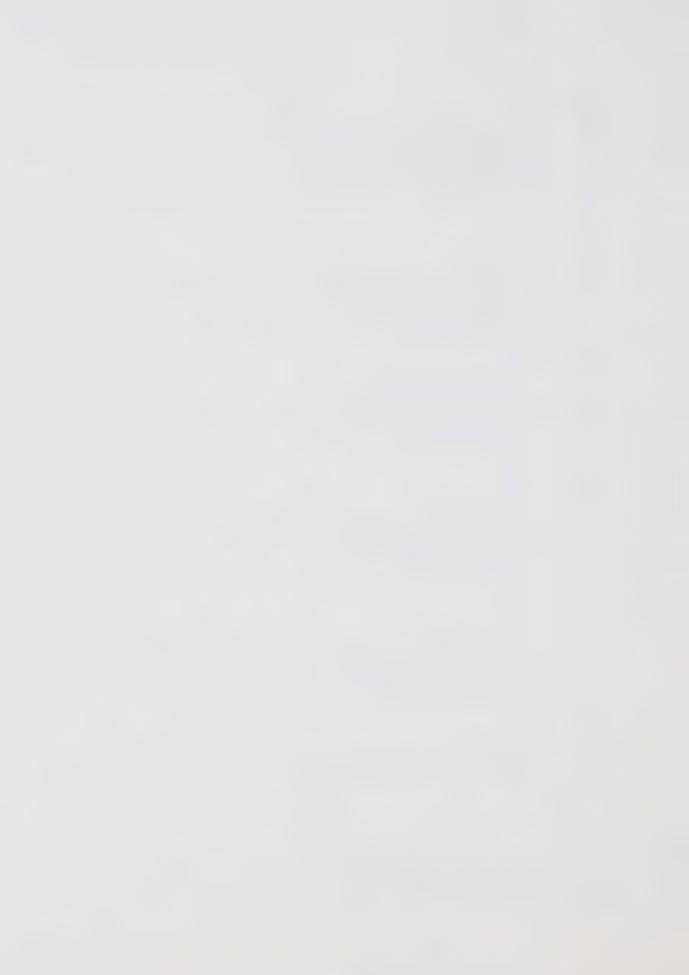


TABLE 4b

DISSIPATION EFFECTS - NO INERTIA

2			e			
	T _p (°F)	PE	ZΙ	Д	IJ÷	T _b (°F)
22	110	.5646	.2262	0.8121	8645	2 80
	\vdash	.2704	.2170	0.7668	8644	7
	\vdash	.2585	.2059	0.7134	8642	1 00 1 00 1 00
	Н	.5290	.1935	0.6569	8640	0 0
	\vdash		0.18147	-0.60201	.8642	00.0
		.9168	.1695	0.5500	.8634	3.79
	\vdash	.0342	.1581	0.5028	.8623	700
	\vdash	1.4340	.1480	0.4604	8620	12.0
	H	4.1160	.1383	.4223	8610	4000
	\vdash	.0800	.1298	.3883	8594	7.0
	Н	0.3270	.1219	.358	0.85918	97.719
i) T _S /T _p	= 1.0		Ф Д	= 10.0		
82.5	82.5	.5646	.1524	0.7375	.6694	3,95
ς.	2	.2704	.1448	0.6964	6734	7 6
2	2	.2585	.1355	0.6441	.6784	7 78
ς.	2	.5290	.1263	0.5919	.6827	0.21
2	2	5.08170	0.11707	-0.54112	0.68732	92,884
2	2	.9168	.1086	0.4943	.6910	5.69
N N	2	.0342	.1009	0.4524	.6951	8.54
2	2	1.4340	.0935	0.4140	6984	01.46
2	2	.1160	.0873	0.3804	7018	4 33
2	2	7.0800	.0818	.3501	7042	07.25
2	2	0.3270	.0763	7008 0	7000) (

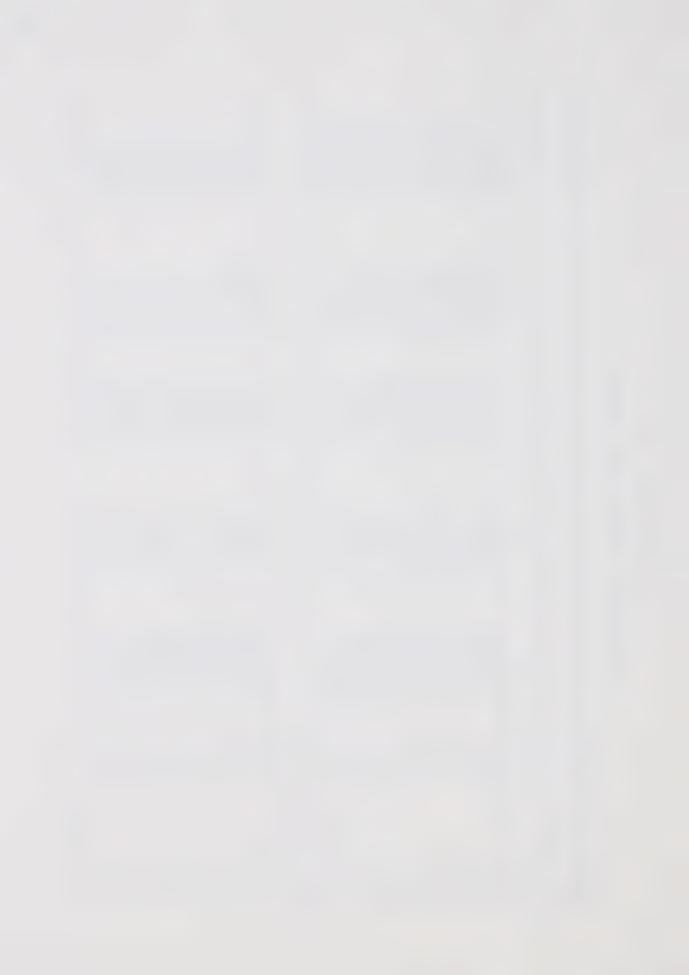


TABLE 4b (Continued)

(iii) $T_{\rm s}/T_{\rm p}$	= 2.0			P _e = 10.0		
T _S (°F)	T (°F)	PE	M	IQ	ρ I⇒'	T _b (°F)
110		.564	.1132	.6011	4880	9.35
110		.270	.1062	.5688	.4942	00.92
110		.258	.0979	0.5315	.5019	02.92
110	55	3.5290	0.08974	-0.49242	0.51011	105.240
110		.081	.0821	0.4531	.5174	07.79
110		.916	.0745	.4169	.5255	10.46
110		.034	.0683	0.3834	.5328	13.22
110		1.434	.0626	0.3528	.5400	16.01
110		.116	.0575	0.3259	.5471	18.81
110		7.080	.0529	3015	.5540	21,61
110		0.327	.0495	2800	.5589	24.45

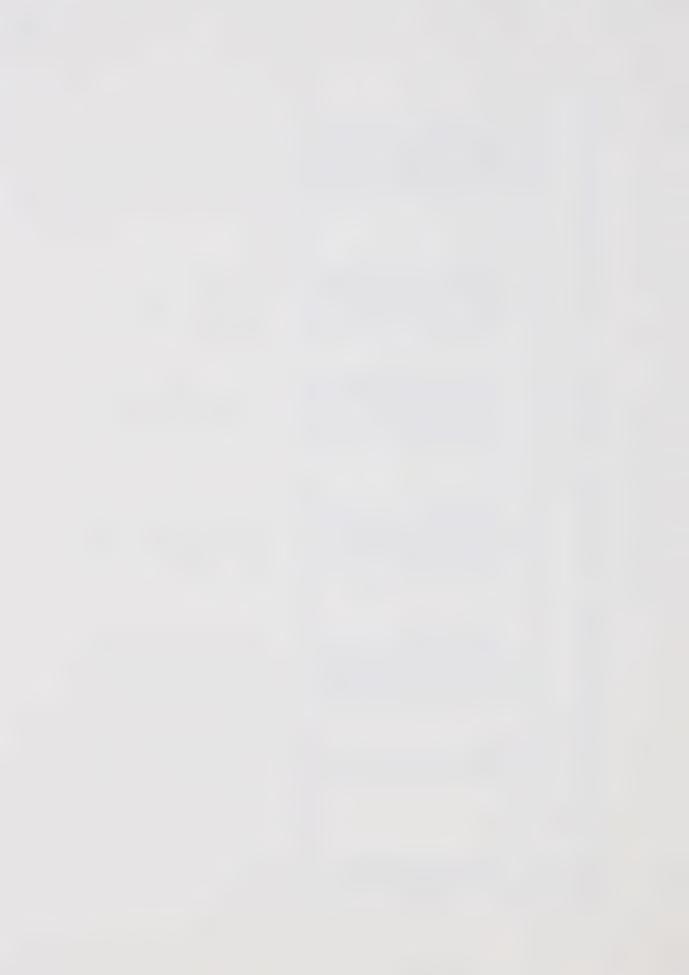


TABLE 4c

DISSIPATION EFFECTS - NO INERTIA

	T _b (°F)	72.230 73.379 74.886 76.694 78.662 80.816 85.327 87.703 90.064	83.579 84.855 86.508 88.454 90.560 92.839 97.637 100.080 102.570
	Ū I>·	0.86447 0.86556 0.86553 0.86792 0.87091 0.87405 0.87426 0.87448	0.66917 0.67268 0.67278 0.68274 0.68268 0.69248 0.70134 0.70536
= 15.0	IQ	-0.83013 -0.79266 -0.74799 -0.69886 -0.64955 -0.51537 -0.47727 -0.44281	= 15.0 -0.74540 -0.67224 -0.62640 -0.53828 -0.49774 -0.46153 -0.42754 -0.36985
P4 D4	IX	0.22827 0.22089 0.22089 0.19022 0.17961 0.15978 0.15061 0.14236	Pe 0.15360 0.14749 0.13120 0.13120 0.12272 0.11468 0.10704 0.10704 0.09374 0.08308
	더	0.5646 1.2704 2.2585 3.5290 5.0817 6.9168 9.0342 17.0800 20.3270	0.5646 1.2704 2.2585 3.5290 5.0817 6.9168 9.0342 11.4340 17.0800 20.3270
0 .5	Tp (°F)	110 0111 01110 01110 1100 1100	
(i) T _S /T _p	T _S (°F)	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	(ii) T _S /T _D 82.5 82.5 82.5 82.5 82.5 82.5 82.5 82.5

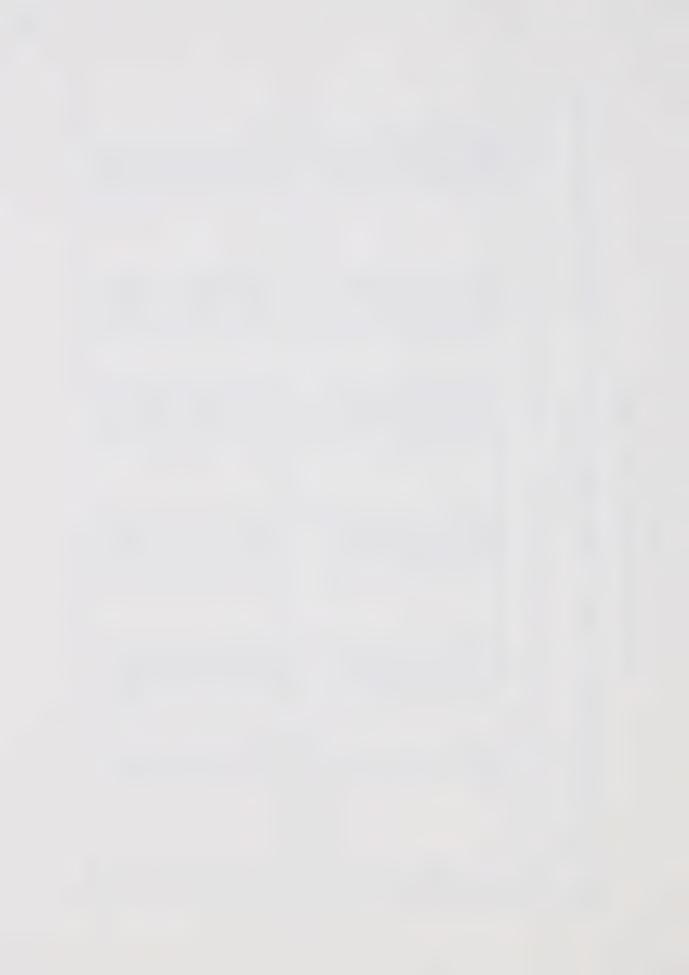


TABLE 4c (Continued)

מ	Q.		Д	e = 15.0		
T _S (°F)	Tp (°F)	PE	IΜ	IQ	υ I∌·	T _b (°F)
		.564	1133	6016	4892	0
\vdash		.270	1074	5762	1001	
110	55	2.2585	0.10030			100.400
\vdash		.529	.0927	. C. T. C.	• 0 0 C C C C C C C C C C C C C C C C C	
\vdash		0.0		1000) · ·	00°04
-		9 6	0000	0.4/72	· 2146	02.30
4 -		9T6.	.0788	.4462	.5215	08.00
-1		9.034	.0722	.4153	.5288	10 37
		1.434	.0666	0.3866	5359	
		4.116	.0616	1038.0	アイング	1 C - 7 C -
\vdash		.080	0569	1988 0	0 1 0 1 V V V V V V V V V V V V V V V V	10.00
\vdash		0.327	α	0.00 0.00 0.00 0.00	1 C	17.40
l			00000	* 3143	. 555	

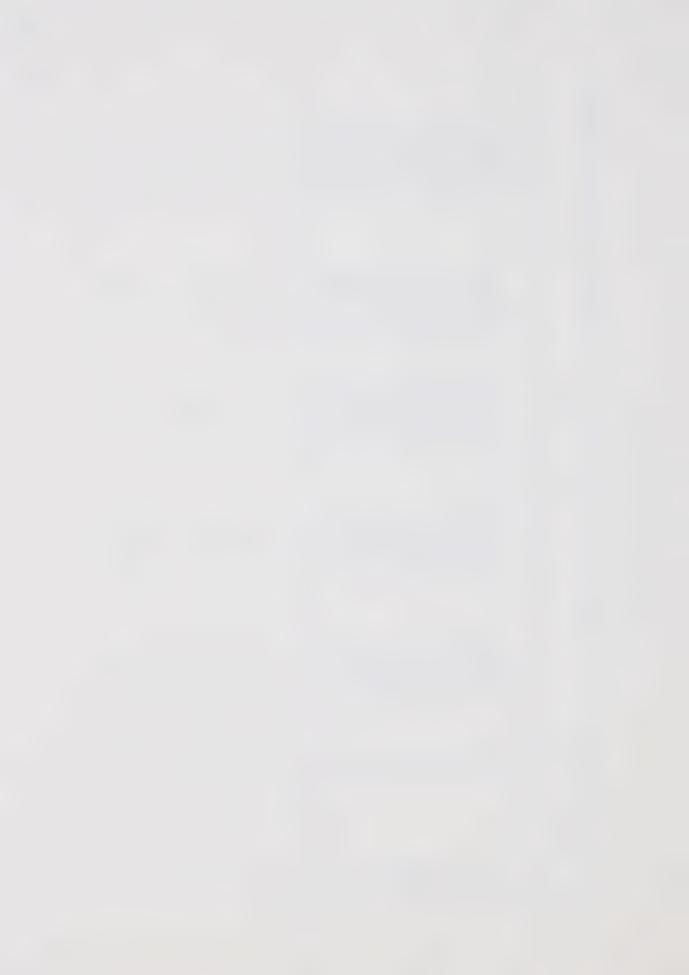


TABLE 4d
DISSIPATION EFFECTS - NO INERTIA

	Ψ̄ _C T _b (°F)	0 0.86392 71.899 1 0.86542 72.828 9 0.86721 74.056 2 0.86921 75.542 0 0.87224 77.187 7 0.87452 80.916 8 0.87922 82.827 2 0.88110 84.834 9 0.88265 86.898 9 0.88370 88.990	0 0.66896 83.360 4 0.67208 84.387 9 0.67694 85.736 6 0.68231 87.339 1 0.68723 89.105 4 0.69727 91.024 0 0.69727 93.054 4 0.70212 97.266 1 0.71087 99.423 7 0.71546 101.480
P _e = 20.0	W DI	0.22962 -0.8415 0.22320 -0.8096 0.21519 -0.7704 0.20571 -0.7271 0.19560 -0.6815 0.18595 -0.6815 0.17620 -0.5941 0.16723 -0.5941 0.15871 -0.5176 0.15051 -0.4834	Pe = 20.0 0.15436 -0.7501 0.14920 -0.7251 0.14201 -0.6901 0.13413 -0.6993 0.12673 -0.6093 0.11880 -0.5688 0.11170 -0.5688 0.10493 -0.4630 0.09862 -0.4630 0.09286 -0.4630
	PE	0.5646 1.2704 2.2585 3.5290 5.0817 6.9168 9.0342 11.4340 17.0800	0.5646 1.2704 2.2585 3.5290 5.0817 6.9168 9.0342 11.4340 17.0800
$T_{\rm p} = 0.5$	Tp (°F)	110 110 1110 1110 1110 1110	s/T _p = 1.0 82.5 82.5 82.5 82.5 82.5 82.5 82.5 82.5
(i) T _s	Ts (°F)		(ii) 88888825.5 8822.5 8822.5 822.5 822.5 822.5

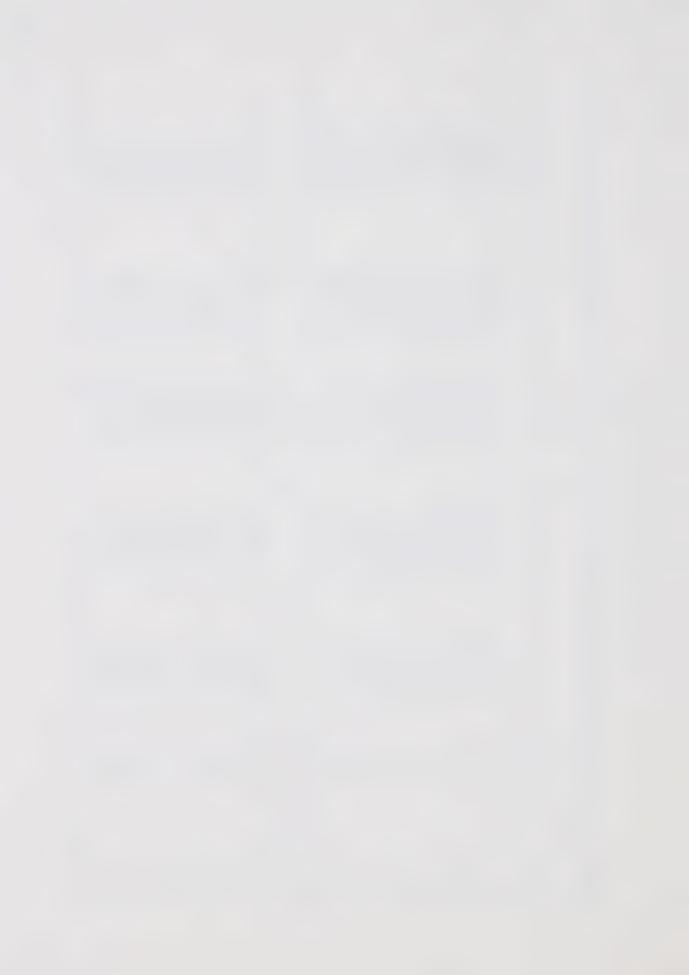


TABLE 4d (Continued)

	T _b (°F)	9.16	100.140	01.41	02.94	4.66	06.53	08.47	10.49	12.55	14.71	16.80
	IJ-l	.4901	0.49419	.4996	.5059	.5124	.5187	.5254	.5320	.5387	.5443	.5507
= 20.0	IQ	.6021	-0.58115	0.5554	0.5271	.4974	0.4672	0.4384	0.4117	0.3863	0.3626	.3410
С' Ф	Μ	.1132	0.10834	.1021	.0952	.0885	.0821	.0757	.0701	.0649	909	562
	되스	.564	1.2704	. 258	.529	.081	.916	.034	.434	4.116	7.080	0.327
$T_{p} = 2.0$	T (°F)		52									
(iii) T _S /	T _S (°F)		110	$\overline{}$	\Box	$\overline{}$	\vdash	-	\vdash	\vdash	\vdash	\vdash

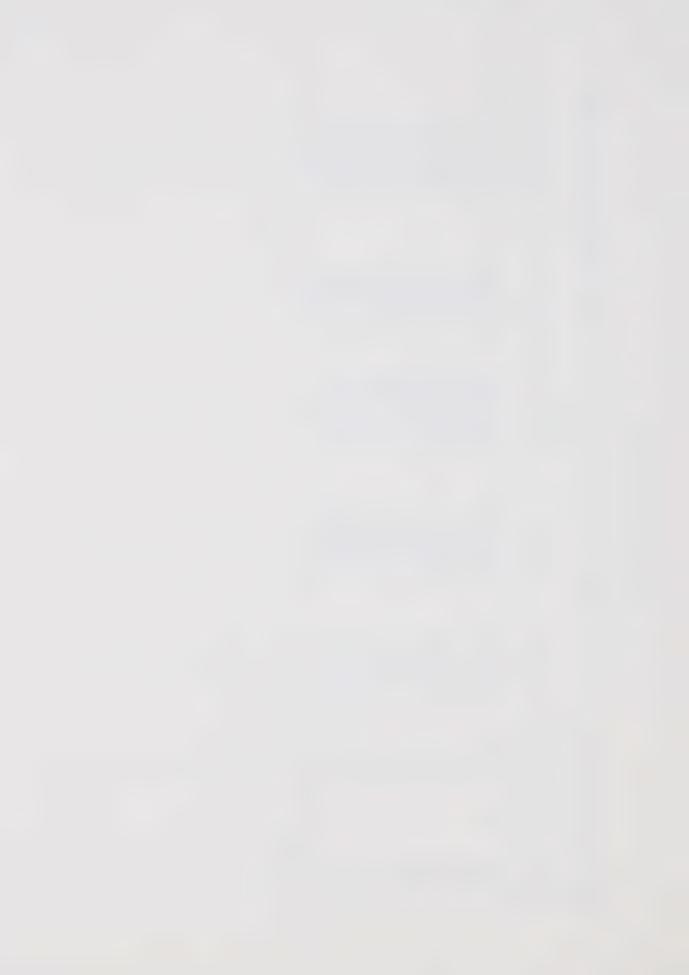


TABLE 5a CONVECTION EFFECTS - NO INERTIA

	oF)	1	• 00		, A	† C	0	15	0.			-	1 6	00	0	1	-	. 64		-	\sim	10	1	0	0	0	.91
	T _b (200	3 0		100	66	197	5		31	31	30	29	29	00	27	226		69	69	69	69	69	69	70	0
	υ I⇒	8516	8550	8574	8600	.8616	.8626	0.86369	.8633		.6672	.6677	.6680	.6684	.6686	.6687	.6686	0.66829		.4855	.4863	.4871	4882	4891	.4897	0.49127	.4937
0.39253	IQ	0.7578	0.7759	0.7904	0.8079	0.8212	0.8317	-0.85258	0.8789	0.39253	0.7174	0.7216	0.7254	.7310	0.7357	0.7394	0.7471	0.756	0.39253	0.6428	0.6401	0.6378	0.6349	0.6329	0.6316	-0.62954	0.6274
PE ==	M	.2216	.2272	.2309	.2343	.2365	.2380	0.24064	.2438	DE =	.1489	.1501	.1509	0.15185	.1525	.1530	.1541	.1556	田田田	.1218	.1218	.1216	.1212	.1209	.1208	0.12047	.1199
	Ъ	0	. 7	5	. 7	0.	6.2	10.00				. 7	rO.	3.75	0.	.2	0.	0.0			. 7	5		0.	2 .	0.	0.0
= 0.5	~	0	0	0	\circ	0	0	300	\circ	= 1.0		\sim	\sim	225	\sim	N.	\sim	α	= 2.0	150	Ŋ	LO	LO	LO	LO	10	LO
(i) T _S /T _p	0	2	Ŋ	Ŋ	Ŋ	LO	5	150	2	~	225	\sim	\sim	\sim	\sim	\sim	\sim	α	(iii) T _S /T _p	300	0	0	0	0	0	0	0

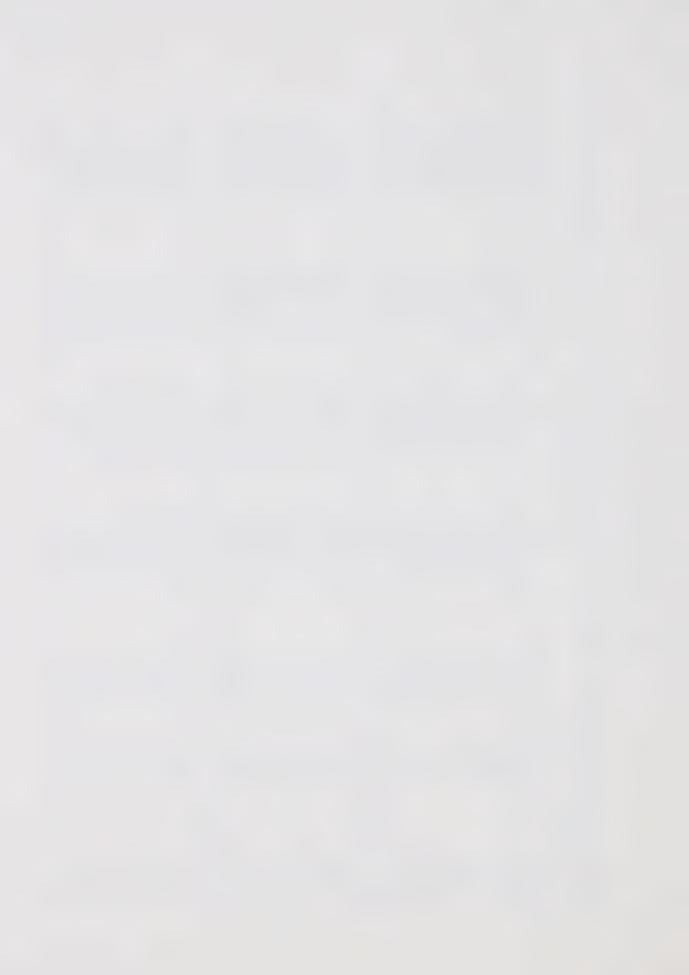


TABLE 5b CONVECTION EFFECTS - NO INERTIA

s, d			면데	1.59		
F)	T _D (°F)	D. D.	M	Q	D I⇒	T _b (°F)
			.1790	0.5975	.8461	55.8
5			.1900	0.6223	.8522	53.7
	\Box	5	.1977	0.6438	.8574	51.8
05	210	3.75	0.20643	-0.67346	0.86390	149.39
		0.	.2121	0.6966	.8681	47.4
	\vdash	. 2	.2163	0.7153	.8711	46.0
	\vdash	0	.2237	0.7544	.8755	43.1
	-1	0.0	.2322	0.8058	.8784	39.7
T /T	= 1.0		PE ==	1.59		
1	57.	0	.1225	0.5739	.6685	73.6
	57.		.1259	0.5841	.6705	72.5
7	57.	.5	.1286	0.5957	.6719	71.2
	57.		.1317	0.6128	.6736	9.69
	57.	0.	.1338	0.6273	.6746	68.2
	57.	.2	.1356	0.6397	.6750	67.0
7.5	157.5	10.00	0.13949	-0.66661	0.67522	164.75
7	57.	0.0	.1448	0.7014	.6743	61.9
T _S /T	= 2.0		E E	1.59		
	0	0	.0981	0.5176	.4890	98.6
10	0		.0988	0.5204	.4896	98.1
	0	5	.0991	0.5230	.490I	97.6
0.	105	3.75	0.09957	-0.52756	0.49062	196.91
	0	0.	.0999	0.5322	.4907	96.2
	0	.2	.1004	0.5367	.4905	95.6
	0	0 .	.1019	0.5477	.4899	94.2
			0101		000	000

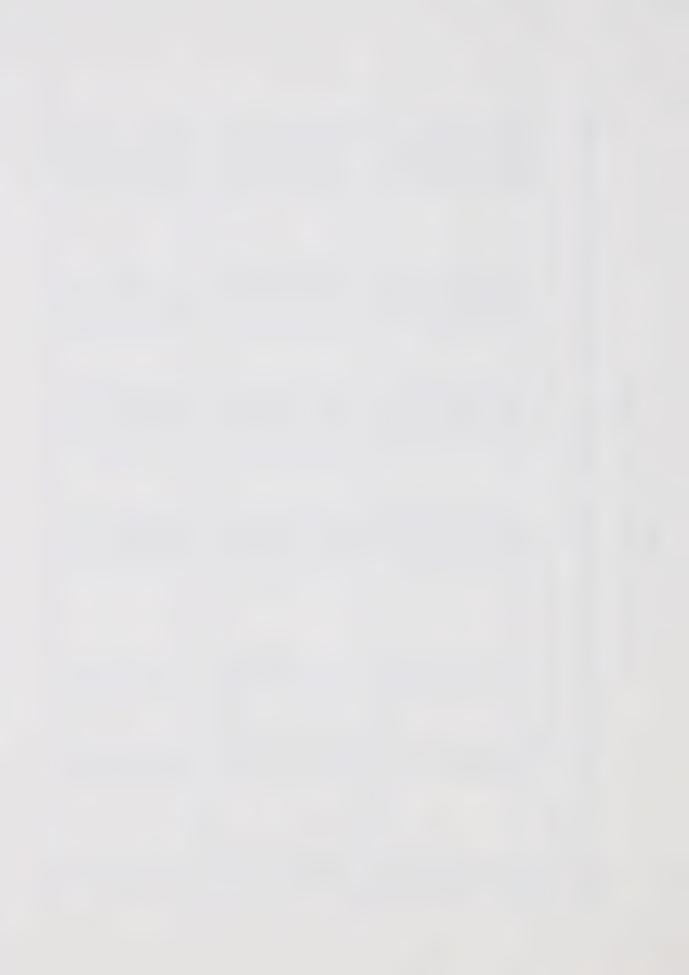


TABLE 5c CONVECTION EFFECTS - NO INERTIA

S, D				9		
0 1						
	T _p (°F)	ъ O	IZ	IQ		D (°F
	\sim	0	.0844	0.2815	.7973	24.4
	$^{\circ}$.0956	0.3009	.8065	21.3
	$^{\circ}$.1055	0.3208	.8159	18.9
	$^{\circ}$. 7	.1180	0.3509	.8301	15.4
	\sim	0.	.1274	0.3785	.84132	12.4
55	130	6.25	0.13488	-0.40270	0.85034	109.92
65	\sim	0.	.1499	0.4604	.86748	04.3
	\sim	0.0	.1692	0.5528	.8845	97.0
$i)$ T_S/T_p	1.0		日日日	10.89		
7	7	0	.0647	0.2777	.6692	35.7
			.0693	0.2885	.6742	33.7
97.5	97.5	2.50	0.07357	-0.30253	0.67846	131.71
		. 7	.0789	0.3252	.6842	28.7
		0.	.0827	0.3456	.6886	26.1
		. 2	.0861	0.3653	.6921	23.7
		0.0	.0928	0.4114	.6973	18.6
7	7	0	.1038	0.491	.7011	15.9
TS/T	11		P	000		
\sim		0	.0522	0.2619	,5352	49.4
$^{\circ}$.0537	0.2700	.5369	47.5
$_{\odot}$		5	.0549	0.2786	.5378	46.0
130	65	3.75	0.05618	-0.29210	0.53840	143.82
\sim		0.	.0572	0.3050	.5383	41.8
$_{\odot}$.2	.0582	0.3175	.5378	40.0
$_{\odot}$		0	.0611	0.3489	.5345	35.9
\odot		0.0	.0685	0.4044	.5255	29.8

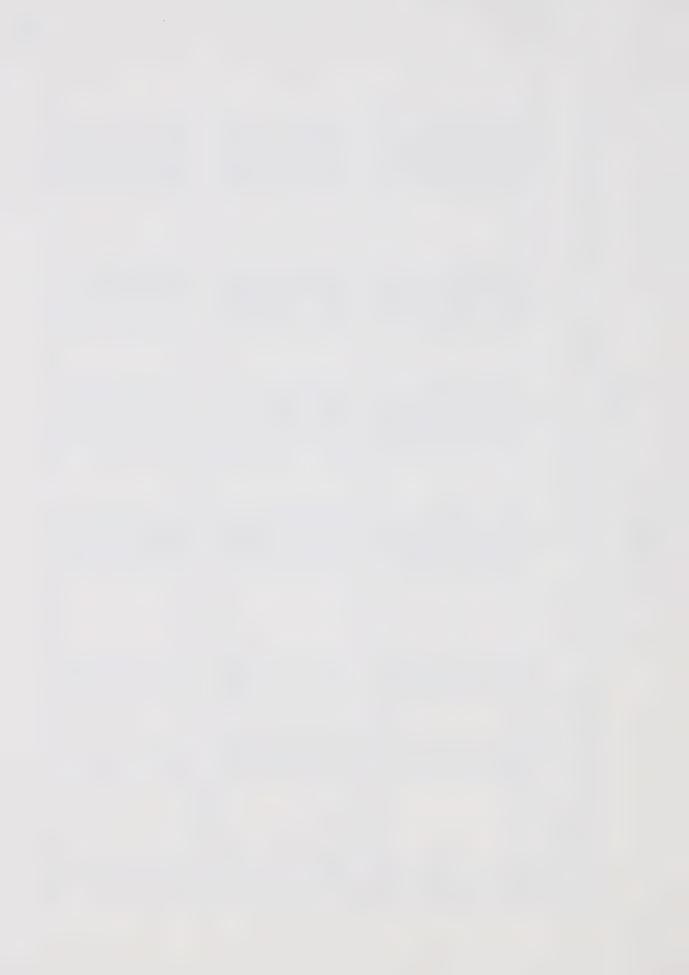


TABLE 5d CONVECTION EFFECTS - NO INERTIA

		7674 121.7	8508 117.3	9530	1156 110.3	2543 106.9	3662 104.1	5918	8370 88.9		6876 130.4	7381 126.9	7900 124.6	8626 121.2	9224 118.3	9762 115.9	0657 110.13	1546 101.4		5640 140.5	5844 137.9	5974 136.1	6049 133.6	6124 131.3	6130 129,3	5897 124.4	5075 116
= 20.33	ID	0.20398 0.	0.21613 0.	0.23150 0.	0.25756 0.	0.28196 0.	0.30369 0.	-0.35833 0.8	0.45189 0.	= 20.33	0.20061 0.	0.21187 0.	0.22288 0.	0.24298 0.	.26156 0.	0.27879 0.	-0.32267 0.7	0.40577 0.	= 20.33	19430 0.	.20227 0.	0.21038 0.	0.22308 0.	.23640 0.	0.24845 0.	.28005 0.	.3410
PE	ı⊠	.0612	.0694	.0779	.0898	.0990	.1063	0.12197	.1429	PE	.0483	.0531	.0569	.0623	.0661	.0695	0.07632	.0877	되러	.0400	.0419	.0432	.0447	0.04617	.0471	.0495	.0562
		0	. 7	5		0.	6.2	10.00			0	. 7		. 7	0.	6.2	10.00				. 7	٠ ك		5.00	6.2	0	0.0
= 0.5	\sim	\vdash	\vdash	\vdash	-	-		0	۱.	= 1.0		2	2	ζ.	5	7				55							
(i) T_S/T_p								U U U		_	82.5	· ·	N	2	20	2	· ·	7		110			-	- ,	-		\vdash

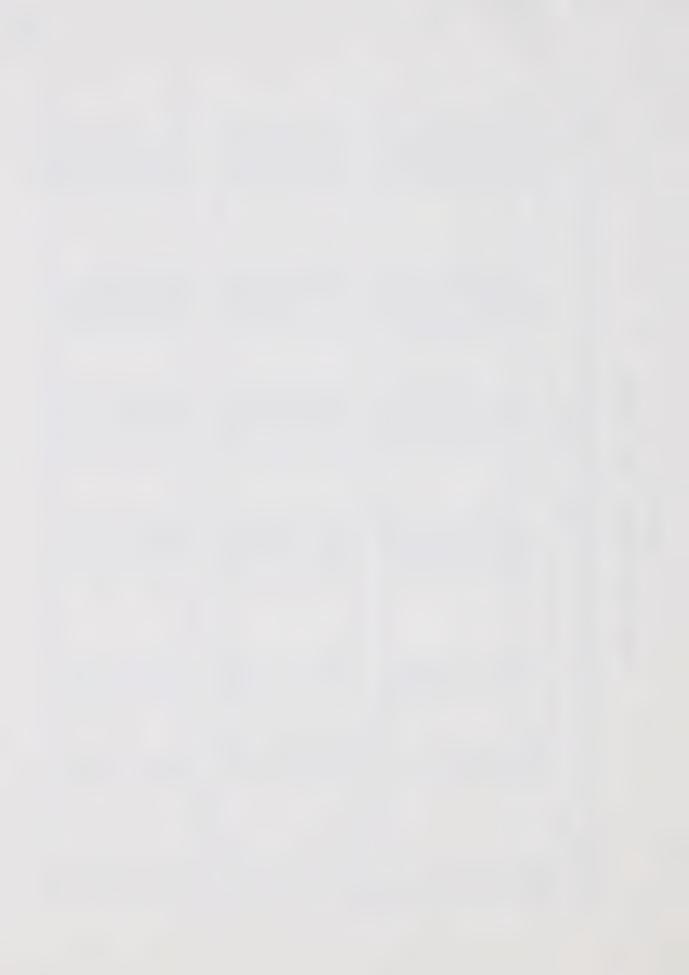
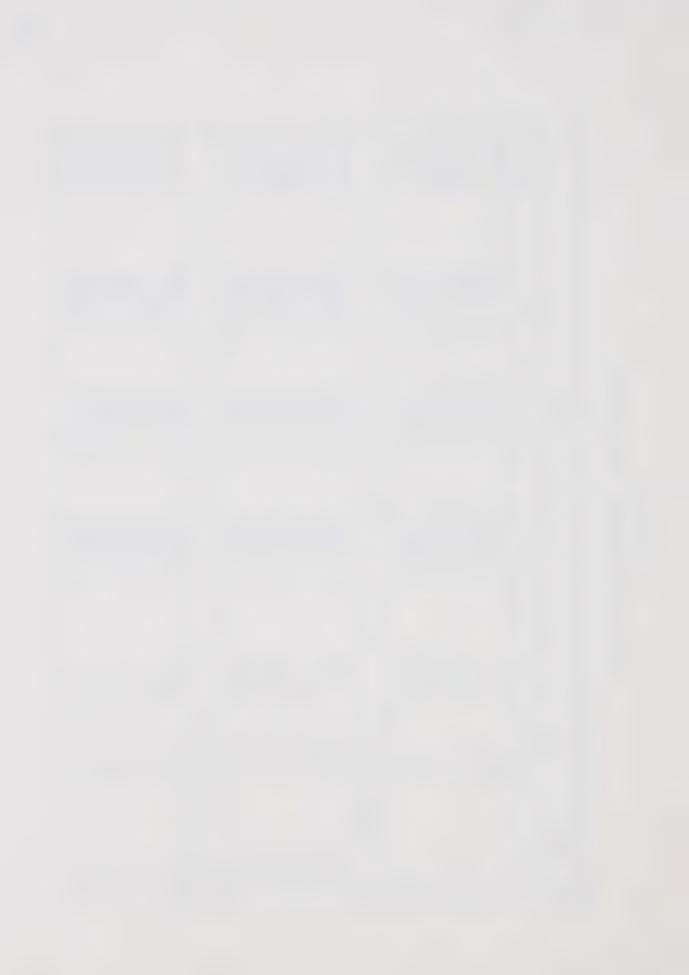


TABLE 5e

CONVECTION EFFECTS - NO INERTIA

	Ψ̄ Th (°F)	75800	. 76657 L All	78947	80574	81801	92	.88285 82.1		.66641 129.9	.67039 124.0	.67766 120.5	.68682 116.1	.69464 112.7	.70129 109.8	0.71628 103.15	.73277 93.0		.57831 131.1	.58175 128.3	.58717 125.0	58858 122.6	0.58995 120.23	.59125	, COTOT
= 43.06	ΙQ	0.1379	0.1427	0.1608	0.1817	0.1996	-0.24551	0.3289	= 43.06	0.1320	0.1362	0.1426	0.1586	0.1732	0.1875	-0.22548	0.2976	= 43.06	0.13328	0.13968	0.15044	0.16055	-0.17135	0.20041	0 25707
PE	M	.0443	.0492	.0602	.0682	.0743	0.08836	.1088	田山	.0331	1.00 0.03317 1.75 0.03598	.50 0.0392	.75 0.0439	.00 0.0474	6.25 0.0504	0.00 0.0572	.00 0.0672	PE	.0293	.0309	.0327	.0336	0.03470	.0371	0010
	Ъ	1.	5		0.	.2	10.00	0.0		0									1	5	. 7	0.	6.25	0.	
= 0.5	T _D (°F)						06		= 1.0	-	7		7	7	7		7	0 = 2.0					45		
(i) T _S /T	臣)						45		(ii) T _S /T _p	67.5	7	7	7	7	7	_	7	(iii) T _S /T					06		

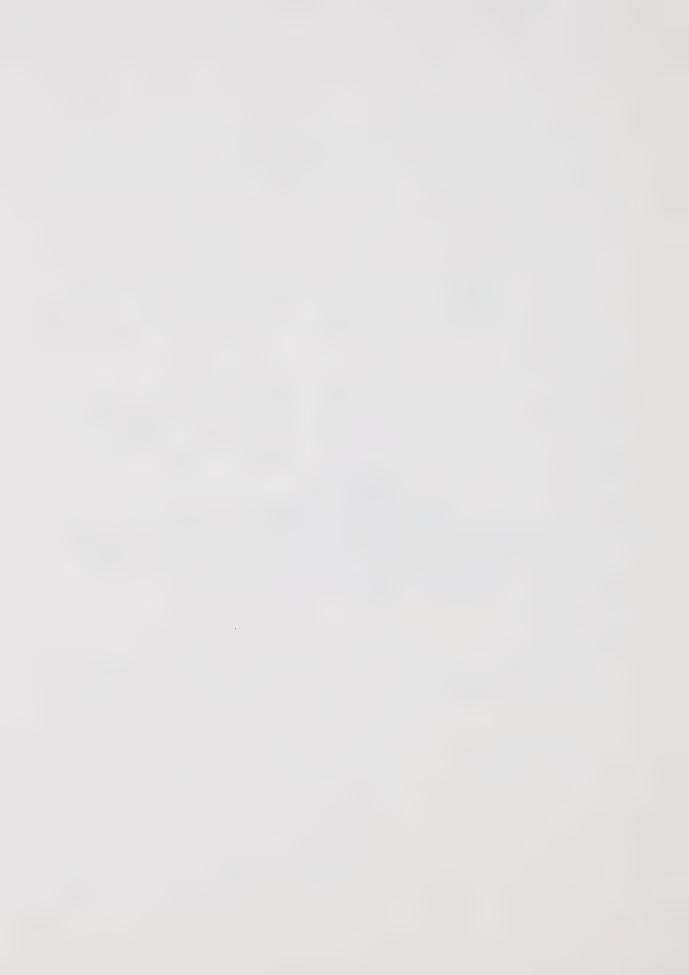


APPENDIX F

THE COMPUTER PROGRAMS

Written in FORTRAN $\overline{\text{IV}}$ for an IBM 360/67

Computer Using the MTS System



* IN THE SIXTH COLUMN INDICATES CONTINUATION FROM PREVIOUS LINE

```
C
                         J.HINDS COMPUTATIONSFOR THESIS TOPIC ON LUBRICATI
                      * ON
                     SOLUTION OF MOMENTUM FQUATION FOR CONSTANT VISCO
                       * SITY AND
                       AND WATER TO THE STATE OF THE S
C
                         CALCULATIONS FOR 2-D FLOW THROUGH BEARING USING STR
                      * FAM FON
                      TMPLICIT REAL *8 (A-H, N-Z)
                       DIMENSION X(11), Y(21), SUM(11,21), SUMY(11,21), DSUM(11,
                       * 21),FDY(11),
                       * 11,21),
                       *** ( | 1 . 1 ) , -Y: ( | ( , ) ) ) , a x ( | 1 . 1 ) . | ( | 1 . 1 ) , 1 . | . | . | . | . |
                      * A(1), 71),
                      *H(11),F(11,21),FY(11,21),C(11),D(11),CSUM(11),HF(11),T
                     · ( 1 / 11 , · 1 ) ,
                      ** (11,921), == (11, 1), == (11, 21), A(11, 1), A(1, 1), 
                      * 21),QYP(11),
                      * (11, 1), " (11, 11), " (11, 11), "(11, 1)), " (11, 1)
                     * M(21),
                      * 11),
                     · · · · · (11, 11), (11), T(11, 11), Tell F(11, 1), J, J, J, , , , , , , ,
                     * 1,21),
                     * (11), TA(11)
                        An(5,996)0X,07,X(1),Y(1),V(1),V(1),
       996 FORMAT(6E13.5)
                       READ(5,795)R, FPRES
         7100 - CONDENTED 1 7 1 7 1 7
                     READ(5,997) NUM
      997 FORMAT(12)
```

11 12 (11)

.

```
READ(5,597)RF
  I N=0
      MN=0
      11-1-11
     M = 1.1
     1 - 1
      N . 7 - . . -
     M1 = M - 1
C
      GENERATION OF POINT LOCATIONS IN FLUID FILM AND INITIA
      LIZE TEMP DIST
     DO 31 I=1.11
     IF(I.EQ.1)60 TO 3
     X(I) = X(I-1) + 0 X
    3 H(I) = R - X(I) * (R - 1.00)
     DO 4 J=2,N
      Y(J) = Y(J-I) + DY
   4 CONTINUE
   31 CONTINUE
    FVALUATION OF MASS FLOW FOR CONST VISCOSITY
     DO 104 I=1,11
     C(1) - - , 10/-(1) . > ?
     J(1)-120-17/22(1) 31577
  104 CONTINUE
     CSSUM=0.00
     DSSHM=0.00
     DO 107 I=3,11,2
     CSSUM = CSSUM + DX * (C(I) + 4 * D0 * C(I-1) + C(I-2))/3 * D0
         107 CONTINUE
     AFM=CSSUM/DSSUM
     EVALUATION OF PRESS GRADIENT AND STREAM FOR DIST F
     * DR CONST VISCOSITY
     DO 191 I=1.M
     DPDX(1)=C(1)-D(1)*AFM
     DD 38 J=1,N
     S(I,J) = H(I) **3*PPDX(I) **(J) **2/6.00-Y(J) /3.00
    2 41 47 7 / 6 0 0 ) /
    C
     EVALUATION OF GRAD'S DE STREAM FON
                                            IN
    X CIIIV
               H(I)**3*DPDX(I)*(Y(J)**2/2.D0-2.D0*Y(J)/3.D
     SY(1,J)=
    * 0+1.D0/6.D0)
    SYY(I,J)=
                H(I)**3*DPDX(I)*(Y(J)-2.D0/3.D0)/AFM-2.D0
  38 CONTINUE
 191 CONTINUE
     DO 212 I=1.M
```



```
00 213 J=1,N
                                11(1), 33-42-44-(1,3)/11(1)
             213 CONTINUE
              212 CONTINUE
                                  MITERED
                                  EPVAL=1.00
                                 GB TO 112
                                Carrier of the Carrie
            275 IN=IN+1
                                MN=MN+1
                                 ITER=ITER+1
                                DO 251 I=1.M
                               00 249 J=1.N
                              OSM(I,J)=RE*H(I)**2*(SY(I,J)*UX(I,J)-SX(I,J)*UY(I,J))
            249 CONTINUE
                                EVALUATION OF FIRST INTEGRAL
  C
                                7 17 (1,1)=0.00
                                DA 250 J=2.N
                                 J2=J/2
                              1.1.1000 , W. . 1) (1) TH 251
                                 IF(J.NF.2)GO TO 790
                               DSUM(I,4) = (DSM(I,1)+3.D0*(DSM(I,2)+DSM(I,3))+DSM(I,4))
                           本つ
                               DLSM=(DSM(I,2)+4.D0*DSM(I,3)+DSM(I,4))*DY/3.D0
                              ) · ( ( ) , · ) = ( ) . ( ( ) , a ) = ( ) . . . .
                               GD TO 250
           790 OSUM(I, J) = DSUM(I, J-3) + (DSM(I, J) + 3 \cdot D0 * (DSM(I, J-1) + DSM(I, J-1) + D
                          * ,J-21)+DSM(I
                          GD TO 250
              * (I,J-2))/3.0
                         ※ 〇
           25) CONTINUE
           251 CONTINUE
                               00 258 I=1,M
                                DEC. (1"1)-0"-0
                               NN=21
                               EVALUATION OF
                                                                                                              SECOND INTEGRAL
C
                               DR 255 J=2. NN
                               J2=J/2
                               IF(J2*2.NF.J)G0 TO 254
                              IF ( Jan 2 ) ... 70 1
                              PFSM(I,4)=(DSUM(I,1)+3.D0*(DSUM(I,2)+DSUM(I,3))+DSUM(I
                         * ,4))*3.00*0Y
                           */8.00
                             DPFSM=(DSUM(I,2)+4.D0*DSUM(I,3)+DSUM(I,4))*DY/3.D0
```

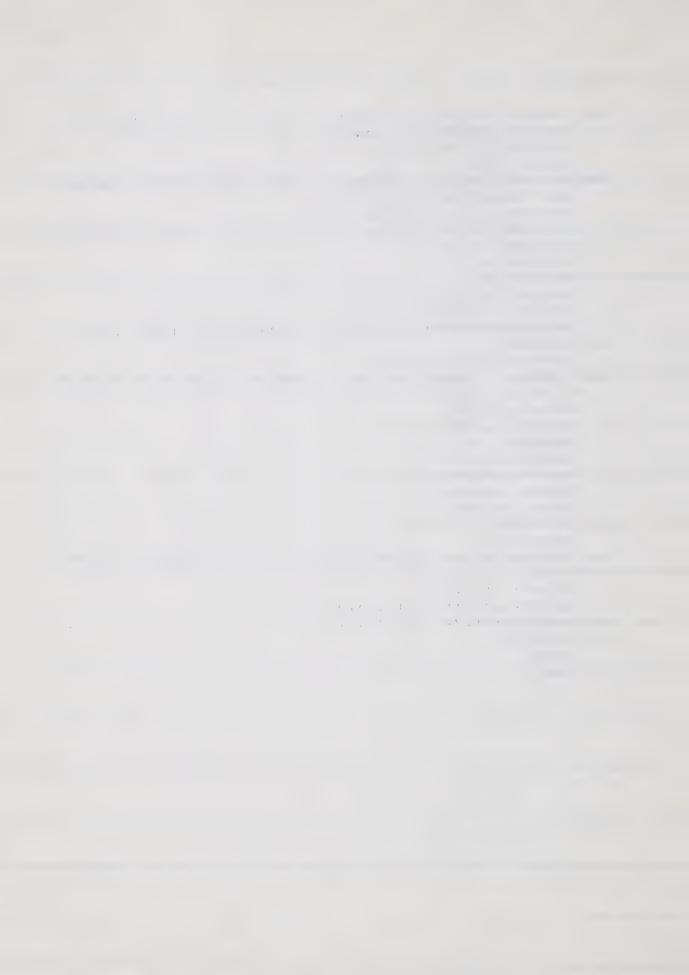
```
PESM(I,2)=PESM(I,4)-DPESM
             60 TO 255
  789 PFSM(I,J)=PFSM(I,J-3)+(DSUM(I,J)+3.D0*(DSUM(I,J-1)+DSU
           * M(I,J-2))+
           main (1, 1) - 1) Jan " 11 4 1 X 1 8 " 1)
             GO TO 255
  254 PFSM(I.J)=PFSM(I.J-2)+DY*(DSUM(I.J)+4.D0*DSUM(I.J-1)+D
          * - SIIM(1, 1-2))/
          *3.D0
  255 CONTINUE
  S28 COALINDE
            FVALUATION OF THIRD INTEGRAL
            00 260 I=1, M
            DA 262 J=2, NN
             J2=J/2
             TIJIKS.NE.J)GUTTI 75!
            IF(J.NE.2)GO TO 798
          * 1,41)*3.DO*
          *DY/P.DO
           NOTE OF A STATE OF A S
                 GO TO 262
  788 PESUM(I,J)=PESUM(I,J-3)+(PESM(I,J)+3.D0*(PESM(I,J-1)+P
          # ECM ( = 5 + = 7 + ) +
          *PFSM(I, J-3))*3.D0*DY/9.D0
            GO TO 262
                 * +PFSM(I,J-2)
         *1/3.00
The transfer of the property of
            C(I) = 6.00/H(I) **2
            D(I)=6.D0*(PFSM(I.N)-2.D0*PFSUM(I.N)+2.D0)/H(I) **3
  250 CONTINUE
            WRITE(6,105) (C(I), I=1,6)
           WRITE (6, 151) (C(I), I=7,11)
           WPITE(6,151)(D(I),I=7,11)
           FVALUATION OF NEW VALUE FOR MASS FLOW
                                                                                                                        USING SIMPSON
                15 RULE
            CSSUM=0.DO
           DSSUM=0.00
           CSSUM = CSSUM + DX * (C(I) + 4 \cdot D0 * C(I-1) + C(I-2))/3 \cdot D0
            CONTINUE
           AFM=CSSUM/DSSUM
```

```
` `!=: ` }
            ... ... [-1, 1]
            DPDX(I)=C(I)-D(I)*AFM
            * 1/11-11/11/
             EVALUATION OF STREAM FON DIST
            DO 215 J=1.N
           ) + 11( ) - 1(1)
          ***2/2.D0+C2(I)*Y(J)
             May 1 he still it is the description of the descrip
         * )+C1(I)*Y(J)
         *+C2(I)
          11(1,1). 1 18-1(1,1)/1(1)
  215 CONTINUE
      5 CONTINUE
           FVALUATION OF PRESS DIST IN FLUID FILM
112 CSUM(1)=0.00
           DFSUM(1)=0.00-
           00 61 1=2,10
            T2=I/2
            IF(I.NE.2)GO TO 785
           CSUM(4) = (C(1) + 3.D0 * (C(2) + C(3)) + C(4)) * 3.D0 * DX/8.D0
           DCSM=(C(2)+4.D0*C(3)+C(4))*DX/3.D0
           CSUM(2)=CSUM(4)-DCSM
          DESUM(4)=(D(1)+3.D0*(D(2)+D(3))+D(4))*3.D0*DX/8.D0
            DESUM(2)=DESUM(4)-DOSM
          GD TO 64
 785 CSUM(1)=CSUM(1-3)+(C(1)+3.D0*(C(1-1)+C(1-2))+C(1-3))*3
         * .D0*DX/8.D0
          DESUM(I) = DESUM(I-3) + (D(I) + 3 \cdot D0 * (D(I-1) + D(I-2)) + D(I-3))
              * 3 20 4 1 7 10 00
         *0
          GO TO 64
   62 CSUM(1)=CSUM(1-2)+DX*(C(1)+4.D0*C(1-1)+C(1-2))/3.
          DFSUM(I) = DESUM(I-2) + DX*(D(I) + 4 \cdot D0*D(I-1) + D(I-2))/3 \cdot D0
   64 P(I)=CSUM(I)-AFM*DESUM(I)
           IF(MN.EQ.0)GD TO 269
          IF(I.EO.2)EPVAL=DPVAL
           11 (10 1/10) ( 1 1 1 2 1 )
           IF (DPVAL . GT . FPVAL ) EPVAL = DPVAL
 269 P9(I)=P(I)
   SI CONTINUE
          WRITE (6,793) MN, AFM
```

```
793 FORMAT(* *,//,30X,*ITER EQUALS*,2X,13,3X,*MASS FLOW
                 * - 0 341 5 * 2 X 9
                    *D13.5)
                      WRITE (6,792) MN, FOVAL
         The state of the s
                 4- 9
                       WPITE(6:105)(P(T): I=1,6)
                       WRITE(6,151)(P(1),1=7,11)
        270 DD 109 I=1,M
                       "Y(1.N)=(U(1,N-2)+3.D0*U(1.N)-4.D0*U(1.N-1))/(2.00* 11)
                       UY(I,1)=(4.00*U(I,2)-3.00*U(I,1)-U(I,3))/(2.00*DY)
        267 DO 108 J=1,N
C EVALUATION OF GRAD'S DE STREAM FON IN X DIRE
                   * CTION
                    IF(I \cdot EO \cdot M) SX(I \cdot J) = (S(I-2, J) + 3 \cdot D0 * S(I, J) - 4 \cdot D0 * S(I-1, J))
                            /( *D(*DX)
                      IF(I \cdot EQ \cdot 1) SX(I \cdot J) = (4 \cdot D0 * S(I + 1 \cdot J) - 3 \cdot D0 * S(I \cdot J) - S(I + 2 \cdot J))
                   * /(2.D0*DX)
                   * *DX)
                      IF(I.EQ.M)UX(I,J)=(U(I-2,J)+3.D0*U(I,J)-4.D0*U(I-1,J))
                   * /(? . no*() X )
                     (F(1.F).)'!X(1.J)=(2.f)*(!+1.J)-4.Cm*(!1.J)-1(1*.,!))
                   * /(2.D0*DX)
                      IF(1.NF.1.AND.1.NF.M)UX(1.J)-("(141.1)-"(1-1.J))/(2.70
                      W XIIY
       108 CONTINUE
       109 CONTINUE
                      TI ("N. F.Q. 0) GO TO 445
                      IF(EPVAL.LT.EPRES) GU TO 445
                      GO TO 275
      445 PRIMI 211
      211 FORMAT(30X, 'RESULTS FOR VELOCITY DIST')
                      DG 502 I=1, M
                     2011 (1) V2 (13) A(1"1) \ A(1) 12 13 42
                      · [ ] ( [ [ ] , ] ) ( [ [ ] , ] ) ( ] [ ] )
                     WRITE (6.161)(U(I,J),J=13.21)
         was a second of the
      105 FORMAT(2X,6(D13.6,2X)/)
      151 FORMAT(2X,5(D13.6,2X)/)
      23 FORMAT(2X,12(F9.4,1X)/)
     161 FORMAT(2X,9(F9.4,1X)/)
                    IF(MN.GT.O)PRINT 277
                       Control to the transfer of the
                    PRINT 140
```

c c

```
140 FORMAT(30X, FINAL RESULTS FOR PRESS DIST!)
                                   WRITE (6, 105) (P(1), T=1,6)
                                   WRITE(6,151)(P(I),I=7,11)
                                  PRINT 794
                                   The same of the sa
                                  . 21 * · ( .103)((DY(1), ! =1 . ·)
                                 WRITE(6,151)(FDY(I),I=7,11)
C EVALUATION OF LOAD CAPACITY OF BEARING AND FRICTIONAL ...
                            * FORCE ON RUNNER
                                 FSUM=0.DO
                                 DSUM=0.00
                                 ) / / 4 / - / 4 1 1 3
                                 PSUM=PSUM+(P(I)+4.00*P(I-1)+P(I-2))*DX/3.00
                                 F DIVE CORMAR (* ) * (*) * 4 * JUNEL J. (1-1) * D. (3 - 23) . . . . . .
        444 CONTINUE
                               17-(/,44)
           ALL CONTRACTOR OF A STATE OF A ST
                           * IDRAG FQUAL
                         - IF(MN.F0.0)60 TO 275
                                ANS(11,1)=R
                                ANS(I1,2)=PSUM
                                120(1100)
                                ANS(11.4)=AFM
                                ANS(11,5)=RE
     1000-CONTINUE ---
                      PRINT 698
         698 FORMAT("1",////,30X, "RESULTS
                                                                                                                                                                                                                OF NUMERICAL
                                                                                                                                                                                                                                                                                                     ANALYSIS
                        * +)
                          DO 691 I1=1, NUM
                            WRITE(6,700)(ANS(II,J),J=1,5)
         700 FORMAT(+++,//3X,5(513.5,2X))
         691 CONTINUE
                                STOP
```



* IN THE SIXTH COLUMN INDICATES CONTINUATION FROM PREVIOUS LINE

```
C
      J. HINDS COMPUTATIONSFOR THESIS
                                         TOPIC ON LUBRICATI
     * CN
      SOLUTION OF MOMENTUM AND
                                     ENERGY
                                             EQUATIONS
                                                         FOR V
     * ARIABLE
     *VISCOSITY AND IMCLUDING INTERTA TRANS
C
     CALCULATIONS FOR 2-D FLOW THROUGH BEARING USING STR
     * EAM FCN
      IMPLICIT REAL*8 (A-H,C-Z)
     DIMENSION X (11), Y (21), SUM (11, 21), SUMY (11, 21), DOG. (11,
     * 21), FDY(11),
     *DSM(11,21), PP(11,21), PFSM(11,21), P(11), OPDX(11), SX(
     * 11,21),
     *SY(11,21),SYY(11,21),SHX(11,21),SHY(11,21),S(11,21),TH
     * ETA(11,21),
     *H(11), F(11,21), FY(11,21), C(11), D(11), CSUM(11), HF(11), T
     * HETB (11,21),
     *B(11,21),BF(11,21),AF(11,21),A(11,21),AEF(11,21),2(11,
     * 21), CYP(11),
     *oys(11),*(11,21),33(11,21),ao(11,21),cs(11,21),535(21)
     * ,ISI(21).
     *SM(11,21),SMY(11,21),DF(11,21),DFY(11,21),TSIM(21),TSE
     * M(21),
     *DESUM(11), DTDYP(11), DTDYS(11), C1(11), C2(11), CN(11), DN(
     * 11),
     *PFSUM(11,21),PB(11),T(11,21),THET(11,21),U(11,21),UX(1
     * 1,21),
     *UY(11,21), RTHET(11,21), E(11,21), ANS(30,30), V(11,21), 14
     * (11),TA(11)
     CALL INV
      PRINT 994
 994 FORMAT ('1',30X,'DATA USED IN ANALYSIS',//)
FRAD IN VALUES OF DIMENSIONAL CONSTANTS
     READ (5,996) TK, ROE, CPEC, CPPR, EMUO, TI
 996 FORMAT (6E13.5)
      THITE (6,695) TH, SCY, CPFC, CIPE, BMJO, TI
```



```
995 FORMAT (* *,2X,6(E13.5,2X))
    MEAD (5, 996) DX, DY, X (1), Y (1), P (1), P (11)
    WRITE (6,995) DX, DY, X (1), Y (1), P (1), P (11)
    RFAC (5, 999) ETHET, EPRES, BT, CNTHT
993 ICEMAI (4E13.5)
    READ (5, 28) TS, TP, VEL, IN, T1, TAA, R, AL, HO
 28 FORMAT (3F7. 2,6F8.5)
   CFAC (5, 957) 844
997 FORMAT (12)
    DO 1000 I1=1, NUM
    READ (5,597) RT
597 FORMAT (E13.5)
499 WRITE (6,993) ETHET, EPRES
993 FORMAT ( 1, 2X, CCNVERGENCE
                                   CRITERIA ON TEMP', 2X, F6.
   * 4,4X,
   * CONVERGENCE CHIEFLA C.
                                   Px235U(11,27,76.4)
    4 MITE (6, 29) IS, IE
 29 FOR 1AT (28, SLIDEL TEMP DOUALS', 28, F6. 2, 28, PAT TIME
   * FQUALS',
   *24, F6.2,2X)
    WRITE (6,998) R
998 FORMAT ( 1, 2X, INLET TO OUTLET RATIO EQUALS 1, 2X, F4
   * .2,3 Y)
    PRINT 276
276 FORMAI( ',////,3CX, RESULTS NEGLECTING INSETTA TE
   * FMS!)
    NA = 0
    IN = 0
    MN = 0
    IAV = (TP + IS) / 2.D0
    DT=TAV
    ETDT=31*DT
    ISTP=IS/TP
    N = 21
    M = 11
    N1 = N - 1
    N3=N-3
    v_1 = M - 1
    CAIL VIS(TAV, EUTAV)
    PRL=CPPR*FUTAV/TK
    EC=VEL**2/(CPEC*DT)
    PEC=PRL*EC
    PF=PRL*RE
    CEDRE=PEC/PE
    RPEC=1. DO/PE
    FEDYS=PE*DY**2
    G=1.DO/PEDYS
    WRITE (6, 294) PE, PEC
```

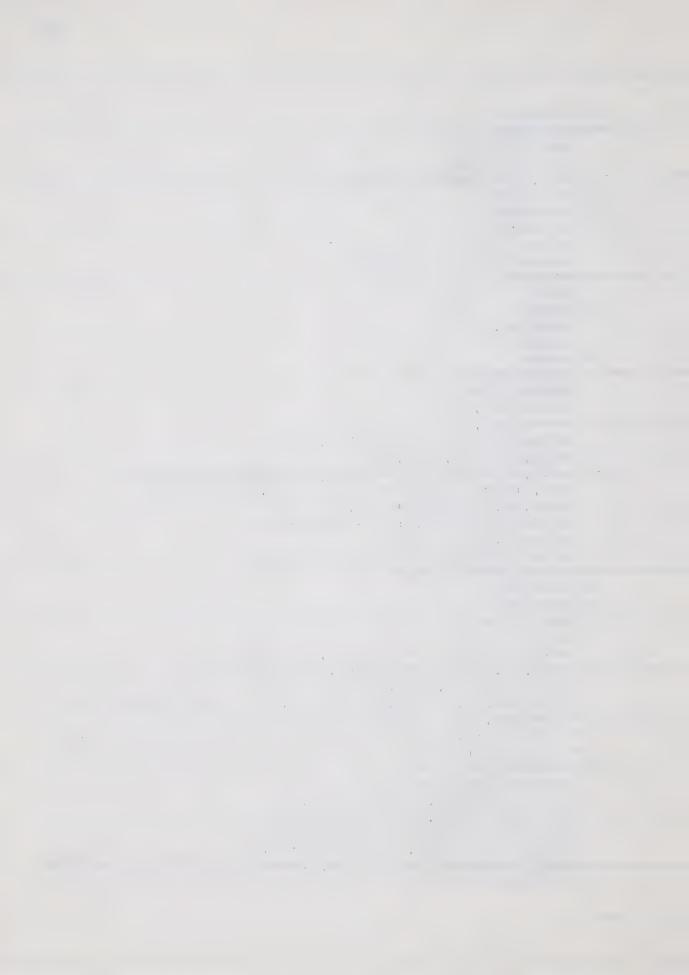


```
294 FORMAT (2X, PECLET EQUALS, 2X, D13.6, P*EC EQUALS, 2X,
   * 013.61
    WRITE (6, 190) RPEC, CEDSE, PAL
190 FORMAT (2X, 1.0/PECLET EQUALS 1, 3X, D13.6, 2X, EC/RE EQU
   * ALS',3X,D13.
   *6,2X, 'PRL EQUALS',2X,E13.6)
    GENERATION OF POINT LOCATIONS IN FLUID FILM AND INITIA
   * LIZE TEMP DIST
    DO 31 I=1,11
    IF (I.EQ. 1) GO TO 3
    \lambda(1) = \chi(1-1) + \mu \chi
  3 H(I) = R - X(I) * (R-1.D0)
    THETA (I.N) = IN
    7417 Tr (1, N) = Tremn(1, N)
    THETA (I, 1) = I1
    THETB (I, 1) = THETA (I, 1)
    IG 4 J=2,N
    Y(J) = Y(J-1) + DY
    THEIA (1, J) = TAA * Y (J) + T1
    THE TO (1, J) = 9 HLTA (1, J)
  4 CONTINUE
 31 CONTINUE
    RVALUATION OF PASS FICE TOP CONST VISCOSIPY
    DO 104 I=1,11
    C(I) = 6.D0/H(I) **2
    \Sigma(I) = 12. E(I + (1) **?
104 CONTINUE
    CSSUM=0.DO
    USSUM=0.DO
    DO 107 I=3,11,2
    CSSUM = CSSUM + DX * (C(I) + 4.D0 * C(I-1) + C(I-2))/3.D0
    1580 = 1880 + 18 * (D(I) + 4.50 * P(T-1) + D(I-3)) /3. Do
107 CONTINUE
    AFM=CSSUM/DSSUM
    IVALUATION OF PRESS GRADIENT AND "TELAT FOR DIST
   * OR CONST VISCOSITY
    DO 191 I=1, M
    DPPX(I) = C(I) - DII) * TPE
   DO 38 J=1, N
    S(I,J) = H(I) **3*DPDX(I) *Y(J) *(Y(J) **2/6.D0-Y(J)/3.D0
   * +1.D0/6.D0)/
   *AFM+Y(J)*(2.D0-Y(J))
    EVALUATION OF GRAD'S OF STREAM FON
                                                IN
                                                            DIRE
   * CTION
    SY(I,J) = H(I) **3*DPDX(I) * (Y(J) **2/2.D0-2.D0*Y(J)/3.D
   * 0+1.D0/6.D0)
   */AFM+2.D0*(1.D0-Y(J))
    SYY(I,J) = H(I) **3*DPDX(I) * (Y(J) -2.D0/3.D0)/AFM-2.D0
```

C

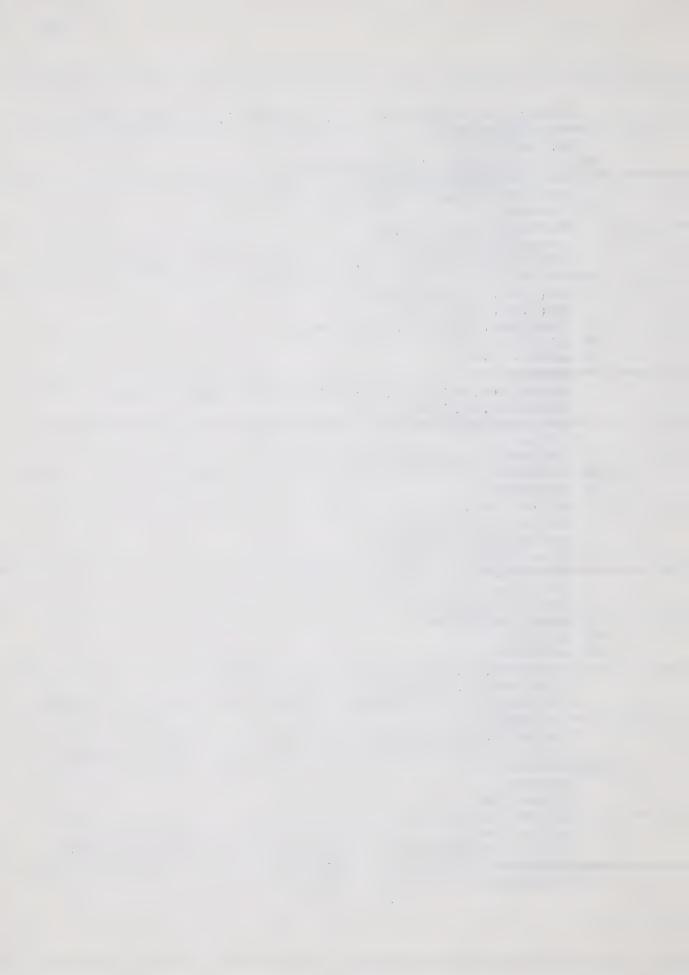


```
38 CONTINUE
   191 CONTINUE
      DO 212 I=1.M
       DO 213 J=1, N
       U(I,J) = AFM*SY(I,J)/H(I)
  213 CONTINUE
  212 CONTINUE
       NITER=()
       GO TO 112
C
       EVALUATION OF TEMP DIST
   113 NETER=0
       例例(三)
   63 ITER=:)
       EPVAL=1.DO
       MM = MM + 1
   25 NN=21
       NITER=NITER+1
       ITER=ITER+1
       DO 46 I=1.M1
       10 47 J=2, N1
       BF(I,J) = G + HF(I) * AFM * SHY(I,J) / DX
       BE(I,J) = BF(I,J) - 2.D0*G
    77 AH(I,J) =- (PF(I) *AFM*SHX(I,J)/(4.F)*BY) +G/2.D)
       A(I,J) = -(G/2.DO-HF(I) *AFM*SHY(I,J)/(4.D)*FY)
       IF(J.EQ.2)W(I,J) = +BF(I,J)
       If (J, \mathbb{R}^n, \mathbb{C}, \mathbb{C}) Alf (\mathbb{T}, J) = \mathbb{A} \mathbb{H} (\mathbb{T}, J) / \mathbb{W} (\mathbb{T}, J)
       IF (J.EQ.2) GO TO 47
       W(I,J) = +BF(I,J) - ALF(I,J-1) * A(I,J)
       ALF(I,J) = Ah(I,J)/W(I,J)
   47 CONTINUE
   46 CONTINUE
       DO 75 T=1, M1
       DO 77 J=2.N1
       IE (J. EC. N 1) CNS = IHPTA (1+1, N) * (-AH (I,J))
       IF (J. EQ. 2) CNS1=THETA (I+1, J-1) * (-A(I, J))
       IF (J. NE. 2. AND. J. NE. N1) CNST=0.DO
       IF (NITER. EQ. 1) B (I, J) = THETA (I, J-1) * (-A(I,J)) + THETA (I, J
      * ) * * (I, J) +
      *THETA(I,J+1)*(-AH(I,J))+CEDBE*((SYY(I,J)+SYY(I+1,J))*A
      * FM/HF(I)) **2
      #/4. DU+CMST
       IF (NITER.EQ. 1) GO TO 98
       IF(T(I,J).GT.2.3D2) VII=AB(I,J)
       IF(T(I+1,J).CT.2.3D2) VII1=AB(T+1,J)
       IF (T (I, J) . LE. 2. 3D2) VII=V (I, J)
       IF(T(I+1,J).LE.2.3D2) VII1=V(I+1,J)
       E(1,J) = THETA(1,J-1) * (-A(1,J)) + FHITA(T,J) * 17(T,J) * 191,TA
      * (I,J+1) *
```



```
* (-AH (I,J)) + CEDRE* ((SYY (I,J) + SYY (I+1,J)) * AFM/HF (I)) **2*
   * ( VII+VII1) /
   *8.D0+CNST
 98 IF (J.EQ.2) Z (I,J) = B(I,J) / W(I,J)
     1 (J. EQ. 2) GO TO 77
     Z(I,J) = (B(I,J) - A(I,J) * Z(I,J-1)) / W(I,J)
 77 CONTINUE
     THETA (I+1, N1) = 7 (I, N1)
     IF (NITER. EQ. 1) GO TO 99
     DFVAL=EABS ( (THETA (I+1, N1) - THETB (I+1, N1) ) / THETA (I+1, N1)
     IF (I.EQ. 1) EQVAL=DEVAL
     IF (I.EO. 1) GO TO 99
    IF (DPVAL.GI. EQVAL) FOVAL=DFVAL
 99 DO 76 K=1.N3
    NK1 = N - (K+1)
    NA = N - A
    THETA (I+1,NK1) = Z(I,NK1) - ALF(I,NK1) * THETA(I+1,NK)
    IF (NITER. EQ. 1) GO TO 76
    DFVAL=DABS ( (THETA (I+1, NK1) -THETB (I+1, NK1) ) /THETA (I+1, N
   * (1))
    IF (DFVAL.GT. EQVAL) EQVAL=DFVAL
    CONTINUE
 75 CONTINUE
    DO 117 I=1, M
    DO 116 J=1, N
    THETB(I, J) = TEETA(I, J)
    I(I,J) = DI * THETA(I,J)
    IMP-I(I,J)
    IF (I (I, J).GI.2.3D2) GO TO 116
    CALL VIS (TMP, VI)
    V(I,J)=VI/EUTAV
116 CONTINUE
117 CONTINUE
    IF (NITER. EQ. 1) 30 TC 25
    IF (FCVAL.GT. ETHET) GO TO 25
    EVALUATION OF INTEGRAL CONSTS FOR STREAM FOR DIST
   * PITTICM
  IF (MN.EQ.0) GO TO 252
   EVALUATION OF CONTRIBUTION DUE TO
                                               INERTIA
175 IN=17+1
    MN = MN + 1
    ITER=ITER+1
    DO 251 I=1.M
    DO 249 J=1, N
    DSM(I,J) = RE*H(I) **2* (SY(I,J) *UX(I,J) - SX(I,J) *UY(I,J))
249 CONTINUE
    EVALUATION OF FIRST
                              INTEGRAL
```

C



```
DSUM(I, 1) = 0.00
       PO 250 J=2.1
       J2=J/2
       IF (J2*2.NE.J) GO TO 256
       JF (J. NE. 2) 150 20 795
      1.39 \times (1,4) = (13^{+}(1,1) + 3.06 * (05 * (1,2) + 05 * (1,3)) + 05 A (1,4))
      * *3.D0*DY/8.D
      李门
       DISM= (13* (1,2)+4.00*LSP(1,3)+D3Y(1,4))*DY/3.01
       LSUM(I,2) = DSUM(I,4) - DLSM
      GO TO 250
  790 DSUM (I,J) = DSUM(I,J-3) + (DSM(I,J) + 3.D0 * (DSM(I,J-1) + DSM(I
     * , J-2) + DSM (I)
      *, J-3)) *3. [0*1 v/0. ])
       GO TO 250
  256 DSUM (I, J) = DSUM (I, J-2) + DY* (DSM (I, J) + 4. DO*DSM (I, J-1) + DSM
     * (1, J-2))/3.1
     *()
  250 CONTINUE
  251 CONTINUE
      NN=21
      DO 258 I=1,M
       PFS8 (1, 1) = 0. Do
C
      EVALUATION OF
                         SECCND
                                  INTEGRAL
      DO 255 J=2,NN
      32=3/2
      IF (J2*2.NE.J) GO TO 254
      IF (J.NF.2) GC TO 789
      Prom(1,4) = (130 (1,1) +3.00* (LSUN(1,2) +384M(1,3)) +086M(1
     * ,4))*3.DO*DY
     */3.00
      DPFSM= (DSUM (I, 2) +4.DO*DSUM (I, 3) +DSUM (I, 4) ) *DY/3.DO
      PFSM(I,2) = PFSM(I,4) - DPFSM
      GO TO 255
  780 PEST (T,J) = EFSM (E,J-3) + (DSUM (E,J) +3. D0* (DSUM (E,J-1) +DSU
     7 (1,3-2))+
     *DSUM(I,J-3))*3.D0*DY/8.D0
     GO TO 255
  254 PFSM (I,J) = PFSM(I,J-2) + DY*(DSUM(I,J) + 4.D0*DSUM(I,J-1) + D
     * SUM(I,J-2))/
     *3.DO
  255 CONTINUE
  258 CONTINUE
      EVAIUATION OF THIPL INTEGRAL
      DO 260 I=1,M
      PFSUM(I,1)=0.D0
      DC 262 J=2, NN
      32=3/2
```

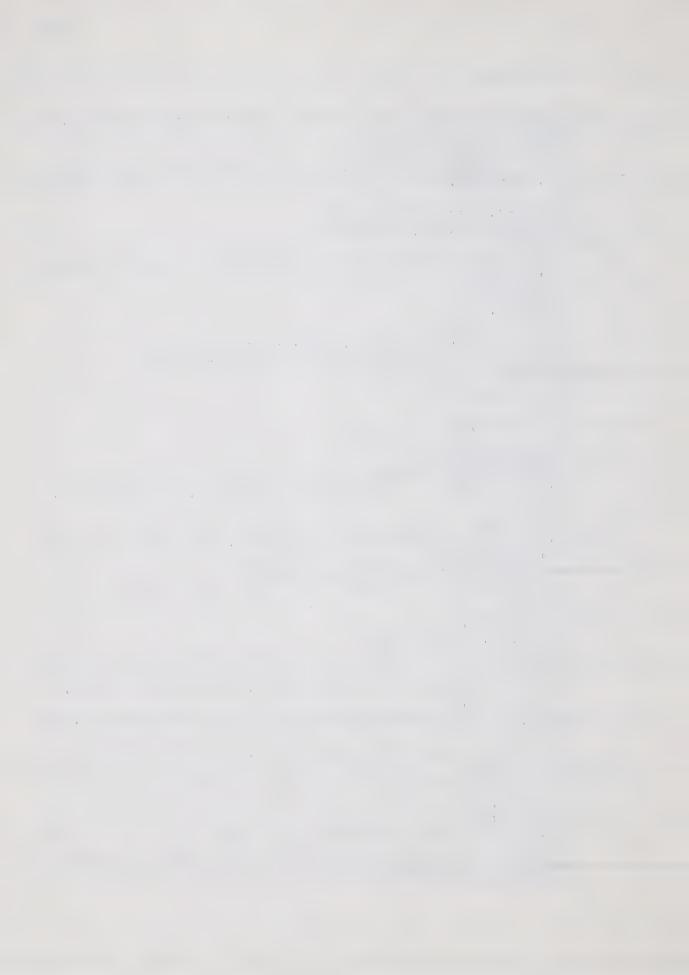


```
IF (J2*2.NE.J) GO TO 261
    IF (J. NR. 2) GO TO 788
     PFSUM(I,4) = (PFSS(2,1)+2.D0*(PFSE(I,2)+P15*(I,3))+FFSE(
   * I,4))*3.DO*
   *DY/8.DO
    DPSUM= (PFSM(I,2)+4.DO*PFSM(I,3)+PFSM(I,4))*DY/3.DO
    PFSUM (I, 2) = PFSUM (I, 4) - DPSUM
    GO TO 262
788 PFSUM(I,J) = PFSUM(I,J-3) + (PFSM(I,J) + 3.D0 * (PFSM(I,J-1) + P
   * FSM(I, J-2)) +
   *DEG = (1, J-3)) *3.00*0 Y/5.00
    31 10 202
261 PFSUM(I,J) = PFSUM(I,J-2) + DY* (PFSM(I,J) + 4. DO*PFSM(I,J-1)
   * FFISK(I,J-2)
   *)/3.DO
262 CONTINUE
260 CONTINUE
252 IO 18 I=1,M
    SM(I,1) = 0.00
    SMY (I, 1) = 0. DO
    D0 5 J=1.N
    IF (T(I,J) \cdot LE \cdot 2 \cdot 3D2) F(I,J) = 1 \cdot D0/V(I,J)
    TE (11, J) . 17. 2. 312) GC TO 83
    F(I, J) = DEXP(BTDT*(THETA(I, J)-1.DO)/(1.DO+DT*(THETA(I, J
   * )-1.D0)
   */CNTHT))
    AB(I,J) = 1.D0/F(I,J)
 83 FY(I,J) = F(I,J) *Y(J)
  5 COLTINAT
    NN = N
    DO 15 J=2,NN
    32=3/2
    IF (J2*2.NE.J) GO TO 8
    IF (J.NE. 2) GO TO 787
    SM(1,4) = (F(1,1) + 3.00 * (E(1,2) + F(1,3)) + *(1,4)) * *1. Pri* F/?
   * . DO
    DSMM = (F(I,2) + 4.D0*F(I,3) + F(I,4))*DY/3.D0
    SM(I,2) = SM(I,4) - LSMM
    SMY(I,4) = (FY(I,1)+3.D0*(FY(I,2)+FY(I,3))+FY(I,4))*3.D0
   * *DY/8.D0
    DSMY=(FY(I,2)+4.DU*FY(I,3)+5Y(I,4))*NY/3.70
    SMY(I,2) = SMY(I,4) - DSMY
    GO IO 15
787 SM(T,J)=SM(I,J-3)+(F(I,J)+3.00*(F(I,J-1)+F(I,J-2))+F(I
  * ,J-3))*3.DC*
   *EY/8.DO
   **Y(!,d)-$MY(!,J-3)+(FY(!,J)+3.D0*(FY(!,J-1)+FY(!,J-2)
   * ) + FY (1, J-3))
```



```
**3.D0*BY/8.D0
           GO TO 15
       8 SM(I,J) = SM(I,J-2) + DY*(F(I,J) + 4.D0*F(I,J-1) + F(I,J-2))/3
         * . DO
           SHY (1, J) = S:Y(1, J-2) + D ** (FY (1, J) + 4, D) * FY (1, J-1) + F? (1, J-
         * 2))/3.E0
    15 CONTINUE
    18 CONTINUE
            NN=N
            FVALUATION OF 2'NO INTUGRAL CONSTR FOR STIFAM F
          * ( 1751
            DO 180 I=1.M
            SUM(I, 1) = 0.D0
            SUMY (I, 1) = 0.D0
            DO 181 J=2, NN
            UZ=3/2
            IF (J2*2.NE.J) GO TO 193
            IF (J.NE. 2) GO TO 786
            SUM(I,4) = (SM(I,1) + 3.D0*(SM(I,2) + SM(I,3)) + SM(I,4))*3.D0
         * *LY/8.DU
            DSUMM= (SM(I,2) + 4.D0*SM(I,3) + SM(I,4))*DY/3.D0
            SUM (I, 2) = SUM (I, 4) - DSUMM
            SDMY(T, 4) = (SMY(T, 1) + 3. DO*(SMY(T, 2) + SMY(T, 2)) + SMY(T, 3))
        * *3.D0*DY
        */8.DO
            DSMMY= (SMY (I, 2) +4. DO *SMY (I, 3) + SMY (I, 4)) *DY/3. DO
           SUMY(I,2) = SUMY(I,4) - DSMMY
           GO TO 181
786 308(1,J)=508(1,J-3)+(54(1,J)+3.50*(58(1,J-1)+54(1,J-2)
        * ) +SM (I, J-3))
        **3.DO*DY/8.DO
         SIMY(I, J) = SIMY(I, J - s) + (SMY(I, J) + 3. PO*(SMY(I, J - 1) + SMY(I
        * , J-2)) + SMY
        *(I,J-3))*3.D0*DY/8.D0
          50 10 101
183 SUM (I,J) = SUM(I,J-2) + DY* (SM(I,J) + 4.D0*SM(I,J-1) + SM(I,J-1)
        * 2))/3.DO
           SUNY(I,J) = SUMY(I,J-2) + DY*(SMY(I,J) + 4.DO*SMY(I,J-1) + SMY
        * (I,J-2))/3.D
       35 (3
131 CONTINUE
          IF (MN.GI.O) GO TO 263
          CN(I) = (SUMY(I, NN) - SMY(I, NN)) *SM(I, NN) / (SUM(I, NN) - SM(I, NN)) + SM(I, NN) / (SUM(I, NN)) - SM(I, NN) 
              NNI
          DN(I) = SM(I,NN) / (SUM(I,NN) - SM(I,NN))
          C(I) = -1.D0/(H(I) **2*(SMY(I,NN) - CN(I)))
          T(1)=04(I)/(
                                                   H(I)**3*(SMY(I, NN)-CN(I)))
          GO TO 180
```

```
263 CN (I) = (SM (I, NN) * (1.DO-PFSUM (I, NN)) + PFSM (I, NN) *SUM (I, NN
             * ))/
             * (SUM (I, NN) - SM (I, NN))
               DN(I) = (SUM(I,NN) *SMY(I,NN) - SM(I,NN) *SUMY(I,NN)) / (SUM(I,NN)) = (SUM(I,NN)) / (SUM(I,NN)) + (SUM(I,NN)) / (SUM(I,NN)) + (SUM(I,NN)) / (SUM(I,NN)) + (SUM(I,NN)) / (SUM(I,NN)) + (SUM(I,NN)) / 
                     , NN) -Se (I, NN
             *))
                C(I) = -1.D0/(H(I) **2*DN(I))
                D(I) = CN(I) / (H(I) **3*DN(I) +
      180 CONTINUE
C
               EVALUATION OF NEW VALUE FOR MASS FLOW
                                                                                                                             USING SIMPSON
              * 'S RILLE
               CSSUM=0.DO
                DSSUM=0.DO
                DO 52 I=3,11,2
                CSSUM = CSSUM + DX * (C(I) + 4.D0 * C(I - 1) + C(I - 2)) / 3.D0
               DSSUM=DSSUM+DX* (D(I)+4.D0*D(I-1)+D(I-2))/3.D0
         Z CONTINUE
                AFM=CSSUM/DSSUM
                NN=21
                DO 55 1=1,11
                DPDX(I) = C(I) - D(I) *AFM
               C2(I) = H(I) / AF
               IF (MN.GT.O) GG TO 264
               C1(I) = -(C2(I) + H(I) **3*DPDX(I) *SMY(I, NN) / AFM) / SM(I, N)
            * (1)
               00 00 265
     264 C1(I) = (1.D0+H(I) ** 3*DPDX(I) * (SMY(I, NN) - SUMY(I, NN)) / AFM
            * + (PFSM(I,NN)
            *-PPSUM(I,NN)))/(SUM(I,NN)-SM(I,NN))
             EVALUATION OF STREAM FON DIST FOR VARIABLE VISC
            * CSITY
     265 DO 215 J=1,NN
               IF (MN. GT. 0) GC TO 266
               EVALUATION OF GRAD'S OF STREAM
                                                                                                             FCN IN
                                                                                                                                                    DIRE
            S. CITCH
               S(I,J) = H(I) **3*DPDX(I) *SUMY(I,J) /AFM+C1(I) *SUM(I,J)
             * +C2(I) *Y(J)
               SY(T,J) = H(T) **3*DTDY(T) *SMY(T,J) /APM+C1(T) *SMY(T,J) +
             * C2(I)
               SYY(I,J) = H(I) **3*DPDX(I) *FY(I,J) / AFM+C1(I) *F(I,J)
    266 S(I,J) = H(I) **3*DFDX(I) *SUMY(I,J) / AFM+PFSUM(I,J) +C1(I) *
            * SUM (I, J) +
            *C2(I) *Y(J)
                                                         GRADIENTS OF STREAM FON IN Y DIR
               EVALUATION OF
            * ECTION
               SY(1.J)=H(1)**3*DFDX(I)*SMY(I,J)/AFM+PFSM(I,J)+C1(I)*S
            * M(I,J) + C2(I)
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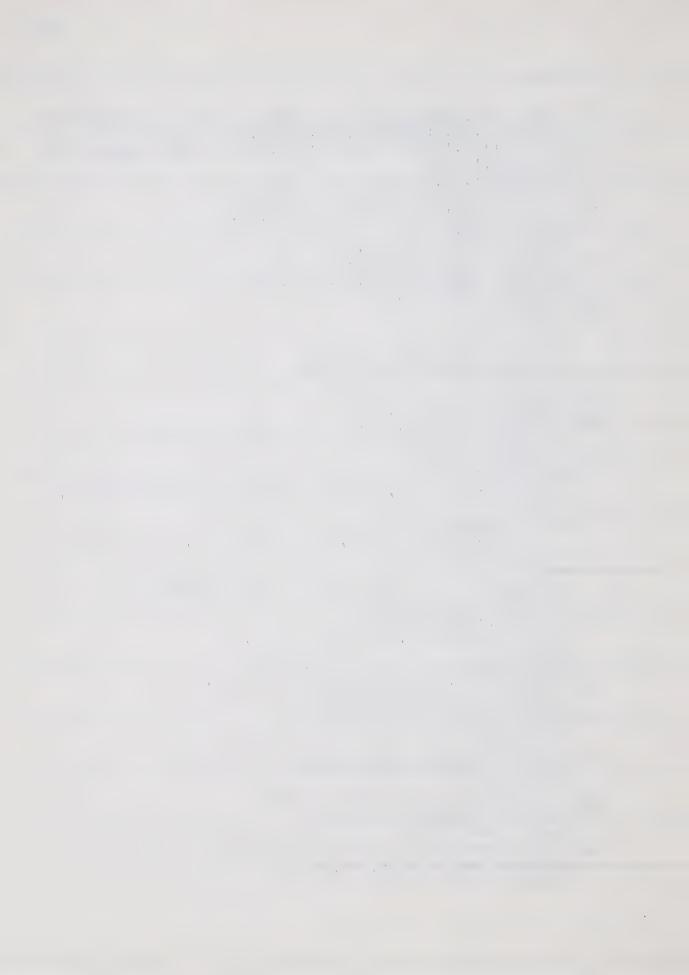


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SYY(I,J) = H(I) **3*DPDX(I) *FY(I,J) / AFM + DSUM(I,J) + C1(I) *F
    * (I,J)
215 CONTINUE
 55 CONTINUE
     DO 214 1=1,M
     IO 216 J=1.N
     U(I,J) = AFM * SY(I,J) / H(I)
216 COMPINUE
214 CONTINUE
     EVALUATION OF PRESS DIST IN FLUID FILM
112 \text{ CSUM}(1) = 0.00
     DESUM(1) = 0.D0
     DO 61 I=2.10
     I2=I/2
     IF (12*2.NE. I) GO TO 62
     IF (I.NE. 2) GO TO 785
     CSUM(4) = (C(1) + 3.00*(C(2) + C(3)) + C(4))*3.00*DY/9.00*
     DCSM = (C(2) + 4.D0 * C(3) + C(4)) * DX/3.D0
     CSUM(2) = CSUM(4) - DCSM
     DESUM (4) = (D(1) + 3.D0*(D(2) + D(3)) + D(4)) *3.D0*DX/8.D0
    DDSM = (D(2) + 4.D0*D(3) + D(4))*DX/3.D0
     DESUM(2) = DESUM(4) - DDSM
    GO TO 64
785 CSUM(I) = CSUM(I-3) + (C(I) +3.D0*(C(I-1)+C(I-2))+C(I-3)) *3
   * .DO*DX/8.DO
     DESUM (I) = DESUM (I-3) + (D(1)+3.70* (D(I-1)+D(I-2))+D(I-3))
   * *3.D0*DX/8.D
   *()
    GC 10 64
 62 CSUM (I) = CSUM (I-2) + DX* (C(I) + 4.D0*C(I-1) + C(I-2))/3.D0
     DESUM (I) = DESUM (I-2) + DX* (D(I) + 4. D0* D(I-1) + D(I-2))/3. D0
 64 P(I) = CSUM(I) - AFM*DESUM(I)
     IF (ITER. EQ. 1. AND. IN. EQ. 0) MN = 1
     IF (ITER. EQ. 1. AND. IN. EQ. 0) ITER=0
    11 (1x.10.0) 90 TO 263
    IF (IN. EQ. 1. AND. ITER. EQ. 2) MN=1
    IF (IN. EQ. 1. AND. ITER. GE. 2) GO TO 269
    PPVAL = PABS((P(I) - PB(I))/P(I))
    IF (I.EQ. 2) EPVAL=DPVAL
    IF (I.EQ. 2) GO TO 269
     IT (DIVAL.GI. FFYAL) FFVAL=DPVAL
269 PB(I) = P(I)
61 CONTINUE
    1 F (MN. EC. ") CC PC 241
    IF (IN. EQ. 0) GC TO 291
    IF (IN. EQ. 1. AND. ITER. GE. 2) GO TO 291
291 CONTINUE
270 DO 109 I=1, M
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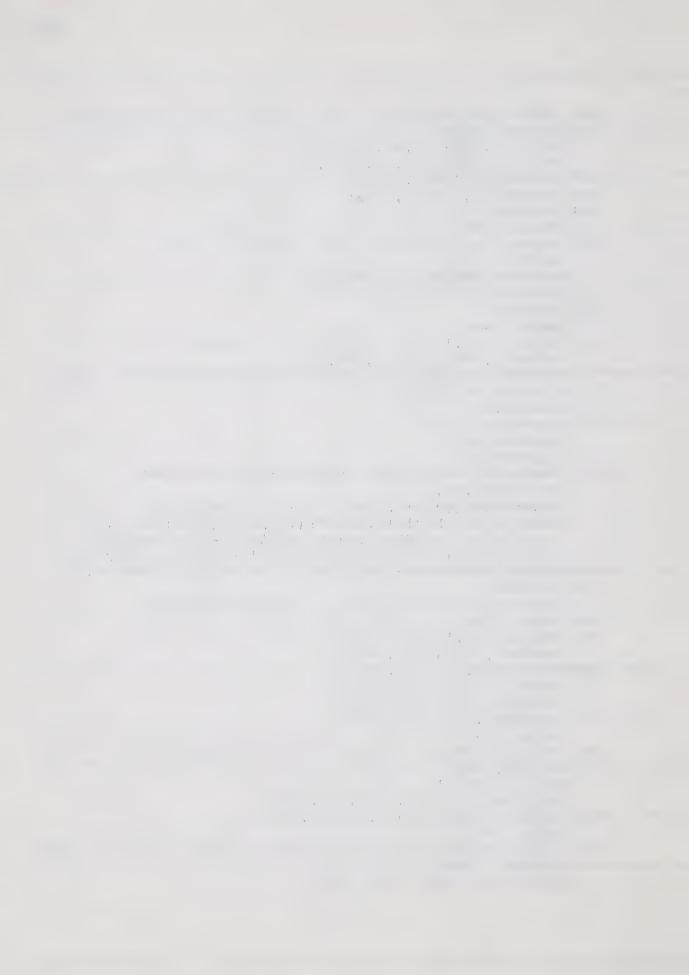


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IF (MN. EQ. 0) GO TO 267
    SY(T, M) = (U(1, M-2) + 3.00*0(I, N) -4.00*0(I, N-1))/(2.00*0))
    \text{UY}(7,1) = (4.10*8(1,2) - 3.00*0(1,1) - 0(1,3)) / (2.00*04)
267 DO 108 J=1, N
    FVALUATION OF GRAD'S OF SITEAT
                                            FCI IN
   * (111)
    IF (I.EQ.M) SX (I,J) = (S(I-2,J)+3.D0*S(I,J)-4.D0*S(I-1,J))
   * / (2. DU*DX)
    IF(T, Tg, 1) SR(1, J) = (4.1.0*S(T+1, J) - 4.1.0*S(T, J) - 3(T+2, J))
   * /(2.D0*EX)
    I! (1. N2. 1. AND. I. NF. !) SX (1, J) = (S(I+1, J) - S(I-1, J)) / (7. D)
   水 水宜区)
    IF (MN. EO. 0) GO TO 102
    IF (I.EQ.M) UX(I,J) = (U(I-2,J)+3.D0*U(I,J)-4.D0*U(I-1,J))
   * /(2.D0*DX)
    IF (I. 10. 1) UN (I,J) = (4.10*U(1+1,J)-3.50*U(E,J)-1(T+2,J))
      /(2, DU*EX)
    IF (I.NE. 1. AND. I. NE. M) UX (I, J) = (U(I+1, J) - U(I-1, J)) / (2.D0)
 水 水丁以)
    IF (J.NE. 1. AND. J. NE. N) UY (I, J) = (U(I, J+1) - U(I, J-1)) / (2.D0)
   * *DY)
108 CONTINUE
109 CONTINUE
    IF (MN.EQ.0) GO TO 272
    IF (MN. EO. 1) GC TO 12
    IF(IN. EO. 1. AND. ITER: GT. 2) GO TO 275
    IF (EPVAL.LT. EPRES) IN=0
    IF (EPVAL.LT. EPRES) GO TO 272
    GD TO 275
    EVALUATION OF
                      AVERAGE GRAD'S FOR POINTS
                                                        IN FILM
272 DO 178 I=1,M1
    HF(I) = (H(I) +H(I+1))/2.D0
    20 174 J=1, N
    SHX(I,J) = (SX(I,J) + SX(I+1,J))/2.D0
    SHY(I,J) = (SY(I,J) + SY(I+1,J))/2.00
174 CONTINUE
178 CONTINUE
    1F (NITER.EQ. 0) GC TC 445
    IF (ECVAL.LT.ETHET.AND.MM.EQ. 1) GO TO 12
    GO TO 63
    SVATRATICE OF TUMP BIST
 12 PRINT 300
300 FORMAT (30X, RESULTS FOR TEMP
                                        DIST')
   1P (MM. FQ. 1) PRINT 138
                                CONST
                                        VISCOSITY BASED ON A
138 FORMAT (9X, RESULTS
                          FOR
 * V PLATE
   115001
    IF (NITER.GT. 1. AND. ITER. EQ. 0) PRINT
                                            139
```

```
134 FORMAL (RY, PRESULTS CONSIDERING VARYING VISCOSITY')
    IF (NITER.GI. 1) WRITE (6, 118) NITER, ITER, EQUAL
118 FORMAT (12x, 'NITER EQUALS', 2x, 13, 2x, 'ITER EQUALS', 2x,
   * I3,2X, EQVAL
   * NOUALS', 2X, D13. 6)
    IF (EQVAL.LT. ETHET) WRITE (6, 119) ETHET
119 FORMAT (40X, 'EQVAL LESS THAN', 3X, D13.6)
    DO 297 1=1.M
     WRITE (6, 132) (THETA (I, J), J=1, 12)
132 FORMAT (1x, 12 (F7. 4, 1x) /)
     WRITE (6, 155) (THETA (1,J), J=13,21)
155 FORMAT (2X, 9 (F7.4, 1X) /)
297 CONTINUE
     TRIVE 300
     DO 296 I=1,M
     WRITE (6,301) (T(I,J),J=1,12)
     WRITE(6,302) (T(T,J),J=13,21)
296 CONTINUE
301 FORMAT (2X, 12 (F7. 2, 1X) /)
302 FORMAT (2x, 9 (F7.2, 1x) /)
     EVALUATION OF HEAT FLUX AT PAD AND SLIDER AND SHEAR ST
   * RESS AT SLIDER
    TO 13 I=1,11
     \mathbb{Z}^{\mathsf{NP}}(1) = -(\mathsf{TFEL}_{\mathsf{N}}(1, \mathsf{N-L}) + \mathsf{S.DO*PHITA}(\mathsf{T, N}) - \mathsf{S.DO*PHITA}(\mathsf{T, N-L})
   * 1))/
   *(2.D0*DY*H(I))
       OYS (I) = (4.D0*THETA(I,2)-3.D0*THETA(I,1)-THETA(I,3))/
       (2.DO*DY*H
   * (I) )
    EVALUATION OF TEMP GRAD'S
                                            BOUNDARIES
                                        AT
    ETDYP(I) = -H(I) *CYP(I)
    DTDYS (I) = H (I) * (YS (I)
    FDY(I) = AFM*SYY(I, 1) / (H(I) **2*F(I, 1))
 13 CONTINUE
    PRINT 195
195 FORMAT (30X, TEMP GRADIENIS
                                      AT PAD')
    WRITE(6, 197) (DTDYF(I), I=1, M)
197 FORMAT (2X, 11 (F10.6, 1X) /)
    PRINT 196
196 FORMAT (30X, 'IEMP GRADIENTS AT SLIDER')
    XRITE (8, 197) (DIEVS (1), J=1, M)
    PRINT 143
143 FORMAT (30X, *HEAT FLUX AT PAD*)
    WRITE(6, 197) (OYP(I), I=1, M)
    PRINT 144
144 FORMAT (30X, 'HEAT FLUX AT SLIDER')
    WRITE (6, 197) (QYS(I), I=1, 8)
    PRINT 121
```



```
121 FORMAR (30%, 1 absules FOR SI FAR PCN DISTRIBUTION!)
    DU 501 1=1, M
    WRITE (6,33) (S(I,J), J=1,12)
    WRITE(6, 161) (S(I,J), J=13,21)
33 FORMAT (2X, 12 (F9.4, 1X) /)
161 FORMAT (2x,9(F9.4,1X)/)
501 CONTINUE
FRINT 211
211 FORMAT (30x, 'RESULTS FOR VELOCITY DIST')
    IO 502 I=1,M
    WILTE (6,33) (U(I,J),J=1,12)
    WRITE (6, 161) (U(I,J),J=13.21)
502 CONTINUE
    PRINT 145
145 FORMAT (30X, 'SHEAR STRESS AT SLIDER')
   WRITE (6, 197) (FDY (I), I=1, M)
    EVALUATION OF LCAD CAPACITY OF SHARING AND FRICTIONAL
   * FORCE ON BUNNER
 FSUM=0.D0
    PSUM=0. DO
    OPSUM=0.DO
    OSSUM=0.00
    FVALUATION
                OF ICAD CAPACITY OF BEARING
    DO 14 I=3,11,2
    PSUM = PSUM + (P(I) + 4.D0 * P(I-1) + P(I-2)) * DX/3.D0
    FSUM=FSUM+ (FDY (I) +4.D0*FDY (I-1) +FDY (I-2))*DX/3.D0
    EVALUATION OF HEAT CONDUCTED AWAY AT BOUNDARIES
    QPSUM=CFSUM+ (QYP (I) +4.D0*QYP (I-1) + QYP (I-2)) *DX/3.PO
    ^3$H!!={$$U!+(Q?5(T)+4.8^**QY5(I-1)+7*3(T-3))*D*/3.hii
 14 CONTINUE
    CSPER=DABS (OSSUM) / (DABS (OSSUM) + DABS (OPSUM) )
445 88599 149
140 FORMAT (30X, 'FINAL RESULTS FOR PRESS DIST')
    WRITE (6, 105) (P(I), I=1, 6)
1"5 FORMAT (2X,6 (D13.6,2X)/)
    WRITE (6, 151) (P(I), I=7,11)
151 FORMAT (2X,5 (D13.6,2X)/)
    IF (NICEP. FC. 0) TO TO 113
   PRINT 141
141 FORMAT (2X, 'LCAD CAPACITY', 10X, 'DRAG', 10X, 'MASS
                                                        FLOW!
   * , OX, FI
   PTHRU SLIDER')
   WRITE (6, 142) PSUM, FSUM, AFM, CSPER
142 FORMAT (2X, F13.6, 14X, 3 (F8.4, 14X))
    RINT 165
165 FORMAT (2X, 'HT CCNEUCTED THRU SLIDER', 15X, 'HT CONDU
   * CIFD TERM
   *PAD', 15X, 'POWER REQUIRED')
```

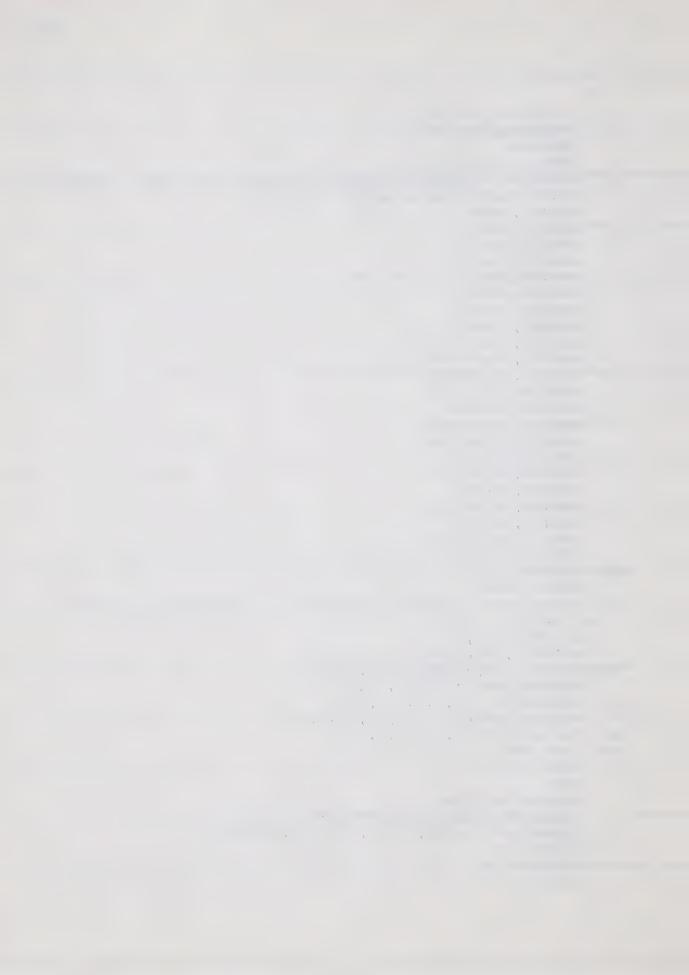


```
WRITE (6, 166) QSSUM, QFSUM, FSUM
  16.6 FORMA? (11%, F10.5, 28%, 2(F11.5, 23%))
      DO 199 J=1, N
      EVALUATION OF ET CONVECTED INTO
C
      TSIM (J) = AFR* THETA (1, J) *SY (1, J)
      EVALUATION OF HT CONVECTED
C
                                         OUT OF
                                                    BEG
      ISEM (J) = AFM*THETA (M, J) *SY (M, J)
  140 CONTINUE-
      OISM=0.DO
      OESM = 0. DO
      DO 201 J=3, N, 2
      QISM=QISM+DY*(TSIM(J)+4.D0*TSIM(J-1)+TSIM(J-2))/3.D0
      QESM = QESM + DY * (TSEM (J) + 4.DO * TSEM (J-1) + TSEM (J-2)) / 3.DO
  2'") CONTINUE
      WRITE (6, 201) OISM, AFM
  201 FORMAT (4X, 'HEAT
                         CCNVECTED
                                     INTO BRG EQU', 2X, F10.5,
        AND', # 10.5)
      WRITE (6, 202) QESM, AFM
  202 FORMAT (4X, 'HT CCNVECTED OUT OF BRG EQU', 2X, F10.5,
     * AND +, F10.5)
      EVALUATION OF
                        AVERAGE TEMP
                                         IN
                                              BEARING
      DO 799 I=1.M
      US 7= 1. DU
      UISM=0.DC
      ISM = 0. DO
      DO 798 J=3, N, 2
      USM = USM + DY * (U(I, J) + 4.D0 * U(I, J-1) + U(I, J-2))/3.D0
      UTSM=UTSM+DY*(U(I,J)*THETA(I,J)+4.D0*(U(I,J-1)*THETA(I
     * ,J-1))
     *+U(I,J-2) *THETA(I,J-2))/3.DO
      ISM=TSM+DY* (THETA (I, J) +4.DO*THETA (I, J-1) +THETA (I, J-2))
     * /3. DO
 798 CONTINUE
      TE (T) = TAV*UTST/UST
      TA(T)=TAV*18Y
 799 CONTINUE
      WRITE (6.105) (TB(I).I=1.6)
      WRITE (6, 151) (TB(I), I=7, 11)
      WRITE (6, 105) (TA (I), I=1, 6)
      WRITE (6, 151) (TA (I), I=7, 11)
      1884=0.00
      TASM=0.DO
      IN 797 T=3, N, 2
      TPS'' = TBSM + DX * (TB(I) + 4 \cdot D0 * TB(I-1) + TB(I-2))/3 \cdot D0
      TASM=TASM+OR* (PA (I) +4.D0*TA (I-1) +TA (I-2))/3.D0
 797 CONTINUE
      XTTF (F. 784) 1824, JASY
 784 FORMAT(1 1,//,30X,'BUIK TEMP EQUALS',2X,E13.5,2X,'AV
     * ERAGE TEMP
```

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t e

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* FQUALS', 2X, E13.5)
     IF (MM.EQ. 1) GC TO 63
     NA=NA+1
     IF (NA. EQ. 1) PRINT277
 ??? FORMAT( ',/,30x, RESULTS INCLUEDED IN PRIME THEMS!)
     IF (NA. EQ. 1. AND. IN. EQ. 0) GO TO 275
     ANS(I1, 1) = R
     ANS (11.2) = 18
     ANS (I1,3) = TF
     ANS (I1,4) = ISIP
     ANS (11,5) = PE
     ANS (I1,6) = PEC
     ANS (I1,7) = PRL
     10=(8,11) SMA
     ANS (I1, 9) = D1*TSTF
     ANS (I1, 10) = CEDRE
     ANS (11, 11) = ESUM
     ANS (11, 12) = FSUM
     ANS(I1.13) = AFM
     ANS (I1, 14) = CPSUM
     ANS (I1, 15) = QSSUM
     ANS (I1, 16) = QISM
     ANS (11, 17) = QESM
     ANS (I1, 18) = BT
     ANS (I1, 19) = CNTHT
     ANS(11,20) = RE
     ANS (11,21) = TESM
     ANS(I1,22) = IASM
1000 CONTINUE
     PRINT 698
698 FORMAT (*11,////,30X, RESULTS OF NUMERICAL ANALYSIS
     IO 691 I1=1, NUM
     WRITE (6,700) (ANS (I1,J),J=1,7)
701 FO-MAI(' ',//,3X,7(E13.5,2X))
     WRITE (6,899) (ANS (I1,J), J=8,14)
899 FORMAT (' ', 3X, 7 (E13.5, 2X))
     WRITE (6,447) (ANS (11,J),J=15,22)
447 FORMAT(' ',3X,8(E13.5,2X))
691 CONTINUE
     STOP
     FND
     SUBROUTINE INV
     IMPLICIT REAL*8 (A-D, F-H, 0-Z)
     DIMENSION T (67), W (67), ARG (10), VAL (10)
     REWIND 2
     " A D (2) " , W
     RETURN
```



FNTRY VIS(TEMP, V)

CALL DATSM (TEMP, T, W, 67, 1, ARG, VAL, 10)

IF (TEMP.LE. 2. 3D2) ERR=0.0168E-6

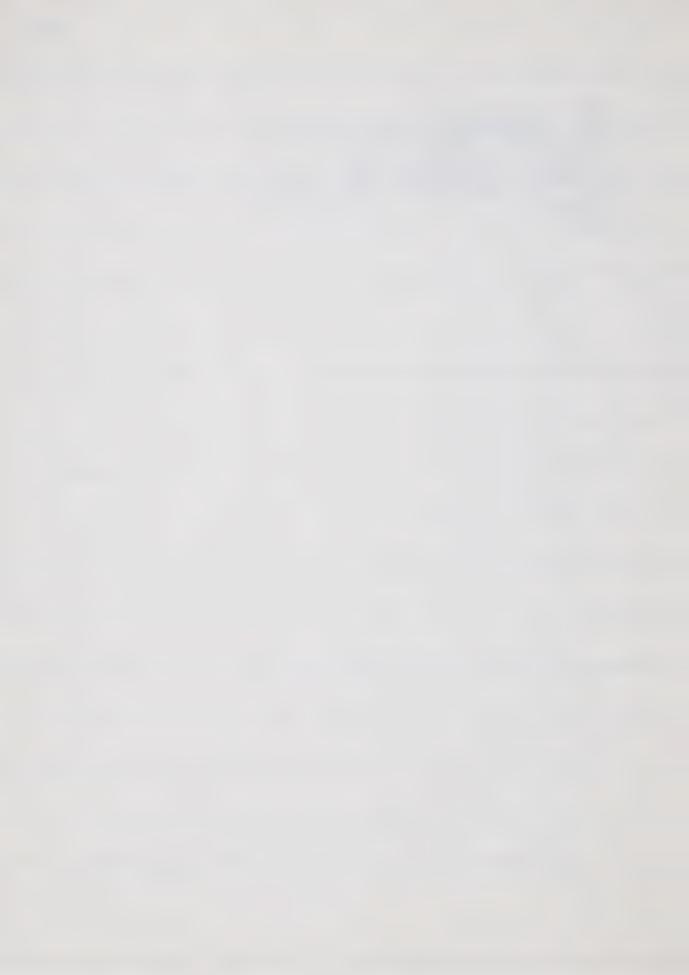
IF (TEMP.LE. 1. 1D2) ERR=0.14E-6

IF (TEMP.LI. 2. 5D1) ERR=0.50E-5

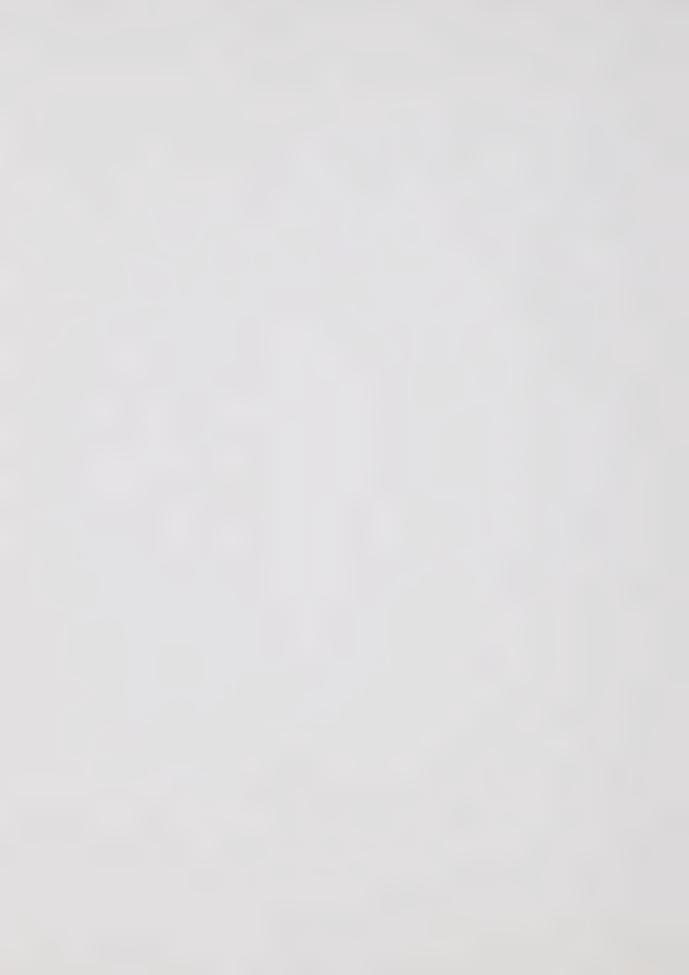
CALL DALI(TEMP, ARG, VAL, V, 10, ERR, IER)

BETUEN

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